BRS366H031ACB

3-phase stepper motor - 1.02 Nm - shaft Ø6.35 mm - L=56 mm - without brake -con.



Main Range compatibility Lexium SD3 Product or component Motion control motor Device short name BRS3 Maximum mechanical 3000 rpm speed Motor type 3-phase stepper motor Number of motor poles 48 V DC Supply voltage limits 34 V DC Mounting support Flange 57.2 mm Motor flange size Length 93 mm

38 mm

Complementary

| Complementary | |
|---------------------------------------|--|
| Centring collar depth | 1.6 mm |
| Number of mounting holes | 4 |
| Mounting holes diameter | 5.2 mm |
| Circle diameter of the mounting holes | 66.6 mm |
| Electrical connection | Connector |
| Feedback type | Single turn encoder |
| Speed feedback resolution | 10000 points/turn |
| Holding brake | Without |
| Shaft end | Smooth shaft |
| Second shaft | With second shaft end |
| Shaft diameter | 6.35 mm |
| Shaft length | 21 mm |
| Nominal torque | 0.9 N.m |
| Holding torque | 1.02 N.m |
| Rotor inertia | 0.22 kg.cm² |
| Resolution | 200, 400, 500, 1000, 2000, 4000, 5000, 10000 steps number of full steps per revolution 1.8 °, 0.9 °, 0.72 °, 0.36 °, 0.18 °, 0.09 °, 0.072 °, 0.036 ° step angle |
| Accuracy error | +/- 6 arc min |
| Maximum starting frequency | 8 kHz |
| [In] rated current | 5.8 A |
| Resistance | 0.5 Ohm (winding) |
| Time constant | 3.3 ms |
| Maximum radial force Fr | 24 N (first shaft end) 25 N (second shaft end) |
| Maximum axial force Fa | 8.4 N (force pressure) 100 N (tensile force) |
| Service life in hours | 20000 h (bearing) |
| Angular acceleration | 200000 rad/s² |
| Product weight | 1.6 kg |
| | |

Centring collar diame-

ter

Environment

| Standards | EN 50347 |
|---------------------------------------|---|
| | IEC 60072-1 |
| Type of cooling | Natural convection |
| Ambient air temperature for operation | -2540 °C |
| Ambient air temperature for storage | -2570 °C |
| Operating altitude | <= 1000 m without power derating |
| Relative humidity | 1585 % without condensation |
| Vibration resistance | A conforming to EN/IEC 60034-14 |
| | 20 m/s² maximum |
| IP degree of protection | IP41 for shaft bushing without shaft seal ring conforming to EN/IEC 60034-5 |
| | IP56 for total except shaft bushing conforming to EN/IEC 60034-5 |
| Temperature class | F class winding conforming to IEC/EN 60034-1 |

Offer Sustainability

| RoHS (date code: YYWW) | Compliant - since 0623 - Schneider Electric declaration of conformity |
|------------------------|---|
|------------------------|---|



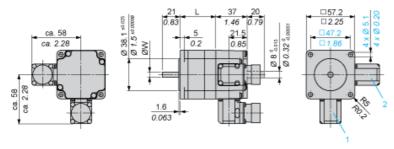
Product data sheet Dimensions Drawings

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Dimensions

3-Phase Stepper Motor in Connector Version





- 1: Plug connection encoder (optional) 12 poles
- 2: Plug connection motor 6 poles

Dimensions in mm

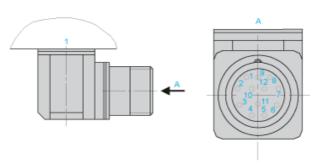
| L | Shaft diameter ØW |
|---------|-------------------|
| 56 ±0.5 | 6.35 ±0.013 |

Dimensions in in.

| L | Shaft diameter ØW |
|-------------|-------------------|
| 2.20 ±0.020 | 0.25 ±0.00051 |

BRS366H031ACB

Wiring Diagram of Encoder Plug on BRS3.



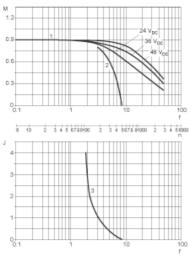
1: Motor housing

| 1 | 3 | |
|---|-----|----------------------|
| A negated B B B negated C, I C negated, I negated 5 V _{GND} 8 + 5 9 -SENSE 10 +SENSE 11 Temperature sensor | Pin | Designation |
| B negated C, I C negated, I negated V SURND C SENSE Temperature sensor | 1 | A |
| B negated C, I C negated, I negated V _{GND} Figure 10 +SENSE Temperature sensor | 2 | A negated |
| 5 C, I 6 C negated, I negated 7 5 V _{GND} 8 + 5 9 -SENSE 10 +SENSE 11 Temperature sensor | 3 | В |
| C negated, I negated 5 V _{GND} + 5 -SENSE +SENSE Temperature sensor | 4 | B negated |
| 7 5 V _{GND} 8 + 5 9 -SENSE 10 +SENSE 11 Temperature sensor | 5 | C, I |
| 8 + 5 9 -SENSE 10 +SENSE 11 Temperature sensor | 6 | C negated, I negated |
| 9 -SENSE 10 +SENSE 11 Temperature sensor | 7 | 5 V _{GND} |
| +SENSE Temperature sensor | 8 | + 5 |
| 11 Temperature sensor | 9 | -SENSE |
| · · | 10 | +SENSE |
| Not connected | 11 | Temperature sensor |
| | 12 | Not connected |

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Torque Characteristics

Measurement at 1000 Steps/Revolution, Nominal Voltage DC Bus U_{N} and Phase Current I_{N}



M: Torque in Nm
n: Speed in rpm
f: Frequency in kHz
J: Rotor inertia in kg.cm²
1: Pull-out torque
2: Pull-in torque
3: Maximum load inertia