SIEMENS

Data sheet

6ES7512-1CK01-0AB0



SIMATIC S7-1500 COMPACT CPU CPU 1512C-1 PN, CENTRAL PROCESSING UNIT WITH WORKING MEMORY 250 KB FOR PROGRAM AND 1 MB FOR DATA, 32 DIGITAL INPUTS, 32 DIGITAL OUTPUTS, 5 ANALOG INPUTS, 2 ANALOG OUTPUTS, 6 HIGH SPEED COUNTERS, 4 HIGH SPEED OUTPUTS FOR PTO/PWM/FREQUENCY OUTPUT 1. INTERFACE: PROFINET IRT WITH 2 PORT SWITCH, 48 NS BIT-PERFORMANCE, INCL. FRONT CONNECTOR PUSH-IN, SIMATIC MEMORY CARD **NECESSARY**

General information	
Product type designation	CPU 1512C-1 PN
HW functional status	FS01
Firmware version	V2.5
Engineering with	
 STEP 7 TIA Portal configurable/integrated as of version 	V15
Configuration control	
via dataset	Yes
Display	
Screen diagonal [cm]	3.45 cm
Control elements	
Number of keys	8
Mode buttons	2
Supply voltage	
Type of supply voltage	24 V DC
permissible range, lower limit (DC)	19.2 V; 20.4 V DC, for supplying the digital inputs/outputs

permissible range, upper limit (DC)	28.8 V
Reverse polarity protection	Yes
Mains buffering	
Mains/voltage failure stored energy time	5 ms; Refers to the power supply on the CPU section
Repeat rate, min.	1/s
Input current	
Current consumption (rated value)	0.8 A; Without load; 18.8 A: CPU + load
Current consumption, max.	1 A; Without load; 19 A: CPU + load
Inrush current, max.	1.9 A; Rated value
I ² t	0.34 A²·s
Digital inputs	
• from load voltage L+ (without load), max.	20 mA; per group
Digital outputs	
from load voltage L+, max.	30 mA; Per group, without load
Output voltage	
Rated value (DC)	24 V
Faradayanah	
Encoder supply Number of outputs	2; One common 24 V encoder supply per 16 digital inputs
24 V encoder supply	2, One common 24 v encoder supply per 10 digital inputs
• 24 V	Yes; L+ (-0.8 V)
	Yes
Short-circuit protection	
Output current, max.	1 A
Power	
Infeed power to the backplane bus	10 W
Power consumption from the backplane bus	9 W
(balanced)	
Power loss	
Power loss, typ.	15.2 W
Memory	
Number of slots for SIMATIC memory card	1
SIMATIC memory card required	Yes
Work memory	
• integrated (for program)	250 kbyte
• integrated (for data)	1 Mbyte
Load memory	
Plug-in (SIMATIC Memory Card), max.	32 Gbyte
Backup	
maintenance-free	Yes
CPU processing times	40
for bit operations, typ.	48 ns

for word operations, typ.	58 ns
for fixed point arithmetic, typ.	77 ns
for floating point arithmetic, typ.	307 ns
CPU-blocks	
Number of elements (total)	2 000; Blocks (OB, FB, FC, DB) and UDTs
DB	
Number range	1 60 999; subdivided into: number range that can be used by the user: 1 59 999, and number range of DBs created via SFC 86: 60 000 60 999
• Size, max.	1 Mbyte; For non-optimized block accesses, the max. size of the DB is 64 KB
FB	
Number range	0 65 535
• Size, max.	250 kbyte
FC	
Number range	0 65 535
• Size, max.	250 kbyte
ОВ	
• Size, max.	250 kbyte
 Number of free cycle OBs 	100
 Number of time alarm OBs 	20
 Number of delay alarm OBs 	20
 Number of cyclic interrupt OBs 	20; With minimum OB 3x cycle of 500 μs
 Number of process alarm OBs 	50
 Number of DPV1 alarm OBs 	3
 Number of isochronous mode OBs 	1
Number of technology synchronous alarm OBs	2
Number of startup OBs	100
Number of asynchronous error OBs	4
Number of synchronous error OBs	2
Number of diagnostic alarm OBs	1
Nesting depth	
• per priority class	24
Counters, timers and their retentivity	
S7 counter	
Number	2 048
Retentivity	
— adjustable	Yes
IEC counter	
• Number	Any (only limited by the main memory)
Detentivity	

Retentivity

— adjustable

Yes

S7 times	
Number	2 048
Retentivity	
— adjustable	Yes
IEC timer	
Number	Any (only limited by the main memory)
Retentivity	
— adjustable	Yes
Data areas and their retentivity	
Data areas and their retentivity Retentive data area (incl. timers, counters, flags),	128 kbyte; In total; available retentive memory for bit memories,
max.	timers, counters, DBs, and technology data (axes): 88 KB
Extended retentive data area (incl. timers, counters,	1 Mbyte; When using PS 60W 24/48/60V DC HF
flags), max.	
Flag	
Number, max.	16 kbyte
 Number of clock memories 	8; 8 clock memory bit, grouped into one clock memory byte
Data blocks	
Retentivity adjustable	Yes
 Retentivity preset 	No
Local data	
per priority class, max.	64 kbyte; max. 16 KB per block
Address area	
Number of IO modules	2 048; max. number of modules / submodules
I/O address area	
• Inputs	32 kbyte; All inputs are in the process image
InputsOutputs	32 kbyte; All inputs are in the process image 32 kbyte; All outputs are in the process image
• Outputs	
Outputs per integrated IO subsystem	32 kbyte; All outputs are in the process image
Outputs per integrated IO subsystem — Inputs (volume)	32 kbyte; All outputs are in the process image 8 kbyte
 Outputs per integrated IO subsystem — Inputs (volume) — Outputs (volume) 	32 kbyte; All outputs are in the process image 8 kbyte
Outputs per integrated IO subsystem — Inputs (volume) — Outputs (volume) per CM/CP	32 kbyte; All outputs are in the process image 8 kbyte 8 kbyte
 Outputs per integrated IO subsystem — Inputs (volume) — Outputs (volume) per CM/CP — Inputs (volume) 	32 kbyte; All outputs are in the process image 8 kbyte 8 kbyte 8 kbyte
 Outputs per integrated IO subsystem — Inputs (volume) — Outputs (volume) per CM/CP — Inputs (volume) — Outputs (volume) 	32 kbyte; All outputs are in the process image 8 kbyte 8 kbyte 8 kbyte
Outputs per integrated IO subsystem — Inputs (volume) — Outputs (volume) per CM/CP — Inputs (volume) — Outputs (volume) Subprocess images Number of subprocess images, max.	32 kbyte; All outputs are in the process image 8 kbyte 8 kbyte 8 kbyte 8 kbyte
● Outputs per integrated IO subsystem — Inputs (volume) — Outputs (volume) per CM/CP — Inputs (volume) — Outputs (volume) Subprocess images ● Number of subprocess images, max. Hardware configuration	32 kbyte; All outputs are in the process image 8 kbyte 8 kbyte 8 kbyte 32
Outputs per integrated IO subsystem — Inputs (volume) — Outputs (volume) per CM/CP — Inputs (volume) — Outputs (volume) Subprocess images Number of subprocess images, max.	32 kbyte; All outputs are in the process image 8 kbyte 8 kbyte 8 kbyte 8 kbyte
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● Outputs per integrated IO subsystem — Inputs (volume) — Outputs (volume) per CM/CP — Inputs (volume) — Outputs (volume) Subprocess images ● Number of subprocess images, max. Hardware configuration	32 kbyte; All outputs are in the process image 8 kbyte 8 kbyte 8 kbyte 32 32; A distributed I/O system is characterized not only by the integration of distributed I/O via PROFINET or PROFIBUS communication modules, but also by the connection of I/O via AS-i master modules or links (e.g. IE/PB-Link)
Outputs per integrated IO subsystem — Inputs (volume) — Outputs (volume) per CM/CP — Inputs (volume) — Outputs (volume) Subprocess images Number of subprocess images, max. Hardware configuration Number of distributed IO systems	32 kbyte; All outputs are in the process image 8 kbyte 8 kbyte 8 kbyte 32 32; A distributed I/O system is characterized not only by the integration of distributed I/O via PROFINET or PROFIBUS communication modules, but also by the connection of I/O via AS-

Number of IO Controllers	
• integrated	1
• Via CM	6; A maximum of 6 CMs/CPs (PROFIBUS, PROFINET, Ethernet) can be inserted in total
Rack	
Modules per rack, max.	32; CPU + 31 modules
Number of lines, max.	1
PtP CM	
Number of PtP CMs	the number of connectable PtP CMs is only limited by the number of available slots
Time of day	
Clock	
● Type	Hardware clock
Backup time	6 wk; At 40 °C ambient temperature, typically
Deviation per day, max.	10 s; Typ.: 2 s
Operating hours counter	
Number	16
Clock synchronization	
• supported	Yes
• in AS, master	Yes
• in AS, slave	Yes
• on Ethernet via NTP	Yes
Digital inputs	
integrated channels (DI)	32
Digital inputs, parameterizable	Yes
Source/sink input	P-reading
Input characteristic curve in accordance with IEC 61131, type 3	Yes
Digital input functions, parameterizable	
Gate start/stop	Yes
Capture	Yes
 Synchronization 	Yes
Input voltage	
Type of input voltage	DC
• Rated value (DC)	24 V
• for signal "0"	-3 to +5V
• for signal "1"	+11 to +30V
Input current	
• for signal "1", typ.	2.5 mA
Input delay (for rated value of input voltage)	
for standard inputs	

— at "0" to "1", min.	4 μs; for parameterization "none"
— at "0" to "1", max.	20 ms
— at "1" to "0", min.	4 μs; for parameterization "none"
— at "1" to "0", max.	20 ms
for interrupt inputs	
— parameterizable	Yes; Same as for standard inputs
for technological functions	
— parameterizable	Yes; Same as for standard inputs
Cable length	
• shielded, max.	1 000 m; 600 m for technological functions; depending on input
	frequency, encoder and cable quality; max. 50 m at 100 kHz
• unshielded, max.	600 m; For technological functions: No
Digital outputs	
Type of digital output	Transistor
integrated channels (DO)	32
Current-sourcing	Yes; Push-pull output
Short-circuit protection	Yes; electronic/thermal
 Response threshold, typ. 	1.6 A with standard output, 0.5 A with high-speed output; see
	manual for details
Limitation of inductive shutdown voltage to	Connector X11: -0.8 V; connector X12: L+ (-53 V)
Controlling a digital input	Yes
Accuracy of pulse duration	Up to ±100 ppm ±2 μs at high-speed output; see manual for details
minimum pulse duration	2 μs; With High Speed output
Digital output functions, parameterizable	
 Switching tripped by comparison values 	Yes; As output signal of a high-speed counter
 PWM output 	Yes
— Number, max.	4
 Cycle duration, parameterizable 	Yes
— ON period, min.	0 %
— ON period, max.	100 %
 Resolution of the duty cycle 	0.0036 %; For S7 analog format, min. 40 ns
 Frequency output 	Yes
Pulse train	Yes; also for pulse/direction interface
Switching capacity of the outputs	
• with resistive load, max.	0.5 A; 0.1 A with high-speed output, i.e. when using a high-speed output; see manual for details
• on lamp load, max.	5 W; 1 W with high-speed output, i.e. when using a high-speed output; see manual for details
Load resistance range	
• lower limit	48 Ω ; 240 ohms with high-speed output, i.e. when using a high-speed output; see manual for details
• upper limit	12 kΩ

Output voltage	
Type of output voltage	DC
• for signal "0", max.	1 V; With high-speed output, i.e. when using a high-speed output; see manual for details
• for signal "1", min.	23.2 V; L+ (-0.8 V)
Output current	
● for signal "1" rated value	0.5 A; 0.1 A with high-speed output, i.e. when using a high-speed output, observe derating; see manual for details
for signal "1" permissible range, min.	2 mA
● for signal "1" permissible range, max.	0.6 A; 0.12 A with high-speed output, i.e. when using a high-speed output, observe derating; see manual for details
for signal "0" residual current, max.	0.5 mA
Output delay with resistive load	
• "0" to "1", max.	200 μs
• "1" to "0", max.	500 μs; Load-dependent
for technological functions	
— "0" to "1", max.	$5\ \mu s;$ Depending on the output used, see additional description in manual
— "1" to "0", max.	$5\;\mu\text{s};$ Depending on the output used, see additional description in manual
Parallel switching of two outputs	
• for logic links	Yes; For technological functions: No
• for uprating	No
 for redundant control of a load 	Yes; For technological functions: No
Switching frequency	
with resistive load, max.	100 kHz; For high-speed output, 100 Hz for standard output
with inductive load, max.	0.5 Hz; Acc. to IEC 60947-5-1, DC-13; observe derating curve
• on lamp load, max.	10 Hz
Total current of the outputs	
Current per channel, max.	0.5 A; see additional description in the manual
 Current per group, max. 	8 A; see additional description in the manual
 Current per power supply, max. 	4 A; 2 power supplies for each group, current per power supply max. 4 A, see additional description in manual
for technological functions	
— Current per channel, max.	0.5 A; see additional description in the manual
Cable length	
• shielded, max.	1 000 m; 600 m for technological functions; depending on output frequency, load, and cable quality; max. 50 m at 100 kHz
• unshielded, max.	600 m; For technological functions: No
Analog inputs	
Number of analog inputs	5; 4x for U/I, 1x for R/RTD
 For current measurement 	4; max.
 For voltage measurement 	4; max.

For resistance/resistance thermometer measurement permissible input voltage for voltage input (destruction limit), max. permissible input current for current input (destruction limit), max. Cycle time (all channels), min. 1 ms; Dependent on the parameter suppression; for details, see convenience.	
(destruction limit), max. permissible input current for current input (destruction limit), max. Cycle time (all channels), min. 40 mA 1 ms; Dependent on the parameter	
limit), max. Cycle time (all channels), min. 1 ms; Dependent on the parameter	
· ·	
Technical unit for temperature measurement Adjustable Yes; °C/°F/K	
Input ranges (rated values), voltages	
• 0 to +10 V Yes; Physical measuring range: ±	: 10 V
• Input resistance (0 to 10 V) 100 kΩ	
• 1 V to 5 V Yes; Physical measuring range: ±	: 10 V
• Input resistance (1 V to 5 V) 100 kΩ	
• -10 V to +10 V	
• Input resistance (-10 V to +10 V) 100 kΩ	
• -5 V to +5 V Yes; Physical measuring range: ±	: 10 V
• Input resistance (-5 V to +5 V) 100 kΩ	
Input ranges (rated values), currents	
• 0 to 20 mA Yes; Physical measuring range: ±	: 20 mA
 Input resistance (0 to 20 mA) 50 Ω; Plus approx. 55 ohm for over 	ervoltage protection by PTC
• -20 mA to +20 mA Yes	
• Input resistance (-20 mA to +20 mA) 50 Ω; Plus approx. 55 ohm for over	ervoltage protection by PTC
• 4 mA to 20 mA Yes; Physical measuring range: ±	: 20 mA
 Input resistance (4 mA to 20 mA) 50 Ω; Plus approx. 55 ohm for over 	ervoltage protection by PTC
Input ranges (rated values), resistance thermometer	
Ni 100 Yes; Standard/climate	
• Input resistance (Ni 100) 10 MΩ	
• Pt 100 Yes; Standard/climate	
• Input resistance (Pt 100) 10 MΩ	
Input ranges (rated values), resistors	
• 0 to 150 ohms Yes; Physical measuring range: 0	600 ohms
• Input resistance (0 to 150 ohms) 10 MΩ	
• 0 to 300 ohms Yes; Physical measuring range: 0) 600 ohms
• Input resistance (0 to 300 ohms) 10 MΩ	
• 0 to 600 ohms Yes	
• Input resistance (0 to 600 ohms) 10 MΩ	
Cable length	
• shielded, max. 800 m; for U/I, 200 m for R/RTD	
Analog outputs	
integrated channels (AO) 2	

Voltage output, short-circuit protection	Yes
Cycle time (all channels), min.	1 ms; Dependent on the parameterized interference frequency
	suppression; for details, see conversion procedure in manual
Output ranges, voltage	
• 0 to 10 V	Yes
● 1 V to 5 V	Yes
• -10 V to +10 V	Yes
Output ranges, current	
• 0 to 20 mA	Yes
• -20 mA to +20 mA	Yes
• 4 mA to 20 mA	Yes
Load impedance (in rated range of output)	
with voltage outputs, min.	1 kΩ
 with voltage outputs, capacitive load, max. 	100 nF
• with current outputs, max.	500 Ω
 with current outputs, inductive load, max. 	1 mH
Cable length	
• shielded, max.	200 m
Analog value generation for the inputs	
Integration and conversion time/resolution per channel	
 Resolution with overrange (bit including sign), 	16 bit
max.	
 Integration time, parameterizable 	Yes; 2.5 / 16.67 / 20 / 100 ms, acts on all channels
Interference voltage suppression for	400 / 60 / 50 / 10
interference frequency f1 in Hz	
Smoothing of measured values	No.
parameterizable	Yes
Step: None	Yes
• Step: low	Yes
Step: Medium	Yes
Step: High	Yes
Analog value generation for the outputs	
Integration and conversion time/resolution per channel	
 Resolution with overrange (bit including sign), 	16 bit
max.	
Settling time	
for resistive load	1.5 ms
for capacitive load	2.5 ms
• for inductive load	2.5 ms
Encoder	
Connection of signal encoders	

• for valte as a second	Yes
• for voltage measurement	
 for current measurement as 4-wire transducer 	Yes
 for resistance measurement with two-wire connection 	Yes
 for resistance measurement with three-wire connection 	Yes
 for resistance measurement with four-wire connection 	Yes
Connectable encoders	
• 2-wire sensor	Yes
 permissible quiescent current (2-wire sensor), max. 	1.5 mA
Encoder signals, incremental encoder (asymmetrical)	
Input voltage	24 V
Input frequency, max.	100 kHz
Counting frequency, max.	400 kHz; with quadruple evaluation
Signal filter, parameterizable	Yes
 Incremental encoder with A/B tracks, 90° phase offset 	Yes
 Incremental encoder with A/B tracks, 90° phase offset and zero track 	Yes
Pulse encoder	Yes
Pulse encoder with direction	Yes
Pulse encoder with one impulse signal per	Yes
count direction	
count direction Errors/accuracies Linearity error (relative to input range), (+/-)	0.1 %
Errors/accuracies	0.1 % 0.005 %/K
Errors/accuracies Linearity error (relative to input range), (+/-)	
Errors/accuracies Linearity error (relative to input range), (+/-) Temperature error (relative to input range), (+/-)	0.005 %/K
Errors/accuracies Linearity error (relative to input range), (+/-) Temperature error (relative to input range), (+/-) Crosstalk between the inputs, max. Repeat accuracy in steady state at 25 °C (relative to	0.005 %/K -60 dB
Errors/accuracies Linearity error (relative to input range), (+/-) Temperature error (relative to input range), (+/-) Crosstalk between the inputs, max. Repeat accuracy in steady state at 25 °C (relative to input range), (+/-) Output ripple (relative to output range, bandwidth 0 to	0.005 %/K -60 dB 0.05 %
Errors/accuracies Linearity error (relative to input range), (+/-) Temperature error (relative to input range), (+/-) Crosstalk between the inputs, max. Repeat accuracy in steady state at 25 °C (relative to input range), (+/-) Output ripple (relative to output range, bandwidth 0 to 50 kHz), (+/-)	0.005 %/K -60 dB 0.05 % 0.02 %
Errors/accuracies Linearity error (relative to input range), (+/-) Temperature error (relative to input range), (+/-) Crosstalk between the inputs, max. Repeat accuracy in steady state at 25 °C (relative to input range), (+/-) Output ripple (relative to output range, bandwidth 0 to 50 kHz), (+/-) Linearity error (relative to output range), (+/-)	0.005 %/K -60 dB 0.05 % 0.02 %
Errors/accuracies Linearity error (relative to input range), (+/-) Temperature error (relative to input range), (+/-) Crosstalk between the inputs, max. Repeat accuracy in steady state at 25 °C (relative to input range), (+/-) Output ripple (relative to output range, bandwidth 0 to 50 kHz), (+/-) Linearity error (relative to output range), (+/-) Temperature error (relative to output range), (+/-)	0.005 %/K -60 dB 0.05 % 0.02 % 0.15 % 0.005 %/K
Errors/accuracies Linearity error (relative to input range), (+/-) Temperature error (relative to input range), (+/-) Crosstalk between the inputs, max. Repeat accuracy in steady state at 25 °C (relative to input range), (+/-) Output ripple (relative to output range, bandwidth 0 to 50 kHz), (+/-) Linearity error (relative to output range), (+/-) Temperature error (relative to output range), (+/-) Crosstalk between the outputs, max. Repeat accuracy in steady state at 25 °C (relative to	0.005 %/K -60 dB 0.05 % 0.02 % 0.15 % 0.005 %/K -80 dB
Errors/accuracies Linearity error (relative to input range), (+/-) Temperature error (relative to input range), (+/-) Crosstalk between the inputs, max. Repeat accuracy in steady state at 25 °C (relative to input range), (+/-) Output ripple (relative to output range, bandwidth 0 to 50 kHz), (+/-) Linearity error (relative to output range), (+/-) Temperature error (relative to output range), (+/-) Crosstalk between the outputs, max. Repeat accuracy in steady state at 25 °C (relative to output range), (+/-)	0.005 %/K -60 dB 0.05 % 0.02 % 0.15 % 0.005 %/K -80 dB
Errors/accuracies Linearity error (relative to input range), (+/-) Temperature error (relative to input range), (+/-) Crosstalk between the inputs, max. Repeat accuracy in steady state at 25 °C (relative to input range), (+/-) Output ripple (relative to output range, bandwidth 0 to 50 kHz), (+/-) Linearity error (relative to output range), (+/-) Temperature error (relative to output range), (+/-) Crosstalk between the outputs, max. Repeat accuracy in steady state at 25 °C (relative to output range), (+/-) Operational error limit in overall temperature range	0.005 %/K -60 dB 0.05 % 0.02 % 0.15 % 0.005 %/K -80 dB 0.05 %

 Resistance thermometer, relative to input range, (+/-) 	Pt100 Standard: ±2 K, Pt100 Climate: ±1 K, Ni100 Standard: ±1.2 K, Ni100 Climate: ±1 K
 Voltage, relative to output range, (+/-) 	0.3 %
 Current, relative to output range, (+/-) 	0.3 %
Basic error limit (operational limit at 25 °C)	
 Voltage, relative to input range, (+/-) 	0.2 %
 Current, relative to input range, (+/-) 	0.2 %
 Resistance, relative to input range, (+/-) 	0.2 %
 Resistance thermometer, relative to input range, (+/-) 	Pt100 Standard: ±1 K, Pt100 Climate: ±0.5 K, Ni100 Standard: ±0.6 K, Ni100 Climate: ±0.5 K
 Voltage, relative to output range, (+/-) 	0.2 %
 Current, relative to output range, (+/-) 	0.2 %
Interference voltage suppression for f = n x (f1 +/- 1 %)	, f1 = interference frequency
 Series mode interference (peak value of interference < rated value of input range), min. 	30 dB
 Common mode voltage, max. 	10 V
• Common mode interference, min.	60 dB; at 400 Hz: 50 dB
Interfaces	
Number of PROFINET interfaces	1
1. Interface	
Interface types	
 Number of ports 	2
• integrated switch	Yes
RJ 45 (Ethernet)	Yes; X1
Protocols	
IP protocol	Yes; IPv4
PROFINET IO Controller	Yes
PROFINET IO Device	Yes
SIMATIC communication	Yes
Open IE communication	Yes
Web server	Yes
Media redundancy	Yes; MRP Automanager according to IEC 62439-2 Edition 2.0
PROFINET IO Controller	
Services	
— PG/OP communication	Yes
— S7 routing	Yes
— Isochronous mode	Yes
— Open IE communication	Yes
— IRT	Yes
— MRP	Yes; As MRP redundancy manager and/or MRP client; max. number of devices in the ring: 50

— MRPD	Yes; Requirement: IRT
 Prioritized startup 	Yes; Max. 32 PROFINET devices
— Number of connectable IO Devices, max.	128; In total, up to 512 distributed I/O devices can be connected via AS-i, PROFIBUS or PROFINET
 Of which IO devices with IRT, max. 	64
 Number of connectable IO Devices for RT, 	128
max.	
— of which in line, max.	128
 Number of IO Devices that can be simultaneously activated/deactivated, max. 	8; in total across all interfaces
 Number of IO Devices per tool, max. 	8
— Updating times	The minimum value of the update time also depends on communication share set for PROFINET IO, on the number of IO devices, and on the quantity of configured user data
Update time for IRT	
— for send cycle of 250 μs	$250~\mu s$ to 4 ms; Note: In the case of IRT with isochronous mode, the minimum update time of 625 μs of the isochronous OB is decisive
— for send cycle of 500 μs	$500~\mu s$ to 8 ms; Note: In the case of IRT with isochronous mode, the minimum update time of $625~\mu s$ of the isochronous OB is decisive
— for send cycle of 1 ms	1 ms to 16 ms
— for send cycle of 2 ms	2 ms to 32 ms
— for send cycle of 4 ms	4 ms to 64 ms
 With IRT and parameterization of "odd" send cycles 	Update time = set "odd" send clock (any multiple of 125 μ s: 375 μ s, 625 μ s 3 875 μ s)
Update time for RT	F-/
— for send cycle of 250 μs	250 µs to 128 ms
— for send cycle of 500 µs	500 μs to 256 ms
— for send cycle of 1 ms	1 ms to 512 ms
— for send cycle of 2 ms	2 ms to 512 ms
— for send cycle of 4 ms	4 ms to 512 ms
PROFINET IO Device	
Services	
— PG/OP communication	Yes
— S7 routing	Yes
— Isochronous mode	No
 Open IE communication 	Yes
— IRT	Yes
— MRP	Yes
— MRPD	Yes; Requirement: IRT
— PROFlenergy	Yes
— Shared device	Yes

 Number of IO Controllers with shared device, max.

- Asset management record

4

Yes; Per user program

Interface types

RJ 45 (Ethernet)

Yes • 100 Mbps Yes Autonegotiation Yes Autocrossing

• Industrial Ethernet status LED Yes

Protocols

Number of connections

128; via integrated interfaces of the CPU and connected CPs / • Number of connections, max. CMs 10 • Number of connections reserved for ES/HMI/web 88 • Number of connections via integrated interfaces

16 Number of S7 routing paths

PROFINET IO Controller

Services

- PG/OP communication Yes Yes - S7 routing Yes - Isochronous mode

Yes - Open IE communication - IRT Yes

- PROFlenergy Yes

Yes; Max. 32 PROFINET devices - Prioritized startup

- Number of connectable IO Devices, max. 128; In total, up to 512 distributed I/O devices can be connected via AS-i, PROFIBUS or PROFINET

64 - Of which IO devices with IRT, max.

128 - Number of connectable IO Devices for RT, max.

128 - of which in line, max.

- Number of IO Devices that can be 8; in total across all interfaces simultaneously activated/deactivated, max.

8 - Number of IO Devices per tool, max.

The minimum value of the update time also depends on - Updating times communication share set for PROFINET IO, on the number of IO

devices, and on the quantity of configured user data

Redundancy mode

Yes; As MRP redundancy manager and/or MRP client; max. - MRP

number of devices in the ring: 50

Yes; Requirement: IRT - MRPD

SIMATIC communication	
S7 communication, as server	Yes
S7 communication, as client	Yes
User data per job, max.	See online help (S7 communication, user data size)
Open IE communication	
• TCP/IP	Yes
— Data length, max.	64 kbyte
 several passive connections per port, supported 	Yes
• ISO-on-TCP (RFC1006)	Yes
— Data length, max.	64 kbyte
• UDP	Yes
— Data length, max.	2 kbyte; 1 472 bytes for UDP broadcast
— UDP multicast	Yes; Max. 5 multicast circuits
• DHCP	No
• SNMP	Yes
• DCP	Yes
• LLDP	Yes
Web server	
• HTTP	Yes; Standard and user pages
• HTTPS	Yes; Standard and user pages
OPC UA	
 Runtime license required 	Yes
OPC UA Server	Yes; Data access (read, write, subscribe), method call, custom address space
 Application authentication 	Yes
— Security policies	Available security policies: None, Basic128Rsa15, Basic256Rsa15, Basic256Sha256
— User authentication	"anonymous" or by user name & password
Number of sessions, max.	32
 Number of accessible variables, max. 	50 000
 Number of registerable nodes, max. 	10 000
 Subscriptions per session, max. 	20
— Sampling time, min.	100 ms
— Send time, min.	500 ms
 Number of server methods, max. 	20
 Number of inputs/outputs per server method, max. 	20
— Number of monitored items, max.	1 000; For 1 s sampling interval and 1 s send interval
 Number of server interfaces, max. 	10
 Number of nodes for user-defined server interfaces, max. 	1 000

Further protocols	
• MODBUS	Yes; MODBUS TCP
Media redundancy	
Switchover time on line break, typ.	200 ms; For MRP, bumpless for MRPD
Number of stations in the ring, max.	50
Tambor or otations in the imig, man	
Isochronous mode	
Isochronous operation (application synchronized up	Yes; With minimum OB 6x cycle of 625 µs
to terminal)	Yes
Equidistance	res
S7 message functions	
Number of login stations for message functions, max.	32
Program alarms	Yes
Number of configurable program alarms	5 000
Number of simultaneously active program alarms	
Number of program alarms	300
 Number of alarms for system diagnostics 	100
 Number of alarms for motion technology 	80
objects	
Test commissioning functions	
Joint commission (Team Engineering)	Yes; Parallel online access possible for up to 5 engineering
	systems
Status block	Yes; Up to 8 simultaneously (in total across all ES clients)
Single step	No
Number of breakpoints	8
Status/control	
Status/control variable	Yes
Variables	Inputs/outputs, memory bits, DBs, distributed I/Os, timers,
	counters
Number of variables, max.	
— of which status variables, max.	200; per job
— of which control variables, max.	200; per job
Forcing	
 Forcing, variables 	Peripheral inputs/outputs
Number of variables, max.	200
Diagnostic buffer	
• present	Yes
Number of entries, max.	1 000
of which powerfail-proof	500
Traces	
Number of configurable Traces	4; Up to 512 KB of data per trace are possible
Interrupts/diagnostics/status information	

Alarms	
Diagnostic alarm	Yes
Hardware interrupt	Yes
Diagnostic messages	
Monitoring the supply voltage	Yes
Wire-break	Yes; for analog inputs/outputs, see description in manual
Short-circuit	Yes; for analog outputs, see description in manual
A/B transition error at incremental encoder	Yes
Diagnostics indication LED	
RUN/STOP LED	Yes
• ERROR LED	Yes
MAINT LED	Yes
STOP ACTIVE LED	Yes
Monitoring of the supply voltage (PWR-LED)	Yes
Channel status display	Yes
• for channel diagnostics	Yes; For analog inputs/outputs
 Connection display LINK TX/RX 	Yes
Supported technology objects	Vac. Note: The grapher of eace effects the grale time of the DLC

Supported technology objects	
Motion Control	Yes; Note: The number of axes affects the cycle time of the PLC
	program; selection guide via the TIA Selection Tool or SIZER
 Number of available Motion Control resources 	800
for technology objects (except cam disks)	
 Required Motion Control resources 	
per speed-controlled axis	40
— per positioning axis	80
— per synchronous axis	160
— per external encoder	80
— per output cam	20
— per cam track	160
— per probe	40
 Positioning axis 	
 Number of positioning axes at motion 	5
control cycle of 4 ms (typical value)	
 Number of positioning axes at motion 	10
control cycle of 8 ms (typical value)	
Controller	
PID_Compact	Yes; Universal PID controller with integrated optimization
• PID_3Step	Yes; PID controller with integrated optimization for valves
• PID-Temp	Yes; PID controller with integrated optimization for temperature
Counting and measuring	
High-speed counter	Yes

Number of sounters 6 Counting frequency (counter) max. 400 kHz; with quadruple evaluation Counting frequency (counter) max. 400 kHz; with quadruple evaluation Counting functions Yes Counter response parameterizable Yes Hardware gate via digital input Yes Software gate Event-controlled stop Yes Synchronization via digital input Yes Counting range, parameterizable Yes Comparator Number of comparators 2; per count channel; see manual for details Yes Direction dependency Yes Suitable for \$37-1500 Motion Control Yes Measuring functions Yes Measuring functions Yes Measuring time, parameterizable Yes Dynamic measurement period adjustment Yes Number of thresholds, parameterizable 2 Measuring range Frequency measurement, min. 2.5 µs Cycle duration measurement, max. 400 kHz; with quadruple evaluation Frequency measurement 100 ppm; depending on measuring interval and signal evaluation Cycle duration measurement 100 ppm; depending on measuring interval and signal evaluation Doppm; depending on measuring interval and sig	Integrated Functions	
Continuous counting Counter response parameterizable Counter response parameterizable Counter response parameterizable Counter response parameterizable Controlled stop Software gate Counting range, parameterizable Counting range, parameterizable Comparator Number of comparators Direction dependency Can be changed from user program Can be changed from user program Suitable for SY-1500 Motion Control Possuring functions Measuring functions Measuring funce, parameterizable Dynamic measurement period adjustment Frequency measurement, min. Frequency measurement, min. Frequency measurement, min. Cycle duration measurement, max. Accuracy Frequency measurement Cycle duration measurement Cycle	Number of counters	6
Continuous counting Counter response parameterizable Hardware gate via digital input Software gate Software gate Comparator Counting range, parameterizable Comparator Number of comparators Direction dependency Can be changed from user program Fostion detection Incremental acquisition Sulvamber of S7-1500 Motion Control Software gate Neasuring functions Measuring functions Measuring time, parameterizable Software gate Number of thresholds, parameterizable Software gate Neasuring range Prequency measurement, min. Frequency measurement, max. Cycle duration measurement, max. Cycle duration measurement, max. Cycle duration measurement C	Counting frequency (counter) max.	400 kHz; with quadruple evaluation
Counter response parameterizable Hardware gate via digital input Software gate Event-controlled stop Software gate So	Counting functions	
Hardware gate via digital input Software gate Ves Ves Ves Ves Venet-controlled stop Synchronization via digital input Counting range, parameterizable Position detection Incremental acquisition Suitable for S7-1500 Motion Control Wes Dynamic measurement period adjustment Number of thresholds, parameterizable Accuracy Frequency measurement, min. Cycle duration measurement Cycle duration measureme	Continuous counting	Yes
Software gate Event-controlled stop Synchronization via digital input Counting range, parameterizable Event-controlled stop Comparator Number of comparators Direction dependency Can be changed from user program Position detection Incremental acquisition Incremental acquisition Suitable for S7-1500 Motion Control Measuring functions Measuring time, parameterizable Dynamic measurement period adjustment Number of thresholds, parameterizable Dynamic measurement, min. Frequency measurement, min. Frequency measurement, min. Cycle duration measurement, min. Cycle duration measurement Potential separation Potential separation digital inputs Detection separation Potential separation channels Detectial separation channels Detectinal separation channels Detection sepa	 Counter response parameterizable 	Yes
Vevent-controlled stop Synchronization via digital input Counting range, parameterizable Comparator Number of comparators Direction dependency Can be changed from user program Position detection Neasuring functions Measuring functions Measuring functions Measuring range Prequency measurement, min. Frequency measurement, min. Cycle duration measurement Cycle duration measurement Velocity measurement Velocity measurement Velocity measurement No ppm; depending on measuring interval and signal evaluation Potential separation Potential separation digital outputs Determinal separation channels Determination	 Hardware gate via digital input 	Yes
Synchronization via digital input Counting range, parameterizable Comparator Number of comparators Direction dependency Can be changed from user program Position detection Incremental acquisition Suitable for S7-1500 Motion Control Wes Wessuring functions Measuring functions Measuring functions Measuring functions Measuring range Dynamic measurement period adjustment Number of thresholds, parameterizable Dynamic measurement, min. Frequency measurement, min. Frequency measurement, min. Cycle duration measurement, min. Cycle duration measurement, max. Dycle duration measurement Cycle duration measurement Dypm; depending on measuring interval and signal evaluation Velocity measurement Velocity measurement Do ppm; depending on measuring interval and signal evaluation Velocity measurement Do ppm; depending on measuring interval and signal evaluation Velocity measurement Velocity measurement Do ppm; depending on measuring interval and signal evaluation Velocity measurement Do ppm; depending on measuring interval and signal evaluation Velocity measurement Do ppm; depending on measuring interval and signal evaluation Velocity measurement Do ppm; depending on measuring interval and signal evaluation Velocity measurement Do ppm; depending on measuring interval and signal evaluation No Detential separation digital inputs Detween the channels, in groups of Detential separation digital outputs Detween the channels, in groups of Detential separation channels Detween the channels, in groups of Detential separation channels Detween the channels and backplane bus	Software gate	Yes
• Counting range, parameterizable Comparator - Number of comparators - Direction dependency - Can be changed from user program • Incremental acquisition • Incremental acquisition • Suitable for 57-1500 Motion Control Measuring functions • Measuring time, parameterizable • Dynamic measurement period adjustment • Number of thresholds, parameterizable • Dynamic measurement, min Frequency measurement, min Frequency measurement, min Cycle duration measurement, max Cycle duration measurement - Cycle duration measurement - Cycle duration measurement - Velocity measurement - Velocit	 Event-controlled stop 	Yes
Comparator - Number of comparators - Direction dependency - Can be changed from user program Position detection • Incremental acquisition • Suitable for S7-1500 Motion Control Measuring functions • Measuring functions • Measuring time, parameterizable • Dynamic measurement period adjustment • Number of thresholds, parameterizable 2 Measuring range - Frequency measurement, min Frequency measurement, min Cycle duration measurement, min Cycle duration measurement, max. 25 s Accuracy - Frequency measurement - Cycle duration measurement - Cycle duration measurement - Velocity m	 Synchronization via digital input 	Yes
- Number of comparators - Direction dependency - Can be changed from user program Position detection Incremental acquisition Suitable for S7-1500 Motion Control Measuring functions Measuring time, parameterizable Dynamic measurement period adjustment Number of thresholds, parameterizable Neasuring range Frequency measurement, min. Frequency measurement, min. Cycle duration measurement, min. Cycle duration measurement, max. Cycle duration measurement Dynamic measurement Dynamic measurement, min. Frequency measurement, min. Cycle duration measurement, min. Cycle duration measurement, min. Cycle duration measurement Dynamic depending on measuring interval and signal evaluation Dynamic depending on measurement Dynamic dep	Counting range, parameterizable	Yes
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Position detection Incremental acquisition Suitable for S7-1500 Motion Control Measuring functions Measuring time, parameterizable Dynamic measurement period adjustment Number of thresholds, parameterizable Prequency measurement, min. Frequency measurement, min. Cycle duration measurement, min. Cycle duration measurement, min. Cycle duration measurement, max. Cycle duration measurement, max. Dynamic measurement Dynamic measurement, min. Frequency measurement, min. Cycle duration measurement, min. Cycle duration measurement, min. Cycle duration measurement Dynamic measurement Cycle duration measurement Dynamic measur	 Direction dependency 	Yes
Position detection Incremental acquisition Suitable for S7-1500 Motion Control Measuring functions Measuring time, parameterizable Dynamic measurement period adjustment Number of thresholds, parameterizable Prequency measurement, min. Frequency measurement, min. Cycle duration measurement, min. Cycle duration measurement, min. Cycle duration measurement, min. Cycle duration measurement, min. Dynamic measurement in the saurement in the saurem	— Can be changed from user program	Yes
• Suitable for \$7-1500 Motion Control Measuring functions • Measuring time, parameterizable • Dynamic measurement period adjustment • Number of thresholds, parameterizable 2 Measuring range — Frequency measurement, min. — Frequency measurement, max. — Cycle duration measurement, min. — Cycle duration measurement, max. — Cycle duration measurement, max. — Cycle duration measurement — Cycle duration measurement — Cycle duration measurement — Cycle duration measurement — Use of the surface of th	Position detection	
Measuring functions • Measuring time, parameterizable • Dynamic measurement period adjustment • Number of thresholds, parameterizable 2 Measuring range — Frequency measurement, min. — Frequency measurement, min. — Cycle duration measurement, min. — Cycle duration measurement, max. 2.5 μs — Cycle duration measurement, max. 2.5 s Accuracy — Frequency measurement — Cycle duration measurement — Cycle duration measurement — 100 ppm; depending on measuring interval and signal evaluation — Velocity measurement — 100 ppm; depending on measuring interval and signal evaluation Potential separation Potential separation Potential separation digital inputs • between the channels • between the channels, in groups of Potential separation digital outputs • between the channels • between the channels, in groups of Potential separation channels • between the channels, in groups of Potential separation channels • between the channels in groups of Potential separation channels • between the channels in groups of Potential separation channels • between the channels and backplane bus Yes	Incremental acquisition	Yes
Measuring time, parameterizable Dynamic measurement period adjustment Number of thresholds, parameterizable Neasuring range — Frequency measurement, min. — Frequency measurement, max. — Oycle duration measurement, min. — Cycle duration measurement, min. — Cycle duration measurement, max. — Cycle duration measurement — Cycle duration measurement — Cycle duration measurement — Cycle duration measurement — Oycle duration measurement — Oycle duration measurement — 100 ppm; depending on measuring interval and signal evaluation — Velocity measurement — Velocity measurement — 100 ppm; depending on measuring interval and signal evaluation Potential separation Potential separation digital inputs • between the channels • between the channels • between the channels, in groups of 16 Potential separation digital outputs • between the channels, in groups of 16 Potential separation channels • between the channels • between the channels and backplane bus Yes	 Suitable for S7-1500 Motion Control 	Yes
Dynamic measurement period adjustment Number of thresholds, parameterizable Measuring range — Frequency measurement, min. — Frequency measurement, max. — Cycle duration measurement, min. — Cycle duration measurement, min. — Cycle duration measurement, max. — Cycle duration measurement, max. — Cycle duration measurement, max. — Cycle duration measurement — Cycle duration measurement — Cycle duration measurement — Cycle duration measurement — Velocity measurement — Oppm; depending on measuring interval and signal evaluation Potential separation Potential separation digital inputs • between the channels • between the channels, in groups of Potential separation digital outputs • between the channels, in groups of Potential separation channels • between the channels, in groups of Potential separation channels • between the channels in groups of Potential separation channels • between the channels and backplane bus Yes	Measuring functions	
 Number of thresholds, parameterizable Measuring range — Frequency measurement, min. — Frequency measurement, max. — Cycle duration measurement, min. — Cycle duration measurement, min. — Cycle duration measurement, max. — Cycle duration measurement, max. — Erequency measurement — Cycle duration measurement — Cycle duration measurement — Cycle duration measurement — Velocity measurement — No — Velocity measurement — No — Velocity measurement — Velocity measurement — No — Velocity measurement — No — Velocity measurement — Velocity measurement — No — Velocity measurement — Velocity measurement — No — Velocity measurement <li< td=""><td>Measuring time, parameterizable</td><td>Yes</td></li<>	Measuring time, parameterizable	Yes
Measuring range — Frequency measurement, min. — Frequency measurement, max. — Cycle duration measurement, min. — Cycle duration measurement, min. — Cycle duration measurement, max. — Cycle duration measurement, max. Accuracy — Frequency measurement — Cycle duration measurement — Cycle duration measurement — Upopm; depending on measuring interval and signal evaluation — Velocity measurement — Velocity measure	 Dynamic measurement period adjustment 	Yes
- Frequency measurement, min Frequency measurement, max Cycle duration measurement, min Cycle duration measurement, min Cycle duration measurement, max. - Cycle duration measurement, max. - Cycle duration measurement, max. - Frequency measurement - Cycle duration measurement - Cycle duration measurement - Cycle duration measurement - Velocity measuring interval and signal evaluation - Velocity measurement - Velocity	 Number of thresholds, parameterizable 	2
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- Cycle duration measurement, min Cycle duration measurement, max. 25 s Accuracy - Frequency measurement - Cycle duration measurement - Cycle duration measurement - Cycle duration measurement - Velocity measurement - Velocity measurement - Velocity measurement - Velocity measurement - Oyenettial separation Potential separation Potential separation digital inputs • between the channels, in groups of - Detential separation digital outputs • between the channels • between the channels, in groups of - Oyenettial separation digital outputs • between the channels • between the channels, in groups of - Oyenettial separation channels • between the channels in groups of - Oyenettial separation channels • between the channels and backplane bus • between the channels and backplane bus • Ves	— Frequency measurement, min.	0.04 Hz
Accuracy - Frequency measurement - Cycle duration measurement - Cycle duration measurement - Velocity measurement - Velocity measurement - Obtential separation Potential separation digital inputs • between the channels, in groups of - between the channels • between the channels • between the channels • between the channels • between the channels, in groups of - between the channels and backplane bus - between the channels and backplane bus - between the channels and backplane bus - State of the product of the p	— Frequency measurement, max.	400 kHz; with quadruple evaluation
Accuracy — Frequency measurement — Cycle duration measurement — Velocity measurement — Velocity measurement — Velocity measurement — Oppm; depending on measuring interval and signal evaluation 100 ppm; depending on measuring interval and signal evaluation 100 ppm; depending on measuring interval and signal evaluation Potential separation Potential separation digital inputs • between the channels • between the channels, in groups of 16 Potential separation digital outputs • between the channels • between the channels, in groups of 16 Potential separation channels • between the channels and backplane bus Yes	 Cycle duration measurement, min. 	2.5 μs
- Frequency measurement - Cycle duration measurement - Velocity measuring interval and signal evaluation - Velocity measurement - Velocity measuring interval and signal evaluation - Velocity me	 Cycle duration measurement, max. 	25 s
- Cycle duration measurement - Velocity measu	Accuracy	
— Velocity measurement 100 ppm; depending on measuring interval and signal evaluation Potential separation Potential separation digital inputs • between the channels • between the channels, in groups of Potential separation digital outputs • between the channels • between the channels, in groups of Potential separation channels • between the channels • between the channels • between the channels • between the channels and backplane bus Yes	— Frequency measurement	100 ppm; depending on measuring interval and signal evaluation
Potential separation Potential separation digital inputs • between the channels • between the channels, in groups of Potential separation digital outputs • between the channels • between the channels • between the channels, in groups of Potential separation channels • between the channels • between the channels and backplane bus Yes	 Cycle duration measurement 	100 ppm; depending on measuring interval and signal evaluation
Potential separation digital inputs • between the channels • between the channels, in groups of • between the channels, in groups of Potential separation digital outputs • between the channels • between the channels, in groups of Potential separation channels • between the channels and backplane bus Yes	 Velocity measurement 	100 ppm; depending on measuring interval and signal evaluation
Potential separation digital inputs • between the channels • between the channels, in groups of • between the channels, in groups of Potential separation digital outputs • between the channels • between the channels, in groups of Potential separation channels • between the channels and backplane bus Yes	Potential senaration	
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Potential separation digital outputs • between the channels • between the channels, in groups of Potential separation channels • between the channels and backplane bus Yes		No
Potential separation digital outputs • between the channels • between the channels, in groups of Potential separation channels • between the channels and backplane bus Yes	 between the channels, in groups of 	16
 between the channels between the channels, in groups of Potential separation channels between the channels and backplane bus Yes 		
 between the channels, in groups of Potential separation channels between the channels and backplane bus Yes 		No
Potential separation channels ● between the channels and backplane bus Yes		16
Between the channels and load voltage L+ No	between the channels and backplane bus	Yes
	Between the channels and load voltage L+	No

Jaclatian	
Isolation Isolation tested with	707 V DC (type test)
ionalion toolog man	To. V Do (type toot)
Ambient conditions	
Ambient temperature during operation	
 horizontal installation, min. 	0 °C
 horizontal installation, max. 	60 °C; Note derating data for onboard I/O in the manual. Display: 50 °C, at an operating temperature of typically 50 °C, the display is switched off
vertical installation, min.	0 °C
 vertical installation, max. 	40 °C; Note derating data for onboard I/O in the manual. Display: 40 °C, at an operating temperature of typically 40 °C, the display is switched off
Ambient temperature during storage/transportation	
• min.	-40 °C
• max.	70 °C
Configuration	
Programming	
Programming language	
— LAD	Yes
— FBD	Yes
— STL	Yes
— SCL	Yes
— GRAPH	Yes
Know-how protection	
User program protection/password protection	Yes
 Copy protection 	Yes
Block protection	Yes
Access protection	
Password for display	Yes
 Protection level: Write protection 	Yes
 Protection level: Read/write protection 	Yes
Protection level: Complete protection	Yes
Cycle time monitoring	
• lower limit	adjustable minimum cycle time
• upper limit	adjustable maximum cycle time
Dimensions	
Width	110 mm
Height	147 mm
Depth	129 mm
Weights	
Weight, approx.	1 360 g
- · · ·	

last modified: 07/17/2018