

DBS60E-S4EAZ0S46

DBS60 Core

INCREMENTAL ENCODERS

SICK
Sensor Intelligence.

Illustration may differ

Ordering information

Type	Part no.
DBS60E-S4EAZ0S46	1081615

Other models and accessories → www.sick.com/DBS60_Core



Detailed technical data

Features

Special device	✓
Specialty	Customer specific Encoder flange: face mount flange with servo slot Male connector M23, 12-pin Radial with customer specific PIN-allocation Optional accessory: customer specific adapter flange (2088849)
Standard reference device	DBS60E-S4EA01000, 1076554

Performance

Pulses per revolution	1,000
Measuring step	≤ 90° electric/pulses per revolution
Measuring step deviation	± 18° / pulses per revolution
Error limits	Measuring step deviation x 3
Duty cycle	≤ 0.5 ± 5 %

Interfaces

Communication interface	Incremental
Communication Interface detail	HTL / Push pull
Number of signal channels	6-channel
Initialization time	< 5 ms ¹⁾
Output frequency	+ 300 kHz ²⁾
Load current	≤ 30 mA, per channel
Power consumption	≤ 1 W (without load)

¹⁾ Valid signals can be read once this time has elapsed.

²⁾ Up to 450 kHz on request.

Electrical data

Connection type	Male connector, M23, 12-pin, radial
Supply voltage	10 ... 27 V
Reference signal, number	1
Reference signal, position	90°, electric, logically gated with A and B

¹⁾ Short-circuit opposite to another channel, US or GND permissible for maximum 30 s.

²⁾ This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40°C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

Reverse polarity protection	✓
Short-circuit protection of the outputs	✓ ¹⁾
MTTFd: mean time to dangerous failure	500 years (EN ISO 13849-1) ²⁾

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Mechanical data

Mechanical design	Solid shaft, face mount flange with servo slot
Shaft diameter	10 mm
Shaft length	19 mm
Flange type / stator coupling	Flange with 3 x M3 and 3 x M4
Weight	+ 0.3 kg ¹⁾
Shaft material	Stainless steel
Flange material	Aluminum
Housing material	Aluminum
Start up torque	+ 1.2 Ncm (+20 °C)
Operating torque	1.1 Ncm (+20 °C)
Permissible shaft loading radial/axial	100 N (radial) ²⁾ 50 N (axial) ²⁾
Operating speed	6,000 min ⁻¹ ³⁾
Maximum operating speed	9,000 min ⁻¹ ⁴⁾
Moment of inertia of the rotor	33 gcm ²
Bearing lifetime	3.6 x 10 ⁹ revolutions
Angular acceleration	≤ 500,000 rad/s ²

¹⁾ Based on an encoder with a male connector outlet or a cable with a male connector outlet.

²⁾ Higher values are possible using limited bearing life.

³⁾ Allow for self-heating of 3.2 K per 1,000 rpm when designing the operating temperature range.

⁴⁾ Maximum speed which does not cause mechanical damage to the encoder. Impact on the service life and signal quality is possible. Please note the maximum output frequency.

Ambient data

EMC	According to EN 61000-6-2 and EN 61000-6-3
Enclosure rating	IP67, housing side (according to IEC 60529) ¹⁾ IP65, shaft side (according to IEC 60529)
Permissible relative humidity	90 % (condensation of the optical scanning not permitted)
Operating temperature range	-20 °C ... +85 °C ²⁾
Storage temperature range	-40 °C ... +100 °C, without package
Resistance to shocks	250 g, 3 ms (according to EN 60068-2-27)
Resistance to vibration	30 g, 10 Hz ... 2,000 Hz (according to EN 60068-2-6)

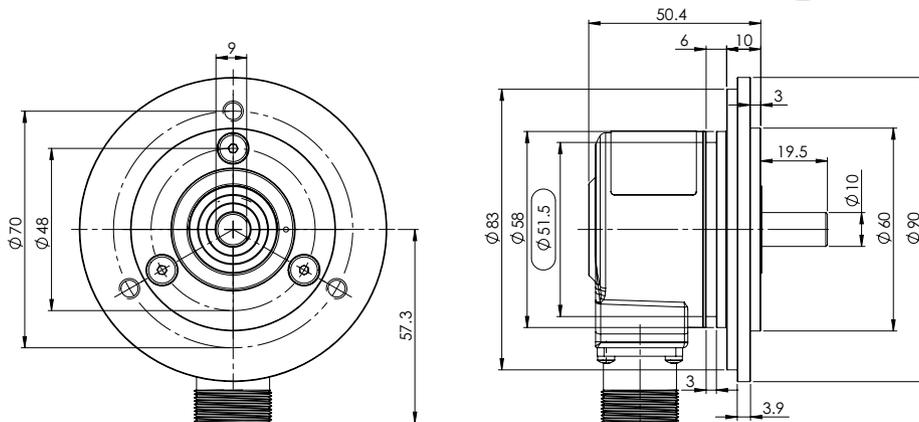
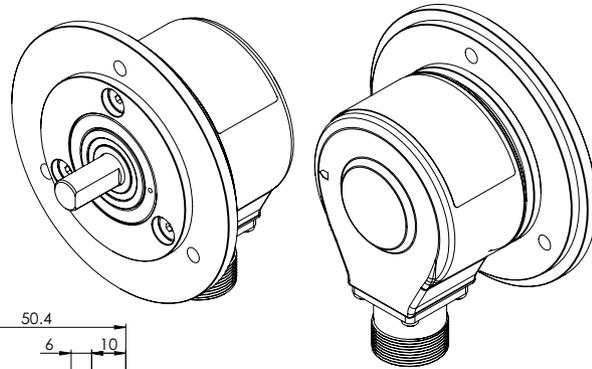
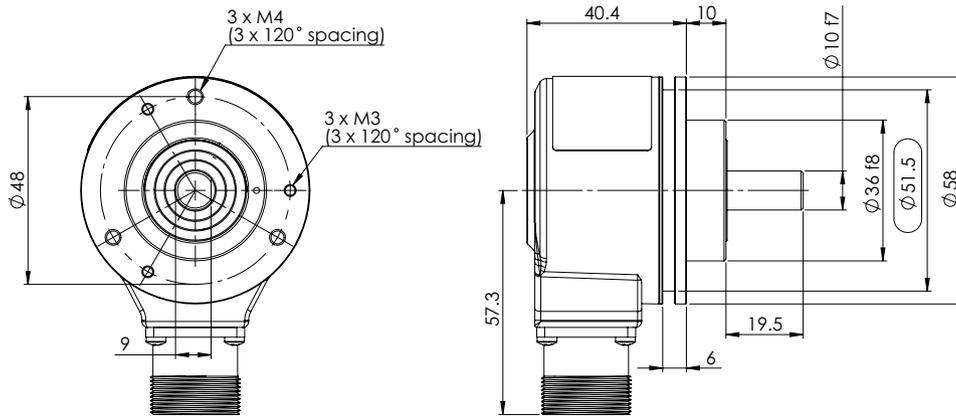
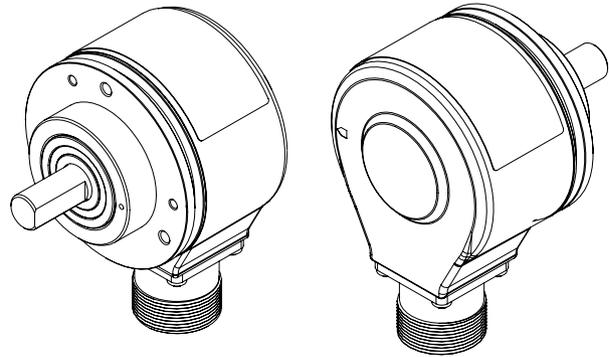
¹⁾ With mating connector fitted.

²⁾ These values relate to all mechanical versions including recommended accessories unless otherwise noted.

Classifications

ECl@ss 5.0	27270501
ECl@ss 5.1.4	27270501
ECl@ss 6.0	27270590
ECl@ss 6.2	27270590
ECl@ss 7.0	27270501
ECl@ss 8.0	27270501
ECl@ss 8.1	27270501
ECl@ss 9.0	27270501
ECl@ss 10.0	27270501
ECl@ss 11.0	27270501
ETIM 5.0	EC001486
ETIM 6.0	EC001486
ETIM 7.0	EC001486
UNSPSC 16.0901	41112113

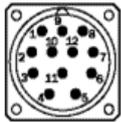
Dimensional drawing (Dimensions in mm (inch))



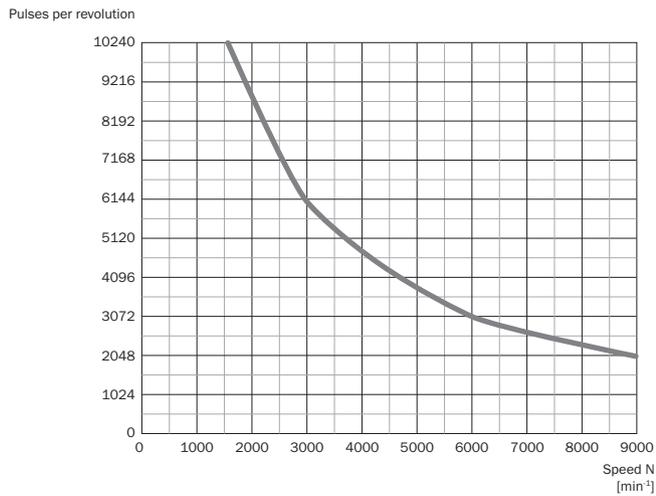
PIN assignment

Pin, 12-pin, M23 connector	HTL signal	Explanation
1	GND	Ground connection of the encoder
2	A	Signal cable
3	N.C.	Not assigned
4	N.C.	Not assigned
5	B	Signal cable
6	N.C.	Not assigned
7	N.C.	Not assigned
8	+U _S	Supply voltage (volt-free to housing)
9	N.C.	Not assigned
10	N.C.	Not assigned
11	N.C.	Not assigned
12	N.C.	Not assigned
Shield	Shield	Shield connected to housing on side of encoder. Connected to ground on side of control.

View of M23 device connector on cable cable/housing

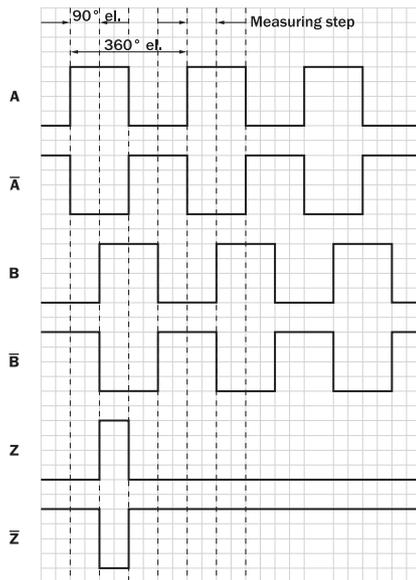


Maximum revolution range



Signal outputs

Signal outputs for electrical interfaces TTL and HTL



Cw with view on the encoder shaft in direction "A", compare dimensional drawing.

Supply voltage	Output
4,5 V ... 5,5 V	TTL
10 V ... 30 V	TTL
10 V ... 27 V	HTL
4,5 V ... 30 V	TTL/HTL universal
4,5 V ... 30 V	TTL

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