

DFS60E-T8EM01024

DFS60

INCREMENTAL ENCODERS





Ordering information

Туре	Part no.
DFS60E-T8EM01024	1069931

Other models and accessories → www.sick.com/DFS60

Illustration may differ



Detailed technical data

Performance

Pulses per revolution	1,024 ¹⁾
Measuring step	90° electric/pulses per revolution
Measuring step deviation at binary number of lines	± 0.15°
Error limits	± 0.3°

 $^{^{1)}}$ See maximum revolution range.

Interfaces

Communication interface	Incremental
Communication Interface detail	HTL / Push pull
Number of signal channels	6-channel
Initialization time	40 ms
Output frequency	≤ 300 kHz
Load current	≤ 30 mA
Power consumption	≤ 0.5 W (without load)
4.5 V 5.5 V, TTL/RS-422	
Load current	≤ 30 mA
4.5 V 5.5 V, Open Collector	
Load current	≤ 30 mA
TTL/RS-422	
Load current	≤ 30 mA
Power consumption	≤ 0.5 W (without load)
HTL/Push pull	
Load current	≤ 30 mA
	≤ 0.5 W (without load)
TTL/HTL	
Load current	
Power consumption	≤ 0.5 W (without load)

Open Co	ollector	
	Load current	≤ 30 mA
	Power consumption	≤ 0.5 W (without load)

Electrical data

Connection type	Cable, 8-wire, universal, 5 m ¹⁾
Supply voltage	10 32 V
Reference signal, number	1
Reference signal, position	90°, electric, logically gated with A and B
Reverse polarity protection	✓
Short-circuit protection of the outputs	✓ ²⁾
MTTFd: mean time to dangerous failure	300 years (EN ISO 13849-1) 3)

 $^{^{1)}}$ The universal cable connection is positioned so that it is possible to lay it without bends in a radial or axial direction.

Mechanical data

Mechanical design	Through hollow shaft
Shaft diameter	15 mm
Weight	+ 0.2 kg
Shaft material	Plastic
Flange material	Aluminum
Housing material	Aluminum die cast
Start up torque	0.8 Ncm (+20 °C)
Operating torque	0.6 Ncm (+20 °C)
Permissible shaft movement, axial static/dynamic	± 0.5 mm / ± 0.2 mm
Permissible shaft movement, radial static/dynamic	± 0.3 mm / ± 0.1 mm
Operating speed	≤ 6,000 min ⁻¹ 1)
Moment of inertia of the rotor	40 gcm ²
Bearing lifetime	3.6 x 10^10 revolutions
Angular acceleration	≤ 500,000 rad/s²

 $^{^{1)}}$ Allow for self-heating of 3.3 K per 1,000 rpm when designing the operating temperature range.

Ambient data

EMC	According to EN 61000-6-2 and EN 61000-6-4
Enclosure rating	IP65, housing side, cable connection (according to IEC 60529) IP65, shaft side (according to IEC 60529)
Permissible relative humidity	90 % (condensation of the optical scanning not permitted)
Operating temperature range	0 °C +85 °C
Storage temperature range	-40 °C +100 °C, without package
Resistance to shocks	50 g, 6 ms (according to EN 60068-2-27)

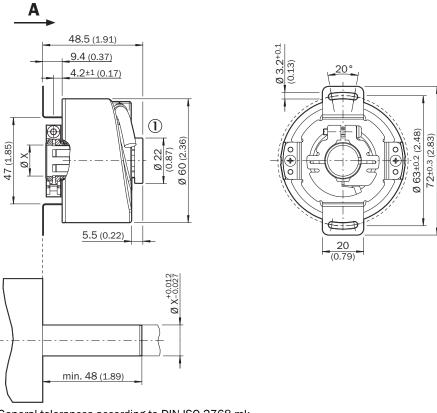
 $^{^{2)}\,\}mbox{Short-circuit}$ opposite to another channel, US or GND permissable for maximum 30 s.

³⁾ This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40°C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

Resistance to vibration	20 g, 10 Hz 2,000 Hz (according to EN 60068-2-6)
Classifications	
ECI@ss 5.0	27270501
ECI@ss 5.1.4	27270501
ECI@ss 6.0	27270590
ECI@ss 6.2	27270590
ECI@ss 7.0	27270501
ECI@ss 8.0	27270501
ECI@ss 8.1	27270501
ECI@ss 9.0	27270501
ECI@ss 10.0	27270501
ECI@ss 11.0	27270501
ETIM 5.0	EC001486
ETIM 6.0	EC001486
ETIM 7.0	EC001486
UNSPSC 16.0901	41112113

Dimensional drawing (Dimensions in mm (inch))

Through hollow shaft, plastic hollow shaft clamping, cable

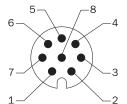


General tolerances according to DIN ISO 2768-mk

PIN assignment

Cable, 8-wire

View of M12 male device connector on encoder



View of M23 male device connector on encoder

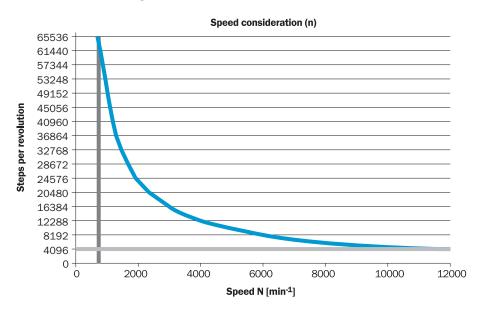


PIN, 8-pin, M12 male connector	PIN, 12-pin, M23 male connector	Color of the wires for encoders with cable outlet	TTL/HTL signal	Sin/cos 1.0 V _{ss}	Explanation	
1	6	Brown	_A	COS-	Signal wire	
2	5	White	A	COS+	Signal wire	
3	1	Black	В	SIN-	Signal wire	
4	8	Pink	В	SIN+	Signal wire	
5	4	Yellow	_Z	_Z	Signal wire	
6	3	Violet	Z	Z	Signal wire	
7	10	Blue	GND	GND	Ground connection of the encoder	
8	12	Red	+U _s	+U _s	Supply voltage (volt-free to housing)	
-	9	-	n.c.	n.c.	Not assigned	
-	2	-	n.c.	n.c.	Not assigned	
-	11	-	n.c.	n.c.	Not assigned	
-	7 1)	-	O-SET 1)	n.c.	Set zero pulse 1)	
Screen	Screen	Screen	Screen	Screen	Screen connected to housing on encoder side. Connected to ground on control side.	

¹⁾ For electrical interfaces only: M, U, V, W with 0-SET function on PIN 7 on M23 male connector. The 0-SET input is used to set the zero pulse on the current shaft position. If the 0-SET input is connected to U_S for longer than 250 ms after it had previously been unassigned for at least 1,000 ms or had been connected to the GND, the current position of the shaft is assigned to the zero pulse signal "Z".

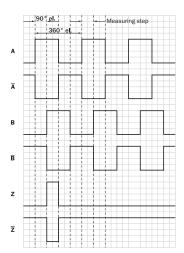
Maximum revolution range

Maximum revolution range



Signal outputs

Signal outputs



CW with view on the encoder shaft in direction "A", compare dimensional drawing.

Supply voltage	Output
4,5 V 5,5 V	ΠL
10 V 32 V	ΠL
10 V 32 V	HTL

Recommended accessories

Other models and accessories → www.sick.com/DFS60

	Brief description	Туре	Part no.				
Flanges	Flanges						
	Standard stator coupling	BEF-DS00XFX	2056812				
Other mounting accessories							
	Clamping ring for metal hollow shaft, metal	BEF-KR-M	2064709				

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