Data sheet for three-phase Squirrel-Cage-Motors INNOMOTICS



INNOMOTICS GP - 80 M - IM B5 - 6p Motor type : 1AV2083C Client order no. Offer no. Item-No Order no. Consignment no. Project Remarks Safe Area

Electri	cal dat	a									-/-						
U	Δ/Υ	f	Р	Р	1	n	М		η ³⁾			cosφ ³⁾		I _A /I _N	M _A /M _N	M _K /M _N	IE-CL
[V]		[Hz]	[kW]	[hp]	[A]	[1/min]	[Nm]	4/4	3/4	2/4	4/4	3/4	2/4	I _I /I _N	T _I /T _N	T _B /T _N	
	DOL duty (S1) - 155(F) to 130(B)																
230	Δ	50	0.55	-/-	2.85	935	5.6	73.1	73.8	70.8	0.66	0.57	0.45	4.4	2.5	2.9	IE2
400	Υ	50	0.55	-/-	1.65	935	5.6	73.1	73.8	70.8	0.66	0.57	0.45	4.4	2.5	2.9	IE2
460	Υ	60	0.63	-/-	1.76	1135	5.3	68.0	68.4	65.8	0.66	0.58	0.45	4.8	2.6	3.1	IE2
460	Υ	60	0.55	-/-	1.66	1145	4.6	68.0	67.4	63.7	0.61	0.52	0.40	5.2	2.9	3.6	IE2
IM B5 / I	M 3001		FS 80 M			IP55	UKCA	IEC/EN	60034		IEC, DIN, IS	SO, VDE, EN	١				
	Environmental conditions: -20 °C - +40 °C / 1000 m					Locked rotor time (hot / cold) · 21.8 s L 30.3 s											

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Sound level (SPL / SWL) at 50Hz 60Hz	42 / 53 dB(A) ^{2) 3)}	45 / 56 dB(A) ^{2) 3)}	Vibrat						

Moment of inertia 0.0025 kg m² 6004 2Z C3 6004 2Z C3

Bearing DE | NDE bearing lifetime $L_{10mh}\,F_{Rad\,min}$ for coupling operation $50|60Hz^{\,1)}$ 40000 h 32000 h

Regreasing device Without

Grease nipple Type of bearing Preloaded bearing DE

Condensate drainage holes Without External earthing terminal Without ation severity grade

Duty type

Direction of rotation

Thermal class

Frame material

Net weight of the motor (IM B3) Coating (paint finish)

Color, paint shade Motor protection

RAL7030 (B) 1 PTC thermistor - for tripping (2 terminals)

Method of cooling

Cable gland

IC411 - self ventilated, surface cooled

Α

F

S1

bidirectional

aluminum

12 kg

Standard paint finish C2

Terminal box

Mechanical data

Terminal box position	top
Material of terminal box	Aluminium
Type of terminal box	TB1 E00
Contact screw thread	M4

Max. cross-sectional area Cable diameter from ... to ...

Cable entry

1.5 mm² 9 mm - 17 mm

1xM25x1,5-1xM16x1,5

2 plugs

I_A/I_N = locked rotor current / current nominal M_A/M_N = locked rotor torque / torque nominal $M_K/M_N = break down torque / nominal torque$ 1) L_{10mh} according to DIN ISO 281 10/2010

2) at rated power / at full load

3) Value is valid only for DOL operation with motor design IC411

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