

Datasheet for SIMOGEAR Geared Motors



19.42

MLFB-Ordering data: 2KJ3105-1FL22-9AL1-Z

D01+G24+G34+K03+K07+L02+L70+M55+N4E

Client order no.:

Order no.:

Offer no.:

Offer no.:

Project:

	Motor data																		
U [V]	D/Y	f _N [Hz]	P _N [kW]	P _N [hp]	I _N [A]	n _N [rpm]	T _N [Nm]	IE-CL	Operating mode	n ₂ [rpm]	T ₂ [Nm]	f _B	η _{4/4 load} [%]	η _{3/4 load} [%]	cos φ	I _A /I _N	T _A /T _N	T _K /T _N	T _H /T _N
440	Υ	60	2.200	2.95	4.23	1,760	11.93	IE2	S1	115.258	182.29	2.47	87.5	88.3	0.78	8.10	2.50	3.90	2.80

Motor type 1LE motor with High Efficiency LE100LE4E

 Number of poles
 4-pole

 Degree of protection
 (K03) IP65

 Thermal class
 155 (F)

 Moment of inertia Jmot
 0.00860 kgm²

Geared motor SIMOGEAR Z59-LE100LE4E Type designation Gearbox Helical gearbox Z59 Mounting type gearbox Foot-mounted design Output shaft V35 x 70 mm (Solid shaft with feather Mounting position (D01) M1 Transmission ratio 15.27 (611 / 40) Nominal torque 450.00 Nm Gear oil (K07) Synthetic oil CLP PG VG220 0.71 Oil charge Specification CE (Europe / other countries) **Environment temperature** -15 ... +40 °C Weight without oil 42.9 kg Housing material first gearbox Cast iron

Gearbox options						
Output shaft bearing	Standard bearing					
Output shaft sealing	(G24) Seal for increased environmental stress					
Gearbox breather	Pressure breather valve					
Oil level control	(G34) Oil sight glass					
Oil drain	Oil drain plug					

	Motor options	
Motor protection	Without	

Terminal box position (M55) 1A

Electrical connection at terminal box

Cable gland metric

Ventilation Standard fan

General options						
Surface treatments	Painted					
Coating	(L02) Coating for normal environmental stress C1					
RAL Color	(L70) 6011 reseda green					
Coating on flange	-					
Packing	Standard packing					

Front on information						
Further information						
General product information	SIMOGEAR					
Configurator	<u>2KJ</u>					
Operating instructions						
Gearbox	BA 2030					
Motor	BA 2330					
Catalog	MD 50.1 Geared motors					

Leg	en	d

U = Voltage
D / Y = Circuit
f = Frequency
P_N = Rated motor power

 I_{N} = Rated current n_{N} = Rated motor speed T_{N} = Rated motor torque IE-CL = Efficiency class

n₂ = Geared motor output speed

 T_2 = Geared motor output torque f_B = Service factor

η = Efficiency *) On request $\cos \phi = \text{Power factor} \\ I_M I_N = \text{Relative starting current} \\ T_M T_N = \text{Relative starting torque} \\ T_M T_N = \text{Relative breakdown torque} \\ T_M T_N = \text{Relative average acceleration torque} \\$