

ATV950D22N4E

variable speed drive, ATV950, 22kW, 400/480V,
w braking unit/switch, IP55



Price* : 3,174.00 GBP



Main

Range of product	Altivar Process ATV900
Product or component type	Variable speed drive
Device application	Industrial application
Device short name	ATV950
Variant	With load break switch With braking chopper
Product destination	Asynchronous motors Synchronous motors
Mounting mode	Wall mount
EMC filter	Integrated with 50 m conforming to EN/IEC 61800-3 category C2 Integrated with 150 m conforming to EN/IEC 61800-3 category C3
IP degree of protection	IP55 conforming to IEC 61800-5-1 IP55 conforming to IEC 60529
Type of cooling	Forced convection
Supply frequency	50...60 Hz +/- 5 %
Network number of phases	3 phases
[Us] rated supply voltage	380...480 V - 15...10 %
Motor power kW	22 kW (normal duty) 18.5 kW (heavy duty)
Motor power hp	30 hp normal duty 25 hp heavy duty
Line current	39.6 A at 380 V (normal duty) 34.4 A at 480 V (normal duty) 34.1 A at 380 V (heavy duty) 29.9 A at 480 V (heavy duty)
Prospective line Isc	50 kA
Apparent power	28.6 kVA at 480 V (normal duty) 24.9 kVA at 480 V (heavy duty)
Continuous output current	46.3 A at 4 kHz for normal duty 39.2 A at 4 kHz for heavy duty

Maximum transient current	55.6 A during 60 s (normal duty) 58.8 A during 60 s (heavy duty)
Asynchronous motor control profile	Variable torque standard Constant torque standard Optimized torque mode
Synchronous motor control profile	Permanent magnet motor Synchronous reluctance motor
Speed drive output frequency	0.1...599 Hz
Nominal switching frequency	4 kHz
Switching frequency	2...16 kHz adjustable 4...16 kHz with derating factor
Safety function	STO (safe torque off) SIL 3
Number of preset speeds	16 preset speeds
Communication port protocol	Modbus serial Modbus TCP Ethernet/IP
Option module	Slot A: communication module for Profibus DP V1 Slot A: communication module for Profinet Slot A: communication module for DeviceNet Slot A: communication module for EtherCAT Slot A: communication module for CANopen daisy chain RJ45 Slot A: communication module for CANopen SUB-D 9 Slot A: communication module for CANopen screw terminals Slot A/slot B/slot C: digital and analog I/O extension module Slot A/slot B/slot C: output relay extension module Slot B: 5/12 V digital encoder interface module Slot B: analog encoder interface module Slot B: resolver encoder interface module communication module for Ethernet Powerlink

Complementary

Output voltage	<= power supply voltage
Motor slip compensation	Not available in permanent magnet motor law Adjustable Can be suppressed Automatic whatever the load
Acceleration and deceleration ramps	Linear adjustable separately from 0.01...9999 s
Braking to standstill	By DC injection
Protection type	Thermal protection: motor Safe torque off: motor Motor phase break: motor Thermal protection: drive Safe torque off: drive Overheating: drive Overcurrent between output phases and earth: drive Overload of output voltage: drive Short-circuit protection: drive Motor phase break: drive Overvoltages on the DC bus: drive Line supply overvoltage: drive Line supply undervoltage: drive Line supply phase loss: drive Overspeed: drive Break on the control circuit: drive
Frequency resolution	Display unit: 0.1 Hz Analog input: 0.012/50 Hz
Electrical connection	Control: screw terminal 0.5...1.5 mm ² Line side: screw terminal 10...16 mm ² DC bus: screw terminal 10...16 mm ² Motor: screw terminal 16 mm ²
Connector type	2 RJ45 for Ethernet IP/Modbus TCP on the control block 1 RJ45 for Modbus serial on the control block
Physical interface	2-wire RS 485 for Modbus serial
Transmission frame	RTU for Modbus serial
Transmission rate	10/100 Mbit/s for Ethernet IP/Modbus TCP

	4.8, 9.6, 19.2, 38.4 kbit/s for Modbus serial
Exchange mode	Half duplex, full duplex, autonegotiation Ethernet IP/Modbus TCP
Data format	8 bits, configurable odd, even or no parity for Modbus serial
Type of polarization	No impedance for Modbus serial
Number of addresses	1...247 for Modbus serial
Method of access	Slave Modbus TCP
Supply	External supply for digital inputs: 24 V DC (19...30 V), <1.25 mA, protection type: overload and short-circuit protection Internal supply for reference potentiometer (1 to 10 kOhm): 10.5 V DC +/- 5 %, <10 mA, protection type: overload and short-circuit protection Internal supply for digital inputs and STO: 24 V DC (21...27 V), <200 mA, protection type: overload and short-circuit protection
Local signalling	Local diagnostic: 3 LED (mono/dual colour) Embedded communication status: 5 LED (dual colour) Communication module status: 2 LED (dual colour) Presence of voltage: 1 LED (red)
Width	264 mm
Height	678 mm
Depth	330 mm
Product weight	20.6 kg
Analogue input number	3
Analogue input type	AI1, AI2, AI3 software-configurable voltage: 0...10 V DC, impedance: 30 kOhm, resolution 12 bits AI1, AI2, AI3 software-configurable current: 0...20 mA/4...20 mA, impedance: 250 Ohm, resolution 12 bits
Discrete input number	10
Discrete input type	DI1...DI8 programmable, 24 V DC (<= 30 V), impedance: 3.5 kOhm DI7, DI8 programmable as pulse input: 0...30 kHz, 24 V DC (<= 30 V) STOA, STOB safe torque off, 24 V DC (<= 30 V), impedance: > 2.2 kOhm
Input compatibility	DI1...DI8: discrete input level 1 PLC conforming to EN/IEC 61131-2 DI7, DI8: pulse input level 1 PLC conforming to IEC 65A-68 STOA, STOB: discrete input level 1 PLC conforming to EN/IEC 61131-2
Discrete input logic	Positive logic (source) (DI1...DI8), < 5 V (state 0), > 11 V (state 1) Negative logic (sink) (DI1...DI8), > 16 V (state 0), < 10 V (state 1) Positive logic (source) (DI7, DI8), < 0.6 V (state 0), > 2.5 V (state 1) Positive logic (source) (STOA, STOB), < 5 V (state 0), > 11 V (state 1)
Analogue output number	2
Analogue output type	Software-configurable voltage AQ1, AQ2: 0...10 V DC impedance 470 Ohm, resolution 10 bits Software-configurable current AQ1, AQ2: 0...20 mA impedance 500 Ohm, resolution 10 bits
Discrete output number	2
Discrete output type	Logic output DQ+ 0...1 kHz <= 30 V DC 100 mA Programmable as pulse output DQ+ 0...30 kHz <= 30 V DC 20 mA Logic output DQ- 0...1 kHz <= 30 V DC 100 mA
Sampling duration	2 ms +/- 0.5 ms (DI1...DI8) - discrete input 5 ms +/- 1 ms (DI7, DI8) - pulse input 1 ms +/- 1 ms (AI1, AI2, AI3) - analog input 5 ms +/- 1 ms (AQ1, AQ2) - analog output
Accuracy	+/- 0.6 % AI1, AI2, AI3 for a temperature variation 60 °C analog input +/- 1 % AQ1, AQ2 for a temperature variation 60 °C analog output
Linearity error	AI1, AI2, AI3: +/- 0.15 % of maximum value for analog input AQ1, AQ2: +/- 0.2 % for analog output
Maximum switching current	Relay output R1 on resistive load, cos phi = 1: 3 A at 250 V AC Relay output R1 on resistive load, cos phi = 1: 3 A at 30 V DC Relay output R1 on inductive load, cos phi = 0.4 and L/R = 7 ms: 2 A at 250 V AC Relay output R1 on inductive load, cos phi = 0.4 and L/R = 7 ms: 2 A at 30 V DC Relay output R2, R3 on resistive load, cos phi = 1: 5 A at 250 V AC Relay output R2, R3 on resistive load, cos phi = 1: 5 A at 30 V DC Relay output R2, R3 on inductive load, cos phi = 0.4 and L/R = 7 ms: 2 A at 250 V AC Relay output R2, R3 on inductive load, cos phi = 0.4 and L/R = 7 ms: 2 A at 30 V DC
Relay output number	3
Relay output type	Configurable relay logic R1: fault relay NO/NC electrical durability 100000 cycles Configurable relay logic R2: sequence relay NO electrical durability 1000000 cycles Configurable relay logic R3: sequence relay NO electrical durability 1000000 cycles
Refresh time	Relay output (R1, R2, R3): 5 ms (+/- 0.5 ms)

Minimum switching current	Relay output R1, R2, R3: 5 mA at 24 V DC
Isolation	Between power and control terminals

Environment

Insulation resistance	> 1 MOhm 500 V DC for 1 minute to earth
Noise level	53.7 dB conforming to 86/188/EEC
Vibration resistance	1.5 mm peak to peak (f= 2...13 Hz) conforming to IEC 60068-2-6 1 gn (f= 13...200 Hz) conforming to IEC 60068-2-6
Shock resistance	15 gn for 11 ms conforming to IEC 60068-2-27
Operating position	Vertical +/- 10 degree
Maximum THDI	<48 % from 80...100 % of load conforming to IEC 61000-3-12
Electromagnetic compatibility	Electrostatic discharge immunity test level 3 conforming to IEC 61000-4-2 Radiated radio-frequency electromagnetic field immunity test level 3 conforming to IEC 61000-4-3 Electrical fast transient/burst immunity test level 4 conforming to IEC 61000-4-4 1.2/50 µs - 8/20 µs surge immunity test level 3 conforming to IEC 61000-4-5 Conducted radio-frequency immunity test level 3 conforming to IEC 61000-4-6
Environmental characteristic	Chemical pollution resistance class 3C3 conforming to EN/IEC 60721-3-3 Dust pollution resistance class 3S3 conforming to EN/IEC 60721-3-3
Pollution degree	2 conforming to EN/IEC 61800-5-1
Relative humidity	5...95 % without condensation conforming to IEC 60068-2-3
Ambient air temperature for operation	-15...40 °C (without) 40...50 °C (with derating factor)
Ambient air temperature for storage	-40...70 °C
Operating altitude	<= 1000 m without 1000...4800 m with current derating 1 % per 100 m
Standards	EN/IEC 61800-3 Environment 1 category C2 EN/IEC 61800-3 Environment 2 category C3 EN/IEC 61800-3 EN/IEC 61800-5-1 IEC 61000-3-12 IEC 60721-3 IEC 61508 IEC 13849-1
Product certifications	TÜV REACH
Marking	CE

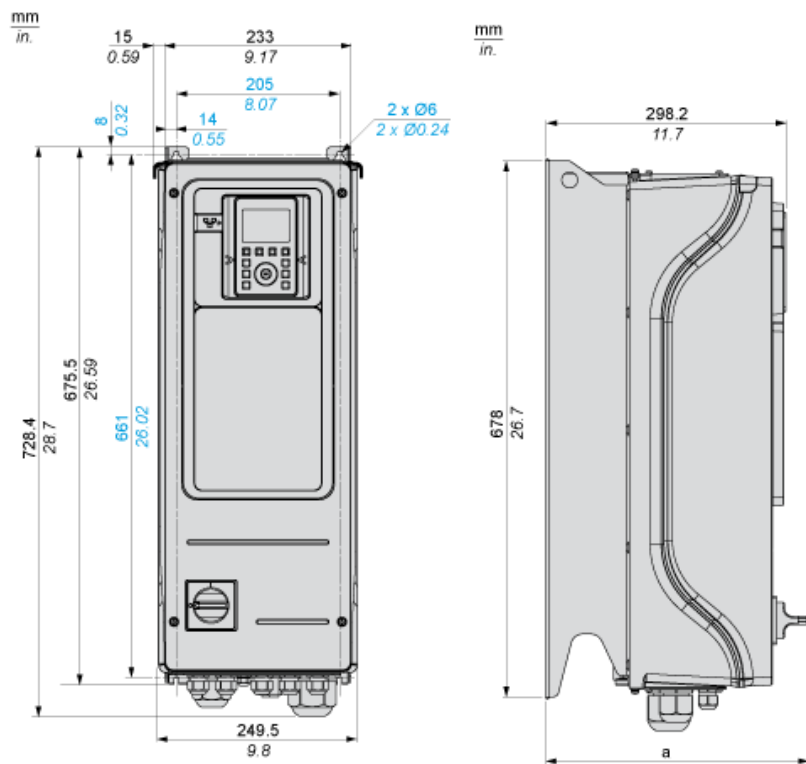
Offer Sustainability

Sustainable offer status	Green Premium product
REACH Regulation	REACH Declaration
EU RoHS Directive	Pro-active compliance (Product out of EU RoHS legal scope) EU RoHS Declaration
Mercury free	Yes
RoHS exemption information	Yes
China RoHS Regulation	China RoHS declaration
Environmental Disclosure	Product Environmental Profile
Circularity Profile	End of Life Information
WEEE	The product must be disposed on European Union markets following specific waste collection and never end up in rubbish bins

Contractual warranty

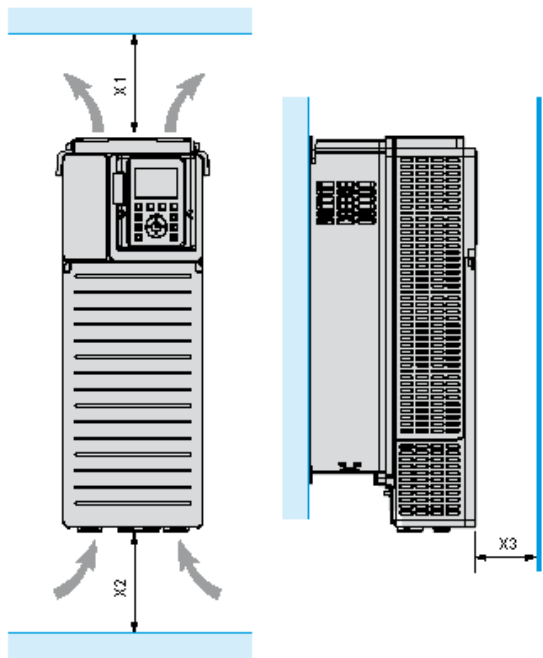
Warranty	18 months
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Front and Left View



$a = 330 \text{ mm (11.8 in.)}$

Clearances

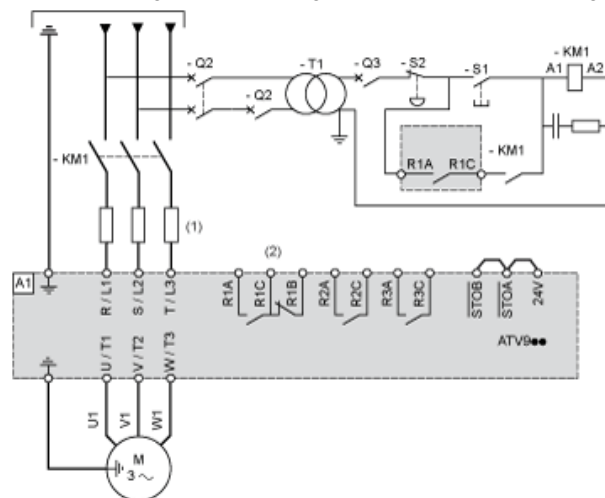


X1	X2	X3
≥ 100 mm (3.94 in.)	≥ 100 mm (3.94 in.)	≥ 10 mm (0.39 in.)

- Mount the device in a vertical position ($\pm 10^\circ$). This is required for cooling the device.
- Do not mount the device close to heat sources.
- Leave sufficient free space so that the air required for cooling purposes can circulate from the bottom to the top of the drive.

Three-Phase Power Supply with Upstream Breaking via Line Contactor

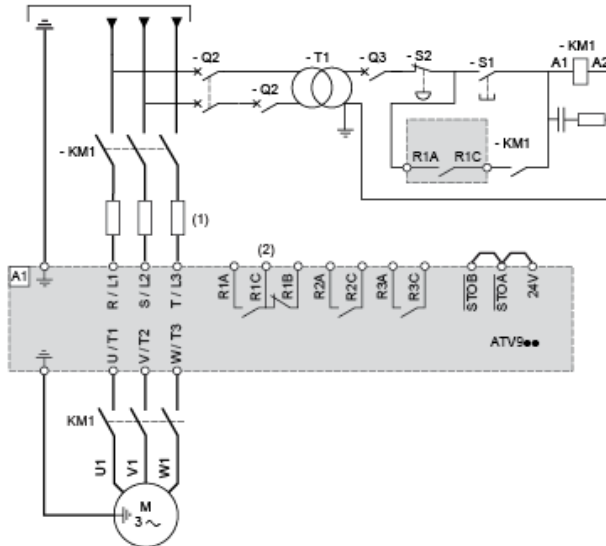
Connection diagrams conforming to standards EN 954-1 category 1 and IEC/EN 61508 capacity SIL1, stopping category 0 in accordance with standard IEC/EN 60204-1



- (1) Line choke if used
(2) Use relay R1 set to operating state Fault to switch Off the product once an error is detected.
A1 : Drive
KM1 : Line Contactor
Q2, Q3 : Circuit breakers
S1, S2 : Pushbuttons
T1 : Transformer for control part

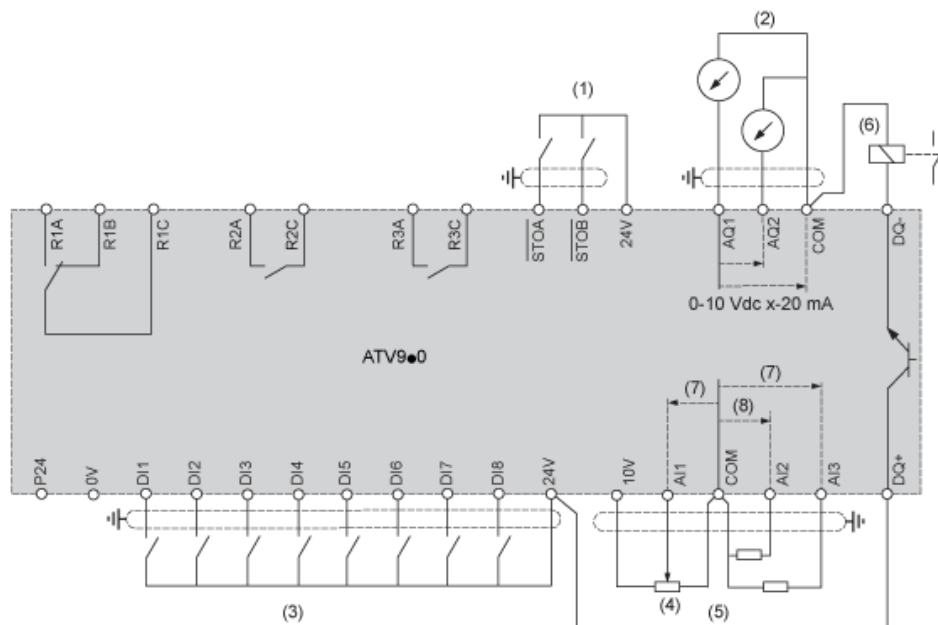
Three-Phase Power Supply with Downstream Breaking via Contactor

Connection diagrams conforming to standards EN 954-1 category 1 and IEC/EN 61508 capacity SIL1, stopping category 0 in accordance with standard IEC/EN 60204-1



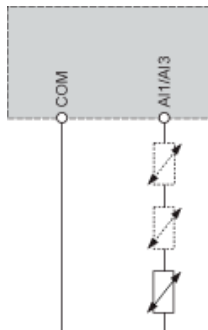
- (1) Line choke if used
 (2) Use relay R1 set to operating state Fault to switch Off the product once an error is detected.
 A1 : Drive
 KM1 : Contactor

Control Block Wiring Diagram



- (1) Safe Torque Off
 - (2) Analog Output
 - (3) Digital Input
 - (4) Reference potentiometer
 - (5) Analog Input
 - (6) Digital Output
 - (7) 0-10 Vdc, x-20 mA
 - (8) 0-10 Vdc, -10 Vdc...+10 Vdc
- R1A, R1B, R1C Relay
R2A, R2C Sequence relay
R3A, R3C Sequence relay

Sensor Connection



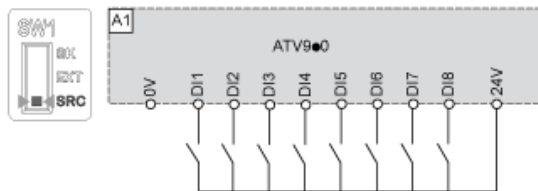
It is possible to connect either 1 or 3 sensors on terminals AI1 or AI3

Sink / Source Switch Configuration

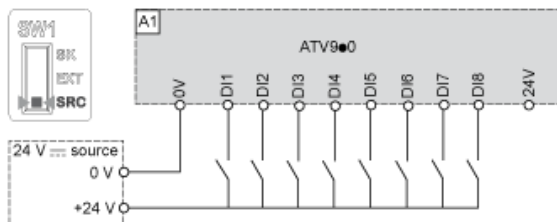
The switch is used to adapt the operation of the logic inputs to the technology of the programmable controller outputs.

- Set the switch to Source (factory setting) if using PLC outputs with PNP transistors.
- Set the switch to Ext if using PLC outputs with NPN transistors.

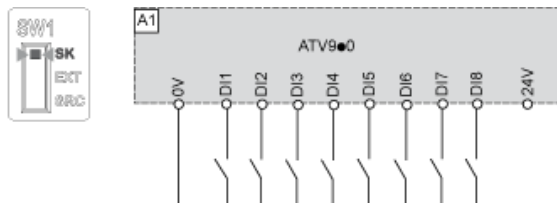
Switch Set to SRC (Source) Position Using the Output Power Supply for the Digital Inputs



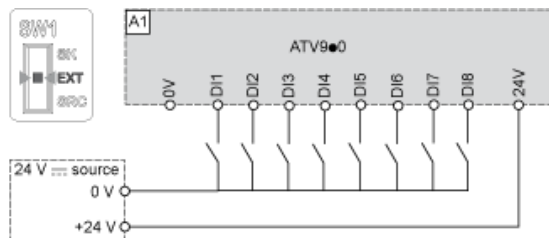
Switch Set to SRC (Source) Position and Use of an External Power Supply for the DIs



Switch Set to SK (Sink) Position Using the Output Power Supply for the Digital Inputs



Switch Set to EXT Position Using an External Power Supply for the DIs



Derating Curves

