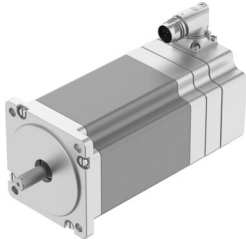


Stepper motor EMMT-ST-87-L-RMB

Part number: 8156202

FESTO



 [General operating condition](#)

Data sheet

Feature	Value
Ambient temperature	-15 °C ... 40 °C
Note on ambient temperature	up to 80°C with derating -2%/°C
Max. installation height	4000 m
Information on max. installation height	with 1,000 m and longer only with derating of -1.0% per 100 m
Storage temperature	-20 °C ... 70 °C
Relative air humidity	0 - 90 % Non-condensing
Conforms to standard	IEC 60034
Thermal class according to EN 60034-1	B
Max. winding temperature	130 °C
Rating class according to EN 60034-1	S1
Temperature monitoring	Dig. motor temp. via BiSS-C
Motor type as per EN 60034-7	IM B5 IM V1 IM V3
Mounting position	Any
Degree of protection	IP40
Note on degree of protection	IP40 for motor shaft without rotary shaft seal IP65 for motor housing, incl. connection technology
Interface code, motor out	87A
Electrical connection 1, connection type	Hybrid plug
Electrical connection 1, connection technology	M17x0.75
Electrical connection 1, number of pins/wires	12
Electrical connection for input 1, connection pattern	00997532
Note on materials	RoHS-compliant
Corrosion resistance class (CRC)	0 - No corrosion stress
LABS (PWIS) conformity	VDMA24364 zone III
Vibration resistance	Transport application test with severity level 2 as per FN 942017-4 and EN 60068-2-6
Shock resistance	Shock test with severity level 2 as per FN 942017-5 and EN 60068-2-27
Certification	RCM compliance mark c UL us - Recognized (OL)
CE marking (see declaration of conformity)	As per EU EMC directive As per EU RoHS directive
UKCA marking (see declaration of conformity)	To UK instructions for EMC To UK RoHS instructions
Certificate issuing authority	UL E342973
Nominal operating voltage DC	48 V

Feature	Value
Number of pole pairs	50
Motor holding torque	9.4 Nm
Nominal torque	8.4 Nm
Peak torque	9.4 Nm
Nominal rotary speed	140 rpm
Max. rotational speed	430 rpm
Max. mechanical speed	7000 rpm
Step angle with full step	1.8 deg
Step angle tolerance	±5%
Motor nominal power	126 W
Continuous stall current	10 A
Motor nominal current	8.4 A
Peak current	10 A
Motor constants	1.06 Nm/A
Voltage constant, phase	78.9 mVmin
Phase winding resistance	0.3 Ohm
Winding inductance phase	2.7 mH
Winding longitudinal inductivity Ld (phase)	4.1 mH
Cross inductivity Lq (phase)	2.7 mH
Electric time constant	9 ms
Thermal time constant	37 min
Thermal resistance	0.75 K/W
Measuring flange	250 x 250 x 15 mm, steel
Total output inertia moment	3.116 kgcm ²
Product weight	5490 g
Permissible axial shaft load	60 N
Permissible radial shaft load	220 N
Rotor position sensor	Absolute encoder, multi-turn
Rotor position sensor for manufacturer designation	KCD-BC33B-1617-U09C-JAQ-009
Rotor position encoder for absolutely detectable revolutions	65536
Rotor position sensor interface	BiSS-C
Rotor position sensor measuring principle	Magnetic
Rotor position encoder for DC operating voltage	14 V
Rotor position encoder for DC operating voltage range	4.75 V ... 15 V
Rotor position encoder, sinusoidal/cosinusoidal periods per revolution	2
Rotor position encoder for positional values per revolution	131072
Rotor position sensor resolution	17 bit
Rotor position encoder system accuracy angle measurement	-310 arcsec ... 310 arcsec
Brake holding torque	4.26 Nm
Brake DC operating voltage	24 V
Brake current consumption	0.49 A
Brake power consumption	12 W
Brake coil resistance	49.2 Ohm
Brake coil inductivity	110 mH
Brake separation time	≤44 ms
Brake closing time	≤110 ms
DC brake response delay	≤30 ms
Max. brake no-load speed	7000 rpm
Max. brake friction work	14000 J
Number of emergency stops per hour	1
Brake mass moment of inertia	0.11 kgcm ²
Switching cycles, holding brake	10 million idle actuations (without friction work!)
MTTF, subcomponent	20 years, rotor position encoder