Data sheet for three-phase Squirrel-Cage-Motors INNOMOTICS



INNOMOTICS GP - 100 L - IM B5 - 4p Motor type: 1AV3104B Offer no. Client order no. Item-No Order no. Consignment no. Project Remarks Safe Area Electrical data -/-U Δ/Υ f Р Р ī М η 3) $cos\phi^{\ 3)}$ I_A/I_N M_A/M_N M_K/M_N IE-CL n [V] [Hz] [kW] [hp] [A] [1/min] [Nm] 4/4 3/4 4/4 2/4 I_I/I_N T_I/T_N T_B/T_N 2/4 3/4 **DOL duty (S1)** - 155(F) to 130(B) 240 Δ 50 2.20 7.40 1455 14.4 86.7 87.2 86.3 0.82 0.76 0.64 8.3 3.0 3.8 IE3 50 2.20 -/-4.30 1455 0.76 3.8 415 14.4 86.7 87.2 86.3 0.82 0.64 8.3 3.0 IE3 Υ 480 60 2.55 -/-4.15 1750 13.9 89.5 90.1 89.2 0.77 0.66 8.8 3.0 3.9 IE3 0.83 Υ 480 60 3.00 3.75 1760 11.9 89.5 89.5 88.0 0.80 0.73 0.61 9.9 3.5 4.6 MG1 2.20 IM B5 / IM 3001 UKCA IEC/EN 60034 IEC, EN, UL, CSA, NEMA MG1-12-12 FS 100 L CC032A kVA Code: N Environmental conditions: -20 °C - +40 °C / 1000 m Locked rotor time (hot / cold): 18.9 s | 23 s Mechanical data 67 / 75 dB(A) 2) 3) Sound level (SPL / SWL) at 50Hz|60Hz 70 / 78 dB(A) 2) 3) Vibration severity grade Α Moment of inertia 0.0101 kg m² Thermal class F Bearing DE | NDE 6206 2Z C3 6206 2Z C3 Duty type S1 bearing lifetime Direction of rotation bidirectional $L_{10mh}\,F_{Rad\,\,min}$ for coupling operation $50|60Hz^{\,1)}$ 40000 h 32000 h Frame material aluminum Regreasing device Without Net weight of the motor (IM B3) 25 kg Coating (paint finish) Standard paint finish C2 Grease nipple Preloaded bearing DE Color, paint shade RAL7030 Type of bearing Condensate drainage holes Without Motor protection (B) 3 PTC thermistors - for tripping (2 terminals) External earthing terminal Without Method of cooling IC411 - self ventilated, surface cooled Terminal box Terminal box position top Max. cross-sectional area 4 mm² Material of terminal box Aluminium Cable diameter from ... to ... 11 mm - 21 mm Type of terminal box TB1 F00 2xM32x1,5-1xM16x1,5 Cable entry Contact screw thread Μ4 Cable gland 3 plugs 1) L_{10mh} according to DIN ISO 281 10/2010 3) Value is valid only for DOL operation with motor design IC411 I_A/I_N = locked rotor current / current nominal 2) at rated power / at full load M_A/M_N = locked rotor torque / torque nominal M_K/M_N = break down torque / nominal torque Transmittal, reproduction, dissemination and/or editing of this document as well as utilization of its contents and communication thereof to others without express authorization are prohibited. Offenders will be held liable for payment of damages. All rights created by patent grant or registration of a utility model or design patent are reserved.

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INNOMOTICS	Technical data sheet				Released			
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