

Data sheet for three-phase Squirrel-Cage-Motors SIMOTICS



Motor type : 1CV3130B

SIMOTICS SD - 132 S - IM B35 - 4p

Client order no.	Item-No.	Offer no.
Order no.	Consignment no.	Project

Remarks

Electrical data

Safe Area

U	Δ / Y	f	P	P	I	n	M	η ³⁾			cosφ ³⁾			I _A /I _N	M _A /M _N	M _K /M _N	IE-CL
[V]		[Hz]	[kW]	[hp]	[A]	[1/min]	[Nm]	4/4	3/4	2/4	4/4	3/4	2/4	I _I /I _N	T _I /T _N	T _B /T _N	
DOL duty (S1) - 155(F) to 130(B)																	
230	Δ	50	5.50	-/-	18.80	1470	35.5	89.6	90.0	89.4	0.82	0.77	0.67	8.5	2.9	3.7	IE3
400	Y	50	5.50	-/-	10.80	1470	35.5	89.6	90.0	89.4	0.82	0.77	0.67	8.5	2.9	3.7	IE3
460	Y	60	6.30	-/-	10.40	1770	34.0	91.7	92.0	91.3	0.83	0.79	0.69	8.7	2.7	3.7	IE3
460	Y	60	5.50	-/-	9.30	1775	29.5	91.7	91.6	90.5	0.81	0.76	0.65	10.0	3.1	4.2	IE3
IM B35 / IM 2001			FS 132 S				IP55			IEC/EN 60034		IEC, DIN, ISO, VDE, EN					
Environmental conditions : -20 °C - +40 °C / 1.000 m									Locked rotor time (hot / cold) : 22.8 s 29.1 s								

Mechanical data

Sound level (SPL / SWL) at 50Hz 60Hz	64 / 76 dB(A) ^{2) 3)}	68 / 80 dB(A) ^{2) 3)}	Vibration severity grade	A
Moment of inertia	0.0340 kg m ²		Thermal class	F
Bearing DE NDE	6208 2Z C3	6208 2Z C3	Duty type	S1
bearing lifetime			Direction of rotation	bidirectional
L _{10mh} F _{Rad min} for coupling operation 50 60Hz ¹⁾	40000 h	32000 h	Frame material	cast iron
Lubricants	Unirex N3		Net weight of the motor (IM B3)	74 kg
Regreasing device	No		Coating (paint finish)	Standard paint finish C2
Grease nipple	-/-		Color, paint shade	RAL7030
Type of bearing	Preloaded bearing DE		Motor protection	(F) 1 temperature sensor KTY84-130 (2 terminals)
Condensate drainage holes	Yes (standard)		Method of cooling	IC411 - self ventilated, surface cooled
External earthing terminal	No			

Terminal box

Terminal box position	top	Max. cross-sectional area	6 mm ²
Material of terminal box	cast iron	Cable diameter from ... to ...	11 mm - 21 mm
Type of terminal box	TB1 H01	Cable entry	2xM32x1,5-1xM16x1,5
Contact screw thread	M4	Cable gland	3 plugs

Notes:

I _A /I _N = locked rotor current / current nominal	1) L10mh according to DIN ISO 281 10/2010	3) Value is valid only for DOL operation with motor design IC411
M _K /M _N = locked rotor torque / torque nominal	2) at rated power / at full load	
M _B /M _N = break down torque / nominal torque		

responsible dep.	technical reference	created by	approved by	Technical data are subject to change! There may be discrepancies between calculated and rating plate values.	Link documents
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Special design

G11 Rotary pulse encoder Sendix 5020 (HTL) H00 Canopy

Notes:

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DI MC LVM

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