

ATV31H075N4T

variable speed drive ATV31 - 0.75kW - 500V 3-phase supply - EMC filter - IP20

Main

Range of product	Altivar
Product or component type	Variable speed drive
Product specific application	Simple machine Wire guiding
Component name	ATV31
Assembly style	With heat sink
EMC filter	Integrated
[Us] rated supply voltage	380...500 V - 5...5 %
Supply frequency	50...60 Hz - 5...5 %
Network number of phases	3 phases
Motor power kW	0.75 kW 4 kHz
Motor power hp	1 hp 4 kHz
Line current	2.7 A 500 V 3.6 A 380 V 1 kA
Apparent power	2.4 kVA
Prospective line Isc	1 kA
Nominal output current	2.3 A 4 kHz
Maximum transient current	3.5 A 60 s
Power dissipation in W	41 W at nominal load
Asynchronous motor control profile	Factory set : constant torque Sensorless flux vector control with PWM type motor control signal

Complementary

Product destination	Asynchronous motors
Supply voltage limits	323...550 V
Network frequency limits	47.5...63 Hz
Speed drive output frequency	0.5...500 Hz
Nominal switching frequency	4 kHz
Switching frequency	2...16 kHz adjustable
Speed range	1...50
Transient overtorque	150...170 % of nominal motor torque
Braking torque	100 % with braking resistor continuously 150 % without braking resistor ≤ 150 % with braking resistor 60 s
Regulation loop	Frequency PI regulator
Motor slip compensation	Adjustable Automatic whatever the load Suppressable
Output voltage	≤ power supply voltage
Electrical connection	Terminal 2.5 mm ² AWG 14 AI1, AI2, AI3, AOV, AOC, R1A, R1B, R1C, R2A, R2B, LI1...LI6 Terminal 2.5 mm ² AWG 14 L1, L2, L3, U, V, W, PA, PB, PA+, PC/-
Tightening torque	0.6 N.m AI1, AI2, AI3, AOV, AOC, R1A, R1B, R1C, R2A, R2B, LI1...LI6 0.8 N.m L1, L2, L3, U, V, W, PA, PB, PA+, PC/-
Insulation	Electrical between power and control

Supply	Internal supply for logic inputs $19...30\text{ V} \leq 100\text{ mA}$ overload and short-circuit protection Internal supply for reference potentiometer ($2.2\text{ to }10\text{ k}\Omega$) $10...10.8\text{ V} \leq 10\text{ mA}$ overload and short-circuit protection
Analogue input number	3
Analogue input type	Configurable current AI3 $0...20\text{ mA } 250\text{ }\Omega$ Configurable voltage AI1 $0...10\text{ V } 30\text{ V max } 30000\text{ }\Omega$ Configurable voltage AI2 $\pm 10\text{ V } 30\text{ V max } 30000\text{ }\Omega$
Sampling duration	4 ms LI1...LI6 discrete 8 ms AI1, AI2, AI3 analog
Response time	8 ms discrete R1A, R1B, R1C, R2A, R2B 8 ms analog AOV, AOC
Linearity error	$\pm 0.2\%$ output
Analogue output number	2
Analogue output type	Configurable current AOC $0...20\text{ mA } 800\text{ }\Omega$ 8 bits Configurable voltage AOV $0...10\text{ V } 470\text{ }\Omega$ 8 bits
Discrete input logic	Logic input not wired LI1...LI4 $< 13\text{ V}$ Negative logic (source) LI1...LI6 $> 19\text{ V}$ Positive logic (source) LI1...LI6 $< 5\text{ V } > 11\text{ V}$
Discrete output number	2
Discrete output type	Configurable relay logic R1A, R1B, R1C 1 NO + 1 NC 100000 cycles Configurable relay logic R2A, R2B NC 100000 cycles
Minimum switching current	10 mA 5 V DC R1-R2
Maximum switching current	2 A 250 V AC inductive $\cos\phi = 0.4$ 7 ms R1-R2 2 A 30 V DC inductive $\cos\phi = 0.4$ 7 ms R1-R2 5 A 250 V AC resistive $\cos\phi = 1$ 0 ms R1-R2 5 A 30 V DC resistive $\cos\phi = 1$ 0 ms R1-R2
Discrete input number	6
Discrete input type	Programmable LI1...LI6 $24\text{ V } 0...100\text{ mA PLC } 3500\text{ }\Omega$ Programmable LI1...LI6 $24\text{ V } 0...100\text{ mA PLC } 3500\text{ }\Omega$
Acceleration and deceleration ramps	S, U or customized Linear adjustable separately from 0.1 to 999.9 s
Braking to standstill	By DC injection
Protection type	Input phase breaks drive Line supply overvoltage and undervoltage safety circuits drive Line supply phase loss safety function, for three phases supply drive Motor phase breaks drive Overcurrent between output phases and earth (on power up only) drive Overheating protection drive Short-circuit between motor phases drive Thermal protection motor
Insulation resistance	$\geq 500\text{ MO}\Omega$ 500 V DC for 1 minute
Display type	1 LED red drive voltage Four 7-segment display units CANopen bus status
Time constant	5 ms for reference change
Frequency resolution	0.1...100 Hz analog input 0.1 Hz display unit
Type of connector	1 RJ45 Modbus 1 RJ45 CANopen via VW3 CANTAP2 adaptor
Physical interface	RS485 multidrop serial link Modbus RS485 multidrop serial link CANopen via VW3 CANTAP2 adaptor
Transmission frame	RTU Modbus RTU CANopen via VW3 CANTAP2 adaptor
Transmission rate	10, 20, 50, 125, 250, 500 kbps or 1 Mbps CANopen via VW3 CANTAP2 adaptor 4800, 9600 or 19200 bps Modbus
Number of addresses	1...127 CANopen via VW3 CANTAP2 adaptor 1...247 Modbus
Number of drive	31 Modbus 127 CANopen via VW3 CANTAP2 adaptor
Marking	CE
Operating position	Vertical ± 10 degree
Product weight	1.8 kg

Environment

Dielectric strength	2410 V DC between earth and power terminals 3400 V AC between control and power terminals
Electromagnetic compatibility	1.2/50 μ s - 8/20 μ s surge immunity test level 3 IEC 61000-4-5 Electrical fast transient/burst immunity test level 4 IEC 61000-4-4 Electrostatic discharge immunity test level 3 IEC 61000-4-2 Radiated radio-frequency electromagnetic field immunity test level 3 IEC 61000-4-3
Standards	EN 50178
Product certifications	C-Tick CSA N998 UL
IP degree of protection	IP20 on upper part without cover plate IP21 on connection terminals IP31 on upper part IP41 on upper part
Pollution degree	2
Protective treatment	TC
Vibration resistance	1 gn 13...150 Hz EN/IEC 60068-2-6 1.5 mm 3...13 Hz EN/IEC 60068-2-6
Shock resistance	15 gn 11 ms EN/IEC 60068-2-27
Relative humidity	5...95 % without condensation IEC 60068-2-3 5...95 % without dripping water IEC 60068-2-3
Ambient air temperature for storage	-25...70 °C
Ambient air temperature for operation	-10...50 °C without derating with protective cover on top of the drive -10...60 °C with derating factor without protective cover on top of the drive
Operating altitude	$\leq$ 1000 m without derating $\geq$ 1000 m with current derating 1 % per 100 m
RoHS EUR conformity date	2Q2009
RoHS EUR status	Will be compliant