Data sheet for three-phase Squirrel-Cage-Motors INNOMOTICS Motor type: 1AV3182B INNOMOTICS GP - 180 M - IM V1 - 4p Offer no. Client order no. Item-No Order no. Consignment no. Project Remarks Safe Area Electrical data -/η 3) Δ/Υ U f Р Р Τ М $cos\phi^{3)}$ I_A/I_N M_A/M_N M_K/M_N IE-CL n [V] [Hz] [kW] [hp] [A] [1/min] [Nm] 4/4 3/4 T_I/T_N T_B/T_N 2/4 4/4 3/4 2/4 I_I/I_N **DOL duty (S1)** - 155(F) to 130(B) 230 Δ 50 18.50 61.00 1470 120.0 92.6 93.1 93.0 0.82 0.77 0.67 7.2 2.5 3.3 IE3 400 18.50 -/-35.00 1470 0.77 0.67 50 120.0 92.6 93.1 93.0 0.82 7.2 2.5 3.3 IE3 Υ 460 60 21.30 -/-34.50 1770 93.6 94.0 93.8 0.78 0.69 7.2 IE3 115.0 0.83 2.4 3.2 Υ 0.75 460 60 18.50 25.00 30.50 1775 100.0 93.6 93.7 0.64 7.8 2.7 3.6 MG1 93.1 0.81 IM V1 / IM 3011 IEC/EN 60034 IEC, EN, UL, CSA, NEMA MG1-12-12 FS 180 M CC032A IP55 UKCA Environmental conditions: -20 °C - +40 °C / 1000 m Locked rotor time (hot / cold): 28.7 s | 41.6 s Mechanical data Sound level (SPL / SWL) at 50Hz|60Hz 66 / 73 dB(A) 2) 3) 68 / 75 dB(A) 2) 3) Vibration severity grade Α Moment of inertia 0.1300 kg m² Thermal class F Bearing DE | NDE 6210 2Z C3 6210 2Z C3 Duty type S1 bearing lifetime Direction of rotation bidirectional $L_{10mh}\,F_{Rad\,\,min}$ for coupling operation $50|60Hz^{\,1)}$ 20000 h 16000 h Frame material aluminum Regreasing device Without Net weight of the motor (IM B3) 134 kg Coating (paint finish) Standard paint finish C2 Grease nipple Locating bearing NDE RAL7030 Type of bearing Color, paint shade Condensate drainage holes Without Motor protection (A) without (Standard) External earthing terminal Without Method of cooling IC411 - self ventilated, surface cooled Terminal box Terminal box position top Max. cross-sectional area $16 \, mm^2$ Material of terminal box Aluminium Cable diameter from ... to ... 19 mm - 28 mm Type of terminal box TB1 J00 2xM40x1,5 Cable entry Contact screw thread М5 Cable gland 2 plugs 1) L_{10mh} according to DIN ISO 281 10/2010 3) Value is valid only for DOL operation with motor design IC411 IA/IN = locked rotor current / current nominal M_A/M_N = locked rotor torque / torque nominal 2) at rated power / at full load M_K/M_N = break down torque / nominal torque Transmittal, reproduction, dissemination and/or editing of this document as well as utilization of its contents and communication thereof to others without express authorization are prohibited. Offenders will be held liable for payment of damages. All rights created by patent grant or registration of a utility model or design patent are reserved.

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