

DBS60E-TBZZ00S31

DBS60 Core

INCREMENTAL ENCODERS



Illustration may differ

Ordering information

Туре	Part no.
DBS60E-TBZZ00S31	1078428

Other models and accessories → www.sick.com/DBS60_Core



Detailed technical data

Features

Special device	✓
Specialty	Customized pcb with 10 zero pulse positions Cable, 8-wire, universal, 6 m with USB connector, A-code, customized pin allocation
Standard reference device	DBS60E-TBEK01000, 1072396

Performance

Pulses per revolution	640
Measuring step	≤ 90° electric/pulses per revolution
Measuring step deviation	± 18° / pulses per revolution
Error limits	Measuring step deviation x 3
Duty cycle	≤ 0.5 ± 5 %

Interfaces

Communication interface	Incremental	
Communication Interface detail	HTL / Push pull	
Number of signal channels	6-channel	
Initialization time	< 5 ms ¹⁾	
Output frequency	+ 300 kHz ²⁾	
Load current	≤ 30 mA, per channel	
Power consumption	≤ 1 W (without load)	

 $^{^{1)}}$ Valid signals can be read once this time has elapsed.

Electrical data

Connection type	Cable, 8-wire, with USB port, universal, 6 m, A-coded ¹⁾ Customized pin assignment	
Supply voltage	10 27 V	
Reference signal, number	1	
Reference signal, position	180°, electric, logically gated with A and B	

¹⁾ The universal cable connection is positioned so that it is possible to lay it without bends in a radial or axial direction.

²⁾ Up to 450 kHz on request.

 $^{^{2)}\,\}mbox{Short-circuit opposite to another channel, US or GND permissable for maximum 30 s.$

³⁾ This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40 °C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

Reverse polarity protection	✓
Short-circuit protection of the outputs	✓ ²⁾
MTTFd: mean time to dangerous failure	500 years (EN ISO 13849-1) 3)

¹⁾ The universal cable connection is positioned so that it is possible to lay it without bends in a radial or axial direction.

Mechanical data

Mechanical design	Through hollow shaft, Front clamp	
Shaft diameter		
Snart diameter	8 mm	
Flange type / stator coupling	2-sided stator coupling, slot, screw hole circle 63-83 mm	
Weight	+ 0.25 kg ¹⁾	
Shaft material	Stainless steel	
Flange material	Aluminum	
Housing material	Aluminum	
Material, cable	PVC	
Start up torque	+ 0.5 Ncm (+20 °C)	
Operating torque	0.4 Ncm (+20 °C)	
Permissible shaft movement, axial static/dynamic	± 0.5 mm / ± 0.2 mm	
Permissible shaft movement, radial static/dynamic	\pm 0.3 mm / \pm 0.1 mm	
Operating speed	6,000 min ^{-1 2)}	
Maximum operating speed	9,000 min ^{-1 3)}	
Moment of inertia of the rotor	50 gcm ²	
Bearing lifetime	3.6 x 10 ⁹ revolutions	
Angular acceleration	≤ 500,000 rad/s²	

 $^{^{1)}}$ Based on an encoder with a male connector outlet or a cable with a male connector outlet.

Ambient data

EMC	According to EN 61000-6-2 and EN 61000-6-3	
Enclosure rating	IP65, housing side (according to IEC 60529) ¹⁾ IP65, shaft side (according to IEC 60529)	
Permissible relative humidity	90 % (condensation of the optical scanning not permitted)	
Operating temperature range	-20 °C +85 °C ²⁾	
Storage temperature range	-40 °C +100 °C, without package	
Resistance to shocks	250 g, 3 ms (according to EN 60068-2-27)	
Resistance to vibration	30 g, 10 Hz 2,000 Hz (according to EN 60068-2-6)	

 $^{^{1)}}$ With mating connector fitted.

 $^{^{2)}\,\}mathrm{Short\text{-}circuit}$ opposite to another channel, US or GND permissable for maximum 30 s.

³⁾ This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40°C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

 $^{^{2)}\,\}mathrm{Allow}$ for self-heating of 2.6 K per 1,000 rpm when designing the operating temperature range.

³⁾ Maximum speed which does not cause mechanical damage to the encoder. Impact on the service life and signal quality is possible. Please note the maximum output frequency.

²⁾ These values relate to all mechanical versions including recommended accessories unless otherwise noted.

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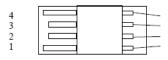
INCREMENTAL ENCODERS

Classifications

ECI@ss 5.0	27270501
ECI@ss 5.1.4	27270501
ECI@ss 6.0	27270590
ECI@ss 6.2	27270590
ECI@ss 7.0	27270501
ECI@ss 8.0	27270501
ECI@ss 8.1	27270501
ECI@ss 9.0	27270501
ECI@ss 10.0	27270501
ECI@ss 11.0	27270501
ETIM 5.0	EC001486
ETIM 6.0	EC001486
ETIM 7.0	EC001486
UNSPSC 16.0901	41112113

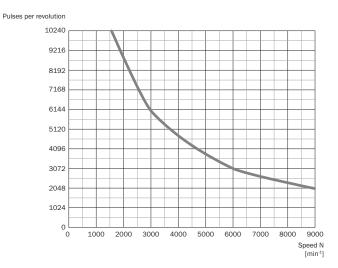
PIN assignment





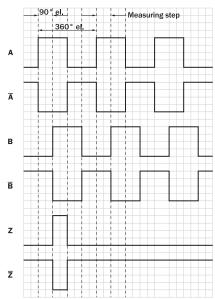
USB connector	TTI/HTL signal	Explanation
1	+U _S	Supply voltage (volt-free to housing)
2	В	Signal cable
3	Z	Signal cable
4	GND	Ground connection of the encoder
		Shield connected to housing on side
		of encoder. Connected to ground on
Shield	Shield	side of control.

Maximum revolution range

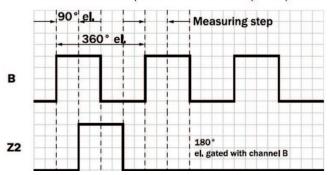


Signal outputs

Signal outputs for electrical interfaces TTL and HTL



Cw with view on the encoder shaft in direction "A", compare dimensional drawing. Width of the zero pulse in relation to a pulse period.



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Supply voltage	Output
4,5 V 5,5 V	πι
10 V 30 V	πL
10 V 27 V	HTL
4,5 V 30 V	TTL/HTL universal
4,5 V 30 V	ΠL

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