

Data sheet for three-phase Squirrel-Cage-Motors SIMOTICS



Motor type : 1AV3090B

SIMOTICS GP - 90 S - IM B5 - 4p

Client order no.	Item-No.	Offer no.
Order no.	Consignment no.	Project

Remarks

Electrical data

Safe Area

U	Δ / Y	f	P	P	I	n	M	η ³⁾			cosφ ³⁾			I _A /I _N	M _A /M _N	M _K /M _N	IE-CL
[V]		[Hz]	[kW]	[hp]	[A]	[1/min]	[Nm]	4/4	3/4	2/4	4/4	3/4	2/4	I _I /I _N	T _I /T _N	T _B /T _N	
DOL duty (S1) - 155(F) to 130(B)																	
230	Δ	50	1.10	-/-	4.20	1440	7.3	84.1	84.7	83.4	0.78	0.70	0.58	6.9	2.9	3.6	IE3
400	Y	50	1.10	-/-	2.40	1440	7.3	84.1	84.7	83.4	0.78	0.70	0.58	6.9	2.9	3.6	IE3
460	Y	60	1.27	-/-	2.40	1740	7.0	84.0	84.4	83.1	0.79	0.72	0.60	7.4	2.9	3.8	IE2
460	Y	60	1.10	-/-	2.15	1750	6.0	86.5	86.4	84.2	0.75	0.67	0.54	8.2	3.4	4.4	IE3
IM B5 / IM 3001		FS 90 S				IP55			IEC/EN 60034		IEC, DIN, ISO, VDE, EN						
Environmental conditions : -20 °C - +40 °C / 1,000 m									Locked rotor time (hot / cold) : 21.4 s 25.8 s								

Mechanical data

Sound level (SPL / SWL) at 50Hz 60Hz	58 / 62 dB(A) ²⁾	58 / 62 dB(A) ²⁾	Vibration severity grade	A
Moment of inertia	0.0036 kg m ²		Thermal class	F
Bearing DE NDE	6205 2Z C3	6004 2Z C3	Duty type	S1
bearing lifetime			Direction of rotation	bidirectional
L _{10mh} F _{Rad min} for coupling operation 50 60Hz ¹⁾	40000 h	32000 h	Frame material	aluminum
Lubricants	Unirex N3		Net weight of the motor (IM B3)	16 kg
Regreasing device	No		Coating (paint finish)	Standard paint finish C2
Grease nipple	-/-		Color, paint shade	RAL7030
Type of bearing	Preloaded bearing DE		Motor protection	(B) 1 PTC thermistor - for tripping (2 terminals)
Condensate drainage holes	No		Method of cooling	IC416 - separately ventilated, surface cooled
External earthing terminal	No			

Terminal box

Terminal box position	top	Max. cross-sectional area	1.5 mm ²
Material of terminal box	Aluminium	Cable diameter from ... to ...	9 mm - 17 mm
Type of terminal box	TB1 E00	Cable entry	1xM25x1,5-1xM16x1,5
Contact screw thread	M4	Cable gland	2 plugs

Notes:

I _A /I _N = locked rotor current / current nominal	1) L10mh according to DIN ISO 281 10/2010	3) Value is valid only for DOL operation with motor design IC411
M _K /M _N = locked rotor torque / torque nominal	2) at rated power / at full load	
M _B /M _N = break down torque / nominal torque		

responsible dep.	technical reference	created by	approved by	Technical data are subject to change! There may be discrepancies between calculated and rating plate values.	Link documents
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Special design

F70 Mounting of separately driven fan G11 Rotary pulse encoder Sendix 5020 (HTL)

Notes:

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