

Data sheet for three-phase Squirrel-Cage-Motors SIMOTICS



Motor type : 1AV3164B

SIMOTICS GP - 160 L - IM V6 - 4p

Client order no.	Item-No.	Offer no.
Order no.	Consignment no.	Project

Remarks

Safe Area

Electrical data

-/-

U [V]	Δ / Y	f [Hz]	P [kW]	P [hp]	I [A]	n [1/min]	M [Nm]	η ³⁾			$\cos\phi$ ³⁾			I_A/I_N I_f/I_N	M_A/M_N T_f/T_N	M_K/M_N T_B/T_N	IE-CL
								4/4	3/4	2/4	4/4	3/4	2/4				
DOL duty (S1) - 155(F) to 130(B)																	
400	Δ	50	15.00	-/-	28.50	1465	98.0	92.1	92.7	92.0	0.83	0.78	0.67	7.9	2.8	3.4	IE3
690	Y	50	15.00	-/-	16.40	1465	98.0	92.1	92.7	92.0	0.83	0.78	0.67	7.9	2.8	3.4	IE3
460	Δ	60	17.30	-/-	28.50	1765	94.0	92.4	92.5	92.0	0.83	0.79	0.69	7.9	2.7	3.3	IE2
460	Δ	60	15.00	-/-	25.00	1775	81.0	93.0	92.9	92.1	0.81	0.75	0.64	8.9	3.1	3.8	IE3
IM V6 / IM 1031		FS 160 L		IP55		UKCA		IEC/EN 60034		IEC, DIN, ISO, VDE, EN							
Environmental conditions : -20 °C - +40 °C / 1000 m										Locked rotor time (hot / cold) : 24.6 s 33.3 s							

Mechanical data

Sound level (SPL / SWL) at 50Hz 60Hz	58 / 66 dB(A) ^{2) 3)}	66 / 74 dB(A) ^{2) 3)}	Vibration severity grade	A
Moment of inertia	0.0890 kg m ²		Thermal class	F
Bearing DE NDE	6309 2Z C3	6309 2Z C3	Duty type	S1
bearing lifetime			Direction of rotation	bidirectional
L_{10mh} $F_{Rad, min}$ for coupling operation 50 60Hz ¹⁾	20000 h	16000 h	Frame material	aluminum
Regreasing device	Without		Net weight of the motor (IM B3)	106 kg
Grease nipple	-/-		Coating (paint finish)	Standard paint finish C2
Type of bearing	Locating bearing NDE		Color, paint shade	RAL7030
Condensate drainage holes	Without		Motor protection	(B) 3 PTC thermistors - for tripping (2 terminals)
External earthing terminal	Without		Method of cooling	IC411 - self ventilated, surface cooled

Terminal box

Terminal box position	top	Max. cross-sectional area	16 mm ²
Material of terminal box	Aluminium	Cable diameter from ... to ...	19 mm - 28 mm
Type of terminal box	TB1 J00	Cable entry	2xM40x1,5-1xM16x1,5
Contact screw thread	M5	Cable gland	3 plugs

I_A/I_N = locked rotor current / current nominal
 M_A/M_N = locked rotor torque / torque nominal
 M_K/M_N = break down torque / nominal torque
 1) L_{10mh} according to DIN ISO 281 10/2010
 2) at rated power / at full load
 3) Value is valid only for DOL operation with motor design IC411

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Special design

G12	Rotary pulse encoder Sendix 5020 (TTL)	R11	Terminal box rotated through 90°, cable entry from NDE
L25	Double sides reinforced bearings for DE and NDE, Type 63		

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