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Figure similar

MLFB-Ordering data1FK7034-5AK71-1LH0

Client order no. :
Order no. :
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Remarks :

Item no. :
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Project :

Engineering data		Mechanical data	
Rated speed (100 K)	6000 rpm	Motor type	Permanent-magnet synchronous motor
Number of poles	6	Motor type	Compact
Rated torque (100 K)	1.0 Nm	Shaft height	36
Rated current	1.3 A	Cooling	Natural cooling
Static torque (60 K)	1.35 Nm	Radial runout tolerance	0.035 mm
Static torque (100 K)	1.60 Nm	Concentricity tolerance	0.08 mm
Stall current (60 K)	1.60 A	Axial runout tolerance	0.08 mm
Stall current (100 K)	1.90 A	Vibration severity grade	Grade A
Moment of inertia	0.980 kgcm²	Connector size	1
Efficiency	88.0 %	Degree of protection	IP64
Physical constants		Design acc. to Code I	IM B5 (IM V1, IM V3)
Torque constant	0.86 Nm/A	Temperature monitoring	KTY84 temperature sensor in the stator winding
Voltage constant at 20° C	55.0 V/1000*min ⁻¹	Electrical connectors	Connectors for signals and power rotatable
Winding resistance at 20° C	4.50 Ω	Color of the housing	without
Rotating field inductance	16.5 mH	Holding brake	with holding brake
Electrical time constant	3.70 ms	Shaft end	Plain shaft
Mechanical time constant	1.60 ms	Encoder system	Encoder AM20DQ: absolute encoder 20 bits (resolution 1048576, encoder-internal 512 S/R) + 12 bits multi-turn (traversing range 4096 revolutions)
Thermal time constant	30 min		
Shaft torsional stiffness	5500 Nm/rad		
Net weight of the motor	4.0 kg		

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Optimum operating point		Recommended Motor Module	
Optimum speed	6000 rpm	Rated inverter current	3 A
Optimum power	0.6 kW	Maximum inverter current	6 A
Limiting data		Maximum torque	4.90 Nm
Max. permissible speed (mech.)	10000 rpm		
Max. permissible speed (inverter)	10500 rpm		
Maximum torque	6.5 Nm		
Maximum current	8.0 A		
Holding brake			
Holding brake version	Permanent-magnet brake		
Holding torque	1.9 Nm		
Power supply voltage	DC 24 V ± 10 %		
Coil current	0.3 A		
Opening time	50 ms		
Closing time	30 ms		
Highest braking work	40 J		