## Data sheet for three-phase Squirrel-Cage-Motors INNOMOTICS



Motor type: 1AV3182B INNOMOTICS GP - 180 M - IM B35 - 4p Offer no. Client order no. Item-No Order no. Consignment no. Project Remarks Safe Area **Electrical data** -/η 3) Δ/Υ U f Р Р ī М cosφ <sup>3)</sup>  $I_A/I_N$  $M_A/M_N$  $M_K/M_N$ IE-CL n [V] [Hz] [kW] [hp] [A] [1/min] [Nm] 4/4 3/4  $I_I/I_N$  $T_I/T_N$  $T_B/T_N$ 2/4 4/4 3/4 2/4 **DOL duty (S1)** - 155(F) to 130(B) 400 Δ 50 18.50 35.00 1470 120.0 92.6 93.1 92.9 0.82 0.77 0.68 7.2 2.5 3.3 IE3 690 18.50 -/-20.50 1470 50 120.0 92.6 93.1 92.9 0.82 0.77 0.68 7.2 2.5 3.3 IE3 Δ 60 21.30 -/-35.00 1770 92.4 92.8 92.4 0.79 0.70 460 115.0 0.83 7.2 2.4 3.2 IE2 Δ -/-30.50 92.7 IE3 460 60 18.50 1775 100.0 93.6 93.6 0.81 0.74 8.7 2.6 3.8 0.62 IM B35 / IM 2001 IEC/EN 60034 IEC, DIN, ISO, VDE, EN FS 180 M UKCA Environmental conditions: -20 °C - +40 °C / 1000 m Locked rotor time (hot / cold): 28.7 s | 41.6 s Mechanical data 66 / 73 dB(A) 2) 3) Sound level (SPL / SWL) at 50Hz|60Hz 68 / 75 dB(A) 2) 3) Vibration severity grade Α Moment of inertia 0.1300 kg m<sup>2</sup> Thermal class F Bearing DE | NDE 6210 2Z C3 6210 2Z C3 Duty type S1 bearing lifetime Direction of rotation bidirectional  $L_{10mh}\,F_{Rad\,\,min}$  for coupling operation  $50|60Hz^{\,1)}$ 40000 h 32000 h Frame material aluminum Regreasing device Without Net weight of the motor (IM B3) 134 kg Coating (paint finish) Standard paint finish C2 Grease nipple Locating bearing NDE RAL7030 Type of bearing Color, paint shade Condensate drainage holes Without Motor protection (A) without (Standard) External earthing terminal Without Method of cooling IC411 - self ventilated, surface cooled Terminal box Terminal box position top Max. cross-sectional area  $16 \, mm^2$ Material of terminal box Aluminium Cable diameter from ... to ... 19 mm - 28 mm Type of terminal box TB1 J00 2xM40x1,5 Cable entry Contact screw thread М5 Cable gland 2 plugs 1) L<sub>10mh</sub> according to DIN ISO 281 10/2010 3) Value is valid only for DOL operation with motor design IC411 IA/IN = locked rotor current / current nominal M<sub>A</sub>/M<sub>N</sub> = locked rotor torque / torque nominal 2) at rated power / at full load M<sub>K</sub>/M<sub>N</sub> = break down torque / nominal torque Transmittal, reproduction, dissemination and/or editing of this document as well as utilization of its contents and communication thereof to others without express authorization are prohibited. Offenders will be held liable for payment of damages. All rights created by patent grant or registration of a utility model or design patent are reserved. Responsible department Technical reference Created by Approved by Technical data are subject to change! There may be discrepancies between calculated and rating plate IN LVM SPC Created automatically Document type Document status Released INNOMOTICS Technical data sheet Document number 1LE1003-1EB23-4JA4 TDS-241021-151808

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