

Data sheet for three-phase Squirrel-Cage-Motors SIMOTICS



Motor type : 1AV3186A

SIMOTICS GP - 180 L - IM B5 - 2p

Client order no.	Item-No.	Offer no.
Order no.	Consignment no.	Project

Remarks

Electrical data

Safe Area

U	Δ / Y	f	P	P	I	n	M	η ³⁾			cosφ ³⁾			I _A /I _N	M _A /M _N	M _K /M _N	IE-CL
[V]		[Hz]	[kW]	[hp]	[A]	[1/min]	[Nm]	4/4	3/4	2/4	4/4	3/4	2/4	I _I /I _N	T _I /T _N	T _B /T _N	
DOL duty (S1) - 155(F) to 130(B)																	
230	Δ	50	30.00	-/-	92.00	2950	97.0	93.3	93.5	93.1	0.88	0.85	0.77	8.6	2.6	3.9	IE3
400	Y	50	30.00	-/-	53.00	2950	97.0	93.3	93.5	93.1	0.88	0.85	0.77	8.6	2.6	3.9	IE3
460	Y	60	33.50	-/-	51.00	3550	90.0	93.0	93.4	92.7	0.88	0.85	0.77	8.6	2.6	4.0	IE3
460	Y	60	30.00	-/-	47.00	3560	80.0	92.4	92.9	92.2	0.87	0.83	0.73	8.8	2.9	4.5	IE3
IM B5 / IM 3001			FS 180 L			IP55	UKCA	IEC/EN 60034		IEC, DIN, ISO, VDE, EN							
Environmental conditions : -20 °C - +40 °C / 1000 m									Locked rotor time (hot / cold) : 13.6 s 23.7 s								

Mechanical data

Sound level (SPL / SWL) at 50Hz 60Hz	69 / 82 dB(A) ^{2) 3)}	73 / 86 dB(A) ^{2) 3)}	Vibration severity grade	A
Moment of inertia	0.0940 kg m ²		Thermal class	F
Bearing DE NDE	6210 2Z C3	6210 2Z C3	Duty type	S1
bearing lifetime			Direction of rotation	bidirectional
L _{10mh} F _{Rad min} for coupling operation 50 60Hz ¹⁾	40000 h	32000 h	Frame material	aluminum
Regreasing device	No		Net weight of the motor (IM B3)	140 kg
Grease nipple	-/-		Coating (paint finish)	Standard paint finish C2
Type of bearing	Locating bearing NDE		Color, paint shade	RAL7030
Condensate drainage holes	No		Motor protection	(A) without (Standard)
External earthing terminal	No		Method of cooling	IC411 - self ventilated, surface cooled

Terminal box

Terminal box position	top	Max. cross-sectional area	16 mm ²
Material of terminal box	Aluminium	Cable diameter from ... to ...	19 mm - 28 mm
Type of terminal box	TB1 J00	Cable entry	2xM40x1,5
Contact screw thread	M5	Cable gland	2 plugs

Notes:

I _A /I _N = locked rotor current / current nominal	1) L10mh according to DIN ISO 281 10/2010	3) Value is valid only for DOL operation with motor design IC411
M _K /M _N = locked rotor torque / torque nominal	2) at rated power / at full load	
M _B /M _N = break down torque / nominal torque		

responsible dep.	technical reference	created by	approved by	Technical data are subject to change! There may be discrepancies between calculated and rating plate values.	Link documents
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Special design

G11 Rotary pulse encoder Sendix 5020 (HTL)

Notes:

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