

Data sheet for three-phase Squirrel-Cage-Motors SIMOTICS



Motor type : 1AV3083B

SIMOTICS GP - 80 M - IM B5 - 4p

Client order no.	Item-No.	Offer no.
Order no.	Consignment no.	Project
Remarks		

Electrical data

Safe Area

U [V]	Δ / Y	f [Hz]	P [kW]	P [hp]	I [A]	n [1/min]	M [Nm]	$\eta^{3)}$			$\cos\phi^{3)}$			I_A/I_N I_f/I_N	M_A/M_N T_f/T_N	M_K/M_N T_B/T_N	IE-CL
								4/4	3/4	2/4	4/4	3/4	2/4				
DOL duty (S1) - 155(F) to 130(B)																	
230	Δ	50	0.75	-/-	3.05	1450	5.0	82.5	82.3	80.1	0.75	0.67	0.55	7.1	2.7	3.9	IE3
400	Y	50	0.75	-/-	1.75	1450	5.0	82.5	82.3	80.1	0.75	0.67	0.55	7.1	2.7	3.9	IE3
460	Y	60	0.86	-/-	1.72	1750	4.7	83.5	83.1	80.7	0.75	0.67	0.55	7.7	2.7	4.1	IE3
460	Y	60	0.75	-/-	1.59	1760	4.0	83.5	82.6	79.7	0.71	0.63	0.50	8.3	3.1	4.7	IE3
IM B5 / IM 3001		FS 80 M		IP55		UKCA		IEC/EN 60034		IEC, DIN, ISO, VDE, EN							
Environmental conditions : -20 °C - +40 °C / 1,000 m										Locked rotor time (hot / cold) : 19.8 s 23.6 s							

Mechanical data

Sound level (SPL / SWL) at 50Hz 60Hz	53 / 64 dB(A) ^{2) 3)}	53 / 64 dB(A) ^{2) 3)}	Vibration severity grade	A
Moment of inertia	0.0029 kg m ²		Thermal class	F
Bearing DE NDE	6004 2Z C3	6004 2Z C3	Duty type	S1
bearing lifetime			Direction of rotation	bidirectional
L_{10mh} , $F_{Rad min}$ 50 60Hz ¹⁾ for coupling operation	40000 h	32000 h	Frame material	aluminum
Regreasing device	No		Net weight of the motor (IM B3)	14 kg
Grease nipple	-/-		Coating (paint finish)	Standard paint finish C2
Type of bearing	Preloaded bearing DE		Color, paint shade	RAL7030
Condensate drainage holes	No		Motor protection	(F) 1 temperature sensor KTY84-130 (2 terminals)
External earthing terminal	No		Method of cooling	IC411 - self ventilated, surface cooled

Terminal box

Terminal box position	top	Max. cross-sectional area	1.5 mm ²
Material of terminal box	Aluminium	Cable diameter from ... to ...	9 mm - 17 mm
Type of terminal box	TB1 E00	Cable entry	1xM25x1,5-1xM16x1,5
Contact screw thread	M4	Cable gland	2 plugs

Notes:

I_A/I_N = locked rotor current / current nominal
 M_K/M_N = locked rotor torque / torque nominal
 M_f/M_N = break down torque / nominal torque
 1) L10mh according to DIN ISO 281 10/2010
 2) at rated power / at full load
 3) Value is valid only for DOL operation with motor design IC411

responsible dep. DI MC LVM	technical reference	created by DT Configurator	approved by	<i>Technical data are subject to change! There may be discrepancies between calculated and rating plate values.</i>	Link documents		
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Special design

G11 Rotary pulse encoder Sendix 5020 (HTL)

Notes:

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