Servo motor EMMT-AS-60-L-HS-RMYB Part number: 8160641

FESTO



General operating condition

Data sheet

| Feature | Value |
|---|--|
| Ambient temperature | -40 °C 40 °C |
| Note on ambient temperature | Up to 80 ℃ with derating of -1.5% per degree Celsius |
| Max. installation height | 4000 m |
| Information on max. installation height | with 1,000 m and longer only with derating of -1.0% per 100 m |
| Storage temperature | -40 °C 70 °C |
| Relative air humidity | 0 - 90 % |
| Conforms to standard | IEC 60034 |
| Thermal class according to EN 60034-1 | F |
| Max. winding temperature | 155 ℃ |
| Rating class according to EN 60034-1 | S1 |
| Temperature monitoring | Digital motor temperature transmission via EnDat® 2.2 |
| Motor type as per EN 60034-7 | IM B5 IM V1 IM V3 |
| Mounting position | Any |
| Degree of protection | IP40 |
| Note on degree of protection | IP40 for motor shaft without rotary shaft seal IP65 for motor shaft with rotary shaft seal IP67 for motor housing, incl. connection technology |
| Concentricity, coaxiality, axial runout according to DIN SPEC 42955 | N |
| Balancing quality | G 2.5 |
| Detent torque | <1.0% of peak torque |
| Bearing lifetime, under nominal conditions | 20000 h |
| Interface code, motor out | 60P |
| Electrical connection 1, connection type | Hybrid plug |
| Electrical connection 1, connection technology | M23x1 |
| Electrical connection 1, number of pins/wires | 15 |
| Electrical connection for input 1, connection pattern | 00995913 |
| Contamination level | 2 |
| Note on materials | RoHS-compliant |
| Corrosion resistance class (CRC) | 0 - No corrosion stress |
| LABS (PWIS) conformity | VDMA24364 zone III |
| Vibration resistance | Transport application test with severity level 2 as per FN 942017-4 and EN 60068-2-6 |
| Shock resistance | Shock test with severity level 2 as per FN 942017-5 and EN 60068-2-27 |
| Certification | RCM compliance mark German Technical Control Board (TÜV) c UL us - Recognized (OL) |

| Feature | Value |
|--|--|
| CE marking (see declaration of conformity) | As per EU EMC directive As per EU low voltage directive As per EU RoHS directive |
| UKCA marking (see declaration of conformity) | To UK instructions for EMC To UK RoHS instructions To UK instructions for electrical equipment |
| Certificate issuing authority | TÜV 968/INS 464.00/24 UL E342973 |
| Nominal operating voltage DC | 680 V |
| Type of winding switch | Star inside |
| Number of pole pairs | 5 |
| Stall torque | 1.56 Nm |
| Nominal torque | 1.3 Nm |
| Peak torque | 5.6 Nm |
| Nominal rotary speed | 3000 rpm |
| Max. rotational speed | 14300 rpm |
| Max. mechanical speed | 16000 rpm |
| Angular acceleration | ≤100000 rad/s² |
| Motor nominal power | 410 W |
| Continuous stall current | 3.5 A |
| Motor nominal current | 3 A |
| Peak current | 18.3 A |
| Motor constants | 0.44 Nm/A |
| Standstill torque constant | 0.52 Nm/A |
| Voltage constant, phase-to-phase | 31.2 mVmin |
| Phase-phase winding resistance | 2.68 Ohm |
| Winding inductance phase-phase | 12 mH |
| Winding longitudinal inductivity Ld (phase) | 5 mH |
| Cross inductivity Lq (phase) | 6 mH |
| Electric time constant | 3 ms |
| Thermal time constant | 44 min |
| Thermal resistance | 1.2 K/W |
| Measuring flange | 250 x 250 x 15 mm, steel |
| Total output inertia moment | 0.49 kgcm ² |
| Product weight | 2230 g |
| Permissible axial shaft load | 70 N |
| Permissible radial shaft load | 350 N |
| Rotor position sensor | Safety encoder, absolute multi-turn |
| Rotor position sensor for manufacturer designation | EQI 1131 |
| Rotor position encoder for absolutely detectable revolutions | 4096 |
| Rotor position sensor interface | EnDat® 22 |
| Rotor position sensor measuring principle | Inductive |
| Rotor position scrisor incusums principle Rotor position encoder for DC operating voltage | 5 V |
| Rotor position encoder for DC operating voltage Rotor position encoder for DC operating voltage range | 3.6 V 14 V |
| Rotor position encoder for positional values per revolution | 524288 |
| Rotor position encoder for positional values per revolution | 19 bit |
| Rotor position sensor resolution Rotor position encoder system accuracy angle measurement | -120 arcsec 120 arcsec |
| Brake holding torque | 2.5 Nm |
| Brake DC operating voltage | 24 V |
| Brake current consumption | 0.46 A |
| · | |
| Brake power consumption | 11 W |
| Brake coil resistance | 52.4 Ohm |
| Brake coil inductivity | 700 mH |
| Brake separation time | ≤35 ms |

| Feature | Value |
|--|---|
| Brake closing time | 10 ms |
| DC brake response delay | ≤2 ms |
| Max. brake no-load speed | 10000 rpm |
| Max. brake friction work | 5600 J |
| Number of emergency stops per hour | 1 |
| Total brake friction work | 615 kJ |
| Brake mass moment of inertia | 0.074 kgcm² |
| Switching cycles, holding brake | 10 million idle actuations (without friction work!) |
| Safety device | Safety device |
| Maximum SIL | Security integrity level 3 See user documentation |
| Safety sub-functions up to SIL2 | Reliable acquisition and transmission of single-turn position data |
| Safety sub-functions up to SIL3 | Reliable recording and transmission of single-turn position data, only with additional software function in the servo drive |
| Maximum PL and category | Performance level e, category 3 See user documentation |
| Safety sub-function up to PL d, Cat. 3 | Reliable acquisition and transmission of single-turn position data |
| Safety sub-function up to PL e, Cat. 3 | Reliable recording and transmission of single-turn position data, only with additional software function in the servo drive |
| PFHd, subcomponent | 15 x 10E-9, encoder |
| Duration of use Tm, subcomponent | 20 years, rotor position sensor |