

Data sheet for three-phase Squirrel-Cage-Motors SIMOTICS



Motor type : 1AV2082A

SIMOTICS GP - 80 M - IM B5 - 2p

Client order no.	Item-No.	Offer no.
Order no.	Consignment no.	Project

Remarks

Electrical data

Safe Area

U	Δ / Y	f	P	P	I	n	M	η ³⁾			cosφ ³⁾			I _A /I _N	M _A /M _N	M _K /M _N	IE-CL
[V]		[Hz]	[kW]	[hp]	[A]	[1/min]	[Nm]	4/4	3/4	2/4	4/4	3/4	2/4	I _I /I _N	T _I /T _N	T _B /T _N	
400	Y	50	0.75	-/-	1.67	2805	2.5	77.4	80.0	80.1	0.84	0.78	0.67	4.9	1.9	2.3	IE2
460	Y	60	0.86	-/-	1.70	3410	2.4	75.5	77.6	77.1	0.84	0.81	0.71	5.2	1.9	2.5	IE2
460	Y	60	0.75	-/-	1.50	3445	2.1	75.5	76.2	74.8	0.83	0.77	0.65	6.0	2.1	3.0	IE2
IM B5 / IM 3001		FS 80 M		9 kg		IP55		IEC/EN 60034		IEC, DIN, ISO, VDE, EN							

Environmental conditions : -20 °C - +40 °C / 1,000 m

Locked rotor time (hot / cold) : 18 s | 29.4 s

Mechanical data

Sound level (SPL / SWL) at 50Hz 60Hz	60.0 / 71.0 dB(A) ²⁾	64.0 / 75.0 dB(A) ²⁾	External earthing terminal	No
Moment of inertia	0.0008 kg m ²		Vibration severity grade	A
Bearing DE NDE	6004 2Z C3	6004 2Z C3	Insulation	155(F) to 130(B)
bearing lifetime			Duty type	S1
L _{10mh} F _{Rad min} 50 60Hz ¹⁾ for coupling operation	40000 h	32000 h	Direction of rotation	bidirectional
Lubricants	Unirex N3		Frame material	aluminum
Regreasing device	No		Coating (paint finish)	Standard paint finish C2
Grease nipple	-/-		Color, paint shade	RAL7030
Type of bearing	Preloaded bearing DE		Motor protection	(A) without (Standard)
Condensate drainage holes	-/-		Method of cooling	IC411 - self ventilated, surface cooled

Terminal box

Terminal box position	top	Max. cross-sectional area	1.5 mm ²
Material of terminal box	Aluminium	Cable diameter from ... to ...	9.0 mm - 17.0 mm
Type of terminal box	TB1 E00	Cable entry	1xM25x1,5
Contact screw thread	M4	Cable gland	1 plug

Notes:

I _A /I _N = locked rotor current / current nominal	1) L10mh according to DIN ISO 281 10/2010	3) Value is valid only for DOL operation with motor design IC411
M _K /M _N = locked rotor torque / torque nominal	2) at rated power / at full load	
M _B /M _N = break down torque / nominal torque		

responsible dep.	technical reference	created by	approved by	Technical data are subject to change! There may be discrepancies between calculated and rating plate values.			
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