

Data sheet for three-phase Squirrel-Cage-Motors INNOMOTICS



Motor type : 1AV2082B INNOMOTICS GP - 80 M - IM B14 - 4p

Client order no.	Item-No.	Offer no.
Order no.	Consignment no.	Project

Remarks

Safe Area

Electrical data -/-

U	Δ / Y	f	P	P	I	n	M	η ³⁾			cosφ ³⁾			I _A /I _N	M _A /M _N	M _K /M _N	IE-CL
[V]		[Hz]	[kW]	[hp]	[A]	[1/min]	[Nm]	4/4	3/4	2/4	4/4	3/4	2/4	I _I /I _N	T _I /T _N	T _B /T _N	
DOL duty (S1) - 155(F) to 130(B)																	
230	Δ	50	0.55	-/-	2.40	1440	3.6	77.1	76.8	73.7	0.74	0.65	0.51	5.3	2.2	3.1	IE2
400	Y	50	0.55	-/-	1.39	1440	3.6	77.1	76.8	73.7	0.74	0.65	0.51	5.3	2.2	3.1	IE2
460	Y	60	0.63	-/-	1.42	1735	3.5	75.5	75.8	73.5	0.74	0.67	0.54	5.7	2.4	3.3	IE2
460	Y	60	0.55	-/-	1.29	1750	3.0	75.5	74.6	71.1	0.71	0.62	0.49	6.4	2.7	3.8	IE2
IM B14 / IM 3601		FS 80 M				IP55	UKCA	IEC/EN 60034		IEC, DIN, ISO, VDE, EN							
Environmental conditions : -20 °C - +40 °C / 1000 m									Locked rotor time (hot / cold) : 17.8 s 23.3 s								

Mechanical data				
Sound level (SPL / SWL) at 50Hz 60Hz	53 / 64 dB(A) ^{2) 3)}	55 / 66 dB(A) ^{2) 3)}	Vibration severity grade	A
Moment of inertia	0.0017 kg m²		Thermal class	F
Bearing DE NDE	6004 2Z C3	6004 2Z C3	Duty type	S1
bearing lifetime			Direction of rotation	bidirectional
L _{10mh} F _{Rad min} 50 60Hz ¹⁾ for coupling operation	40000 h	32000 h	Frame material	aluminum
Regreasing device	Without		Net weight of the motor (IM B3)	10 kg
Grease nipple	-/-		Coating (paint finish)	Standard paint finish C2
Type of bearing	Preloaded bearing DE		Color, paint shade	RAL7030
Condensate drainage holes	Without		Motor protection	(K) 1 Pt1000 resistance thermometer(2 terminals)
External earthing terminal	Without		Method of cooling	IC411 - self ventilated, surface cooled

Terminal box																	
Terminal box position			right				Max. cross-sectional area										
Material of terminal box			Aluminium				Cable diameter from ... to ...										
Type of terminal box			TB1 E00				Cable entry										
Contact screw thread			M4				Cable gland										

I_A/I_N = locked rotor current / current nominal
M_K/M_N = locked rotor torque / torque nominal
M_B/M_N = break down torque / nominal torque

1) L_{10mh} according to DIN ISO 281 10/2010
2) at rated power / at full load

3) Value is valid only for DOL operation with motor design IC411

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