

Product data sheet

Characteristics

BMH2051P21F2A

servo motor BMH - 34.4 Nm - 3800 rpm -
untapped shaft - with brake - IP65/IP67



Main

Product or component type	Servo motor
Device short name	BMH
Maximum mechanical speed	3800 rpm
Continuous stall torque	34.4 N.m for LXM32.D72N4 24 A at 400 V three phase 34.4 N.m for LXM32.D72N4 24 A at 480 V three phase
Peak stall torque	103.4 N.m for LXM32.D72N4 24 A at 400 V three phase 103.4 N.m for LXM32.D72N4 24 A at 480 V three phase
Nominal output power	5400 W for LXM32.D72N4 24 A at 400 V three phase 5400 W for LXM32.D72N4 24 A at 480 V three phase
Nominal torque	25.8 N.m for LXM32.D72N4 24 A at 400 V three phase 25.8 N.m for LXM32.D72N4 24 A at 480 V three phase
Nominal speed	2000 rpm for LXM32.D72N4 24 A at 400 V three phase 2000 rpm for LXM32.D72N4 24 A at 480 V three phase
Product compatibility	LXM32.D72N4 at 400...480 V three phase
Shaft end	Untapped
IP degree of protection	IP65 (standard) IP67 (with IP67 kit)
Speed feedback resolution	131072 points/turn
Holding brake	With
Mounting support	International standard flange
Electrical connection	Rotatable right-angled connectors

Complementary

Range compatibility	Lexium 32
[Us] rated supply voltage	480 V
Network number of phases	Three phase
Continuous stall current	21.5 A
Continuous power	6.8 W
Maximum current I_{rms}	72 A for LXM32.D72N4
Maximum permanent current	78.1 A
Second shaft	Without second shaft end
Shaft diameter	38 mm
Shaft length	80 mm
Feedback type	Single turn SinCos Hiperface
Holding torque	80 N.m (holding brake)
Motor flange size	205 mm
Number of motor stacks	1
Back emf constant	104 V/krpm at 120 °C

The information provided in this documentation contains general descriptions and/or technical characteristics of the performance of the products contained herein. This documentation is not intended as a substitute for and is not to be used for determining suitability or reliability of these products for specific user applications. It is the duty of any such user or integrator to perform the appropriate and complete risk analysis, evaluation and testing of the products with respect to the relevant specific application or use thereof. Neither Schneider Electric Industries SAS nor any of its affiliates or subsidiaries shall be responsible or liable for misuse of the information contained herein.

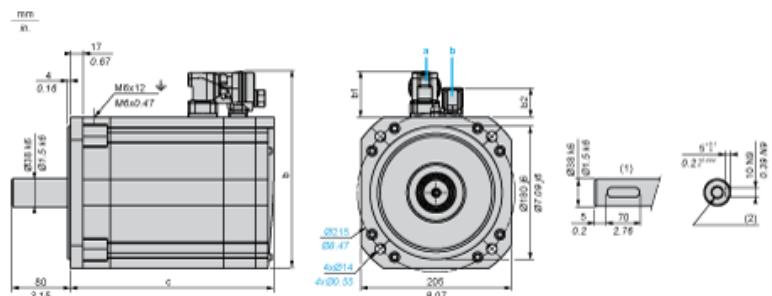
Number of motor poles	10
Rotor inertia	87.4 kg.cm ²
Stator resistance	0.3 Ohm at 20 °C
Stator inductance	5.9 mH at 20 °C
Stator electrical time constant	19.7 ms at 20 °C
Maximum radial force Fr	3730 N at 1000 rpm 2960 N at 2000 rpm 2580 N at 3000 rpm
Maximum axial force Fa	0.2 x Fr
Brake pull-in power	40 W
Type of cooling	Natural convection
Length	370.5 mm
Centring collar diameter	180 mm
Centring collar depth	4 mm
Number of mounting holes	4
Mounting holes diameter	14 mm
Circle diameter of the mounting holes	215 mm
Product weight	37.9 kg

Offer Sustainability

Sustainable offer status	Green Premium product
RoHS (date code: YYWW)	Compliant - since 0936 -  Schneider Electric declaration of conformity
REACH	Reference not containing SVHC above the threshold
Product environmental profile	Available  Download Product Environmental
Product end of life instructions	Need no specific recycling operations

Servo Motors Dimensions

Example with Straight Connectors



- a: Power supply for servo motor brake
- b: Power supply for servo motor encoder
- (1) Shaft end, keyed slot (optional)
- (2) For screw M12 x 28 mm/M12 x 1.10 in.

Dimensions in mm

Straight connectors			Rotatable angled connectors			c (without brake)	c (with brake)
b	b1	b2	b	b1	b2		
259	54	25.5	265	60	39.5	312	370.5

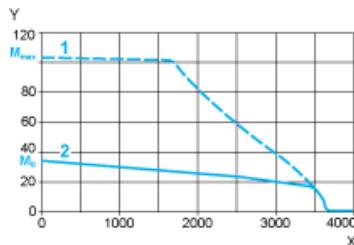
Dimensions in in.

Straight connectors			Rotatable angled connectors			c (without brake)	c (with brake)
b	b1	b2	b	b1	b2		
10.19	2.12	1.00	10.43	2.36	1.55	12.28	14.58

400 V 3-Phase Supply Voltage

Torque/Speed Curves

Servo motor with LXM32•D72N4 servo drive

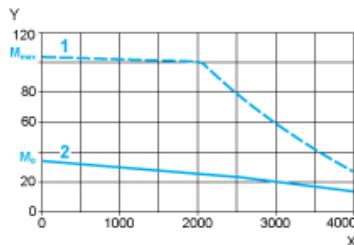


X Speed in rpm
Y Torque in Nm
1 Peak torque
2 Continuous torque

480 V 3-Phase Supply Voltage

Torque/Speed Curves

Servo motor with LXM32•D72N4 servo drive



X Speed in rpm
Y Torque in Nm
1 Peak torque
2 Continuous torque