

Data sheet for three-phase Squirrel-Cage-Motors SIMOTICS



Motor type : 1AV3105D

SIMOTICS GP - 100 L - IM B3 - 8p

Client order no.	Item-No.	Offer no.
Order no.	Consignment no.	Project

Remarks	Safe Area
Electrical data	-/-

U	Δ / Y	f	P	P	I	n	M	η ³⁾			cosφ ³⁾			I _A /I _N	M _A /M _N	M _K /M _N	IE-CL
[V]		[Hz]	[kW]	[hp]	[A]	[1/min]	[Nm]	4/4	3/4	2/4	4/4	3/4	2/4	I _I /I _N	T _I /T _N	T _B /T _N	
DOL duty (S1) - 155(F) to 130(B)																	
230	Δ	50	1.10	-/-	5.30	710	14.8	77.7	76.4	75.1	0.67	0.56	0.45	4.1	1.8	2.3	IE3
400	Y	50	1.10	-/-	3.05	710	14.8	77.7	76.4	75.1	0.67	0.56	0.45	4.1	1.8	2.3	IE3
IM B3 / IM 1001		FS 100 L				IP55	UKCA	IEC/EN 60034		IEC, DIN, ISO, VDE, EN							
Environmental conditions : -20 °C - +40 °C / 1000 m									Locked rotor time (hot / cold) : 33.6 s 44.8 s								

Mechanical data				
Sound level (SPL / SWL) at 50Hz 60Hz	61.9 / 69.9 dB(A) 2) 3)	65.4 / 73.4 dB(A) 2) 3)	Vibration severity grade	A
Moment of inertia	0.0130 kg m²		Thermal class	F
Bearing DE NDE	6206 2Z C3	6206 2Z C3	Duty type	S1
bearing lifetime			Direction of rotation	bidirectional
L _{10mh} F _{Rad min} for coupling operation 50 60Hz ¹⁾	40000 h	32000 h	Frame material	aluminum
Regreasing device	Without		Net weight of the motor (IM B3)	26 kg
Grease nipple	-/-		Coating (paint finish)	Standard paint finish C2
Type of bearing	Preloaded bearing DE		Color, paint shade	RAL7030
Condensate drainage holes	Without		Motor protection	(A) without (Standard)
External earthing terminal	Without		Method of cooling	IC411 - self ventilated, surface cooled

Terminal box			
Terminal box position	right	Max. cross-sectional area	4 mm²
Material of terminal box	Aluminium	Cable diameter from ... to ...	11 mm - 21 mm
Type of terminal box	TB1 F00	Cable entry	2xM32x1,5
Contact screw thread	M4	Cable gland	2 plugs

I_A/I_N = locked rotor current / current nominal
M_A/M_N = locked rotor torque / torque nominal
M_K/M_N = break down torque / nominal torque

1) L_{10mh} according to DIN ISO 281 10/2010
2) at rated power / at full load

3) Value is valid only for DOL operation with motor design IC411

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