

BMH0703P22F1A

servo motor BMH - 3.4 Nm - 8000 rpm - untapped shaft - with brake - IP65/IP67



Main

Product or component type	Servo motor
Device short name	BMH
Maximum mechanical speed	8000 rpm
Continuous stall torque	3.4 N.m for LXM32.D18N4 at 6 A, 400 V, three phase 3.4 N.m for LXM32.D18N4 at 6 A, 480 V, three phase
Peak stall torque	10.2 N.m for LXM32.D18N4 at 6 A, 400 V, three phase 10.2 N.m for LXM32.D18N4 at 6 A, 480 V, three phase
Nominal output power	1300 W for LXM32.D18N4 at 6 A, 400 V, three phase 1300 W for LXM32.D18N4 at 6 A, 480 V, three phase
Nominal torque	2.4 N.m for LXM32.D18N4 at 6 A, 400 V, three phase 2.4 N.m for LXM32.D18N4 at 6 A, 480 V, three phase
Nominal speed	5000 rpm for LXM32.D18N4 at 6 A, 400 V, three phase 5000 rpm for LXM32.D18N4 at 6 A, 480 V, three phase
Product compatibility	LXM32.D18N4 at 400...480 V three phase
Shaft end	Smooth shaft
IP degree of protection	IP65 standard IP67 with IP67 kit
Speed feedback resolution	131072 points/turn x 4096 turns
Holding brake	With
Mounting support	International standard flange
Electrical connection	Straight connectors

Complementary

Range compatibility	Lexium 32
[Us] rated supply voltage	480 V
Network number of phases	Three phase
Continuous stall current	3.91 A
Continuous power	1.68 W
Maximum current Irms	12.6 A for LXM32.D18N4

Maximum permanent current	12.57 A
Second shaft	Without second shaft end
Shaft diameter	14 mm
Shaft length	30 mm
Feedback type	Multiturn SinCos Hiperface
Holding torque	3 N.m holding brake
Motor flange size	70 mm
Number of motor stacks	3
Torque constant	0.87 N.m/A at 120 °C
Back emf constant	55.8 V/krpm at 120 °C
Number of motor poles	10
Rotor inertia	1.78 kg.cm ²
Stator resistance	2.65 Ohm at 20 °C
Stator inductance	8.6 mH at 20 °C
Stator electrical time constant	3.2 ms at 20 °C
Maximum radial force Fr	730 N at 1000 rpm 580 N at 2000 rpm 510 N at 3000 rpm 460 N at 4000 rpm 430 N at 5000 rpm 400 N at 6000 rpm
Maximum axial force Fa	0.2 x Fr
Brake pull-in power	7 W
Type of cooling	Natural convection
Length	225 mm
Centring collar diameter	60 mm
Centring collar depth	2.5 mm
Number of mounting holes	4
Mounting holes diameter	5.5 mm
Circle diameter of the mounting holes	82 mm
Product weight	4 kg

Offer Sustainability

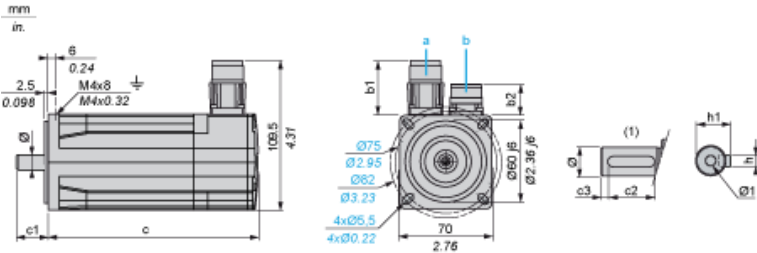
Sustainable offer status	Green Premium product
REACH Regulation	REACH Declaration
EU RoHS Directive	Pro-active compliance (Product out of EU RoHS legal scope) EU RoHS Declaration
Mercury free	Yes
RoHS exemption information	Yes
China RoHS Regulation	China RoHS declaration
Environmental Disclosure	Product Environmental Profile
Circularity Profile	No need of specific recycling operations
WEEE	The product must be disposed on European Union markets following specific waste collection and never end up in rubbish bins

Contractual warranty

Warranty	18 months
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Servo Motors Dimensions

Example with Straight Connectors



- a: Power supply for servo motor brake
b: Power supply for servo motor encoder
(1) Shaft end, keyed slot (optional)

Dimensions in mm

Straight connect		Rotatable angled		c (without brake)	c (with brake)	c1	c2	c3	h	h1	Ø	Ø1 for screws
b1	b2	b1	b2									
39.5	25.5	39.5	39.5	186	225	30	20	5	5 h9	16 ⁺⁰ _{-0.13}	14 k6	M5 x 17

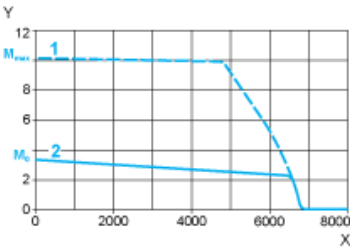
Dimensions in in.

Straight connect		Rotatable angled		c (without brake)	c (with brake)	c1	c2	c3	h	h1	Ø	Ø1 for screws
b1	b2	b1	b2									
1.55	1	1.55	1.55	7.32	8.85	1.18	0.78	0.19	0.20 h9	0.63 ⁺⁰ _{-0.0051}	0.55 k6	M5 x 0.67

400 V 3-Phase Supply Voltage

Torque/Speed Curves

Servo motor with LXM32•D18N4 servo drive

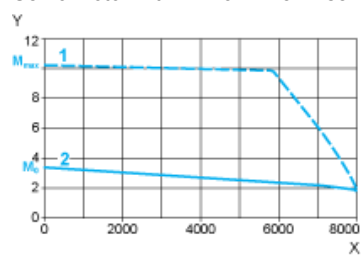


- X Speed in rpm
- Y Torque in Nm
- 1 Peak torque
- 2 Continuous torque

480 V 3-Phase Supply Voltage

Torque/Speed Curves

Servo motor with LXM32•D18N4 servo drive



- X Speed in rpm
Y Torque in Nm
1 Peak torque
2 Continuous torque