

SIMOTICS GP - 200 L - IM B3 - 4p

Client order no.	Item-No.	Offer no.
Order no.	Consignment no.	Project

Remarks

Safe Area

[illegible]

Mechanical data

Sound level (SPL / SWL) at 50Hz 60Hz	65 / 72 dB(A) ^{2) 3)}	67 / 74 dB(A) ^{2) 3)}	Vibration severity grade	A
Moment of inertia	0.2400 kg m²		Thermal class	F
Bearing DE NDE	6212 2Z C3	6212 2Z C3	Duty type	S1
bearing lifetime			Direction of rotation	bidirectional
L _{10mh} F _{Rad min} for coupling operation 50 60Hz ¹⁾	40000 h	32000 h	Frame material	aluminum
Regreasing device	No		Net weight of the motor (IM B3)	189 kg
Grease nipple	-/-		Coating (paint finish)	Standard paint finish C2
Type of bearing	Locating bearing NDE		Color, paint shade	RAL7030
Condensate drainage holes	No		Motor protection	(F) 1 temperature sensor KTY84-130 (2 terminals)
External earthing terminal	No		Method of cooling	IC411 - self ventilated, surface cooled

Terminal box

Terminal box position	left	Max. cross-sectional area	25 mm²
Material of terminal box	Aluminium	Cable diameter from ... to ...	27 mm - 35 mm
Type of terminal box	TB1 L00	Cable entry	2xM50x1,5-1xM16x1,5
Contact screw thread	M6	Cable gland	3 plugs

Notes:

I_r/I_n = locked rotor current / current nominal	1) L10mh according to DIN ISO 281 10/2010	3) Value is valid only for DOL operation with motor design IC411
M_r/M_n = locked rotor torque / torque nominal	2) at rated power / at full load	
M_b/M_n = break down torque / nominal torque		

responsible dep. DI MC LVM	technical reference	created by DT Configurator	approved by	Technical data are subject to change! There may be discrepancies between calculated and rating plate values.		Link documents 	
	document type datasheet			document status released			
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Data sheet for three-phase Squirrel-Cage-Motors SIMOTICS



Motor type : 1AV3205B

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Special design

G06 Mounting a rotary pulse encoder HOG 10 D 1024 I

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