## Data sheet for three-phase Squirrel-Cage-Motors INNOMOTICS



Motor type: 1AV3164D INNOMOTICS GP - 160 L - IM B3 - 8p Offer no. Client order no. Item-No Order no. Consignment no. Project Remarks Safe Area Electrical data -/η 3) U Δ/Υ f Р Р Τ М  $cos\phi^{3)}$  $I_A/I_N$  $M_A/M_N$  $M_K/M_N$ IE-CL n [V] [Hz] [kW] [hp] [A] [1/min] [Nm] 4/4 3/4  $T_I/T_N$  $T_B/T_N$ 2/4 4/4 3/4 2/4  $I_I/I_N$ **DOL duty (S1)** - 155(F) to 130(B) 230 Δ 50 7.50 29.50 730 98.0 87.3 87.9 86.9 0.73 0.64 0.52 5.8 2.3 2.7 IE3 400 7.50 -/-16.90 87.3 0.52 50 730 98.0 87.9 86.9 0.73 0.64 5.8 2.3 2.7 IE3 Υ 60 8.60 -/-880 93.0 88.5 90.1 89.2 0.66 0.54 IE2 460 16.50 0.74 6.1 2.3 2.7 Υ 2.6 60 7.50 10.00 14.80 81.0 89.5 89.5 0.50 6.7 2.6 MG1 460 885 88.1 0.71 0.62 IEC/EN 60034 IM B3 / IM 1001 UKCA IEC, EN, UL, CSA, NEMA MG1-12-12 FS 160 L CC032A IP55 kVA Code: Environmental conditions: -20 °C - +40 °C / 1000 m Locked rotor time (hot / cold): 24.8 s | 40 s Mechanical data Sound level (SPL / SWL) at 50Hz|60Hz 65 / 78 dB(A) 2) 3) 66 / 79 dB(A) 2) 3) Vibration severity grade Α Moment of inertia 0.1300 kg m<sup>2</sup> Thermal class F Bearing DE | NDE 6309 2Z C3 6209 2Z C3 Duty type S1 bearing lifetime Direction of rotation bidirectional  $L_{10mh}\,F_{Rad\,\,min}$  for coupling operation  $50|60Hz^{\,1)}$ 40000 h 32000 h Frame material aluminum Regreasing device Without Net weight of the motor (IM B3) 86 kg Coating (paint finish) Standard paint finish C2 Grease nipple Locating bearing NDE Type of bearing Color, paint shade RAL7030 (F) 1 temperature sensor KTY84-130 (2 terminals) Condensate drainage holes Without Motor protection External earthing terminal Without Method of cooling IC411 - self ventilated, surface cooled Terminal box Terminal box position right Max. cross-sectional area  $16 \, \text{mm}^2$ Material of terminal box Aluminium Cable diameter from ... to ... 19 mm - 28 mm Type of terminal box TB1 J00 2xM40x1,5-1xM16x1,5 Cable entry Contact screw thread М5 Cable gland 3 plugs 1) L<sub>10mh</sub> according to DIN ISO 281 10/2010 3) Value is valid only for DOL operation with motor design IC411 IA/IN = locked rotor current / current nominal M<sub>A</sub>/M<sub>N</sub> = locked rotor torque / torque nominal 2) at rated power / at full load M<sub>K</sub>/M<sub>N</sub> = break down torque / nominal torque Transmittal, reproduction, dissemination and/or editing of this document as well as utilization of its contents and communication thereof to others without express authorization are prohibited. Offenders will be held liable for payment of damages. All rights created by patent grant or registration of a utility model or design patent are reserved. Responsible department Technical reference Created by Approved by Technical data are subject to change! There may be discrepancies between calculated and rating plate IN LVM SPC Created automatically Document type Document status Released INNOMOTICS Technical data sheet Document number

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G41+L22

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Special c	lesign								
G41	Prepared to mount co	omponents with D12 shaf	ft	L22 Be	aring design	n for increa	sed cantilever forces		
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