



Main

Range compatibility	Lexium SD3
Product or component type	Motion control motor
Device short name	BRS3
Maximum mechanical speed	3000 rpm
Motor type	3-phase stepper motor
Number of motor poles	6
Supply voltage limits	230 V AC 325 V DC
Mounting support	Flange
Motor flange size	85 mm
Length	187 mm
Centring collar diameter	73 mm

Complementary

Centring collar depth	2 mm
Number of mounting holes	4
Mounting holes diameter	6.5 mm
Circle diameter of the mounting holes	98.99 mm
Electrical connection	Connector
Feedback type	Single turn encoder
Speed feedback resolution	10000 points/turn
Holding brake	With
Shaft end	Untapped
Second shaft	Without second shaft end
Shaft diameter	12 mm
Shaft length	30 mm
Nominal torque	4 N.m
Peak stall torque	3.82 N.m
Continuous stall torque	3.82 N.m
Holding torque	4.52 N.m
Rotor inertia	2.2 kg.cm²
Resolution	1000 points/turn

1.8 °, 0.9 °, 0.72 °, 0.36 °, 0.18 °, 0.09 °, 0.072 °, 0.036 ° step angle
 200, 400, 500, 1000, 2000, 4000, 5000, 10000 steps number of full steps per revolution

Accuracy error	+/- 6 arc min
Maximum starting frequency	5.3 kHz
[In] rated current	2 A
Resistance	5.8 Ohm (winding)
Time constant	9 ms
Maximum radial force Fr	100 N (first shaft end) 50 N (second shaft end)
Maximum axial force Fa	175 N (tensile force) 30 N (force pressure)
Service life in hours	20000 h (bearing)
Angular acceleration	200000 rad/s²
Product weight	3.2 kg

Environment

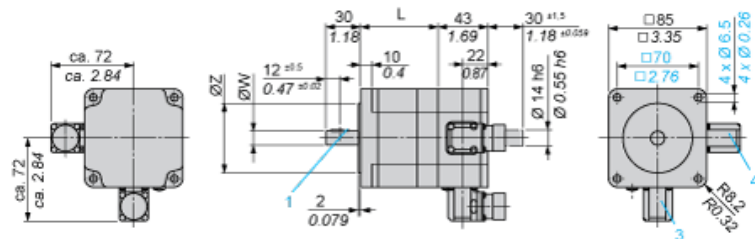
Standards	EN 50347 IEC 60072-1
Type of cooling	Natural convection
Ambient air temperature for operation	-25...40 °C
Ambient air temperature for storage	-25...70 °C
Operating altitude	<= 1000 m without power derating
Relative humidity	15...85 % without condensation
Vibration resistance	20 m/s² maximum A conforming to EN/IEC 60034-14
IP degree of protection	IP41 shaft bushing: conforming to EN/IEC 60034-5 IP56 total except shaft bushing: conforming to EN/IEC 60034-5
Temperature class	F winding conforming to IEC/EN 60034-1

Contractual warranty

Warranty	18 months
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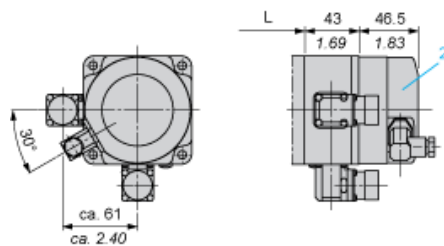
Dimensions

3-Phase Stepper Motor in Connector Version

$$\frac{\text{mm}}{\text{in.}}$$


- 3 : Motor connection 6 poles
4 : Motor connection (optional) 12 poles

Holding Brake

$$\frac{\text{mm}}{\text{in.}}$$


- 2 : Holding brake (optional)

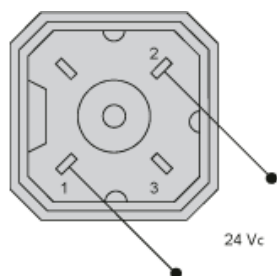
Dimensions in mm

L	Shaft diameter ØW	Centring collar ØZ	Woodruff key DIN 6888 (1)
97.5 (+0.6) (-0.8)	12 h6	73 h8	4 x 6.5

Dimensions in in.

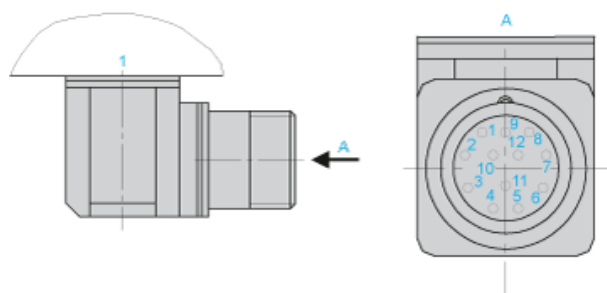
L	Shaft diameter ØW	Centring collar ØZ	Woodruff key DIN 6888 (1)
3.84 (+0.023) (-0.031)	0.47 h6	2.87 h8	0.16 x 0.25

Wiring Diagram of Holding Brake



The connector is part of the scope of delivery. Connector designation: Hirschmann type G4 A 5M

Wiring Diagram of Encoder Plug on BRS3••

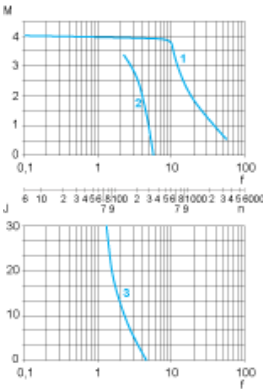


1 : Motor housing

Pin	Designation
1	A
2	A negated
3	B
4	B negated
5	C, I
6	C negated, I negated
7	5 V _{GND}
8	+ 5
9	-SENSE
10	+SENSE
11	Temperature sensor
12	Not connected

Torque Characteristics

Measurement at 1000 Steps/Revolution, Nominal Voltage DC Bus U_N and Phase Current I_N



- M : Torque in Nm
n : Speed in rpm
f : Frequency in kHz
J : Rotor inertia in kg.cm²
1 : Pull-out torque
2 : Pull-in torque
3 : Maximum load inertia