

### **MLFB-Ordering data**

6SL3210-1KE31-1AF1



Client order no. : Order no. : Offer no. :

Item no.: Consignment no. : Project :

Remarks :		Project :	
Rated data		General tech. specifications	
Input		Power factor λ	0.90 0.95
Number of phases	3 AC	Offset factor cos φ	0.99
Line voltage	380 480 V +10 % -20 %	Efficiency η	0.98
Line frequency	47 63 Hz	Sound pressure level (1m)	71 dB
Rated current (LO)	96.00 A	Power loss	1.55 kW
Rated current (HO)	85.00 A	Filter class (integrated)	Class A
Output		Ambia	nt conditions
Number of phases	3 AC	Ambie	nt conditions
Rated voltage	400 V	Cooling	Air cooling using an integrated fan
Rated power IEC 400V (LO)	55.00 kW	Cooling air requirement	0.083 m³/s (2.931 ft³/s)
Rated power NEC 480V (LO)	60.00 hp	Installation altitude	
Rated power IEC 400V (HO)	45.00 kW		1000 m (3280.84 ft)
Rated power NEC 480V (HO)	50.00 hp	Ambient temperature	
Rated current (LO)	103.00 A	Operation	-20 40 °C (-4 104 °F)
Rated current (HO)	83.00 A	Transport	-40 70 °C (-40 158 °F)
Rated current (IN)	103.00 A	Storage	-40 70 °C (-40 158 °F)
Max. output current	165.00 A	Relative humidity	
Pulse frequency	4 kHz	Max. operation	95 % RH, condensation not permitted
Output frequency for vector control	0 240 Hz	Closed-loop control techniques	
Output frequency for V/f control	0 550 Hz	V/f linear / square-law / parame	
		vii iiileai / square iaw / paraiik	ics
		V/f with flux current control (F	CC) Yes
Overload capability		V/f ECO linear / square-law	Yes
Low Overload (LO)		Sensorless vector control	Yes
150 % base load current IL for 3 s, followed by 110 % base load current IL for 57 s in a 300 s cycle time		Vector control, with sensor	No
		Encoderless torque control	No

200 % base load current IH for 3 s, followed by 150 % base load current IH for 57 s in a

High Overload (HO)

300 s cycle time

No

Torque control, with encoder



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			Figure :
Mechanical data		Com	munication
Degree of protection	IP20 / UL open type	Communication	PROFINET, EtherNet/IP
Size	FSE	Connections	
Net weight	28.50 kg (62.83 lb)	Signal cable	
Width	275 mm (10.83 in)	Conductor cross-section	0.15 1.50 mm² (AWG 24 AWG 10
Height	551 mm (21.69 in)	Line side	
Depth	237 mm (9.33 in)	Version	screw-type terminal
Inputs / outputs		Conductor cross-section	25.00 70.00 mm² (AWG 4 AWG
tandard digital inputs		Motor end	
Number	6	Version	Screw-type terminals
Switching level: 0→1	11 V	Conductor cross-section	25.00 70.00 mm² (AWG 4 AWG
Switching level: 1→0	5 V	DC link (for braking resistor)	)
Max. inrush current	15 mA	Version	Screw-type terminals
ail-safe digital inputs		Conductor cross-section	25.00 70.00 mm² (AWG 4 AWG
Number	1	Line length, max.	10 m (32.81 ft)
igital outputs		PE connection	
Number as relay changeover contact	1	Max. motor cable length	Screw-type terminals
Output (resistive load)	DC 30 V, 0.5 A	Shielded	200 m (656.17 ft)
Number as transistor	1	Unshielded	300 m (984.25 ft)
Output (resistive load)	DC 30 V, 0.5 A	S	tandards
nalog / digital inputs		Compliance with standards	UL, cUL, CE, C-Tick (RCM)
Number	1 (Differential input)		, , , , ,
Resolution	10 bit	CE marking	EMC Directive 2004/108/EC, Low-Volt Directive 2006/95/EC
witching threshold as digital in	put		
0→1	4 V		
1→0	1.6 V		
nalog outputs			
Number	1 (Non-isolated output)		
	. (		

### PTC/ KTY interface

1 motor temperature sensor input, sensors that can be connected: PTC, KTY and Thermo-Click, accuracy  $\pm 5~^\circ\text{C}$ 



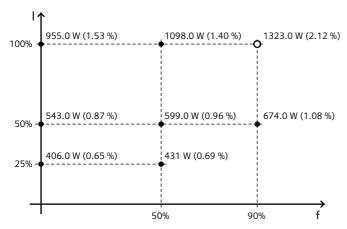
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## Converter losses to EN 50598-2\*

Efficiency class	IE2
Comparison with the reference converter (90% / 100%)	-55.37 %



The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard EN 50598) of the relative torque generating current (I) over the relative motor stator frequency(f). The values are valid for the basic version of the converter without options/components.

\*converted values