

# DBS60E-THFLD0S76

DBS60 Core

**INCREMENTAL ENCODERS** 



Illustration may differ

#### Ordering information

Туре	Part no.
DBS60E-THFLD0S76	1087914

Other models and accessories → www.sick.com/DBS60\_Core



#### Detailed technical data

#### **Features**

Special device	✓
Specialty	Customized orientation of the stator coupling
Standard reference device	DBS60E-THFLD1024, 1074281

#### Performance

Pulses per revolution	1,024
Measuring step	≤ 90° electric/pulses per revolution
Measuring step deviation	± 18° / pulses per revolution
Error limits	Measuring step deviation x 3
Duty cycle	≤ 0.5 ± 5 %

#### Interfaces

Communication interface	Incremental
Communication Interface detail	$TTL /  HTL^{ 1)}$
Number of signal channels	6-channel
Initialization time	< 5 ms <sup>2)</sup>
Output frequency	+ 300 kHz <sup>3)</sup>
Load current	≤ 30 mA, per channel
Power consumption	≤ 0.5 W (without load)

<sup>1)</sup> Output level depends on the supply voltage.

#### Electrical data

Connection type	Cable, 8-wire, universal, 3 m <sup>1)</sup>
Supply voltage	4.5 30 V
Reference signal, number	1
Reference signal, position	90°, electric, logically gated with A and B

<sup>1)</sup> The universal cable connection is positioned so that it is possible to lay it without bends in a radial or axial direction.

 $<sup>^{\</sup>rm 2)}\,{\rm Valid}$  signals can be read once this time has elapsed.

 $<sup>^{3)}</sup>$  Up to 450 kHz on request.

 $<sup>^{2)}\,\</sup>mbox{Short-circuit}$  opposite to another channel, US or GND permissable for maximum 30 s.

<sup>3)</sup> This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40°C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

Reverse polarity protection	✓
Short-circuit protection of the outputs	<b>✓</b> <sup>2)</sup>
MTTFd: mean time to dangerous failure	500 years (EN ISO 13849-1) 3)

 $<sup>^{1)}</sup>$  The universal cable connection is positioned so that it is possible to lay it without bends in a radial or axial direction.

#### Mechanical data

Mechanical design	Through hollow shaft, Front clamp
Shaft diameter	15 mm
Flange type / stator coupling	1-sided stator coupling, slot, screw hole circle radius 31.5–48.5 mm
Weight	+ 0.25 kg <sup>1)</sup>
Shaft material	Stainless steel
Flange material	Aluminum
Housing material	Aluminum
Material, cable	PVC
Start up torque	+ 0.5 Ncm (+20 °C)
Operating torque	0.4 Ncm (+20 °C)
Permissible shaft movement, axial static/dynamic	± 0.5 mm / ± 0.2 mm
Permissible shaft movement, radial static/dynamic	± 0.3 mm / ± 0.1 mm
Operating speed	6,000 min <sup>-1 2)</sup>
Maximum operating speed	9,000 min <sup>-1 3)</sup>
Moment of inertia of the rotor	50 gcm <sup>2</sup>
Bearing lifetime	3.6 x 10 <sup>9</sup> revolutions
Angular acceleration	≤ 500,000 rad/s²

 $<sup>^{1)}</sup>$  Based on an encoder with a male connector outlet or a cable with a male connector outlet.

#### Ambient data

EMC	According to EN 61000-6-2 and EN 61000-6-3
Enclosure rating	IP65, housing side (according to IEC 60529) IP65, shaft side (according to IEC 60529)
Permissible relative humidity	$90\ \%$ (condensation of the optical scanning not permitted)
Operating temperature range	–30 °C +100 °C, at maximum 3,000 pulses per revolution $^{1)}$
Storage temperature range	-40 °C +100 °C, without package
Resistance to shocks	250 g, 3 ms (according to EN 60068-2-27)
Resistance to vibration	30 g, 10 Hz 2,000 Hz (according to EN 60068-2-6)

 $<sup>^{1)}</sup>$  These values relate to all mechanical versions including recommended accessories unless otherwise noted.

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<sup>3)</sup> This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40°C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

 $<sup>^{2)}\,\</sup>mathrm{Allow}$  for self-heating of 2.6 K per 1,000 rpm when designing the operating temperature range.

<sup>3)</sup> Maximum speed which does not cause mechanical damage to the encoder. Impact on the service life and signal quality is possible. Please note the maximum output frequency.

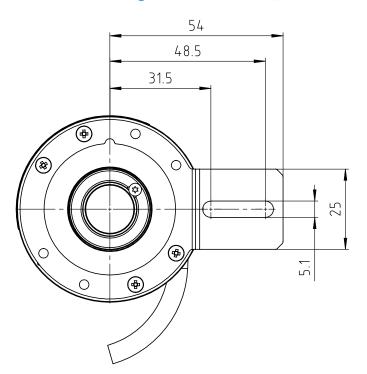
# DBS60E-THFLD0S76 | DBS60 Core

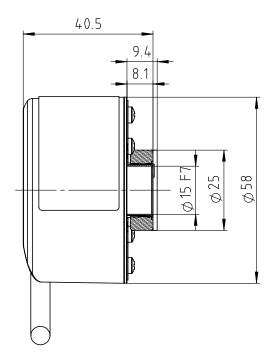
**INCREMENTAL ENCODERS** 

#### Classifications

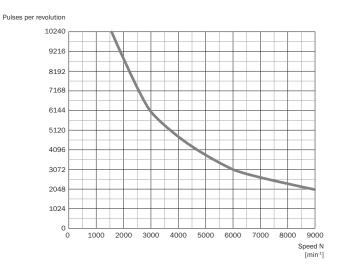
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ECI@ss 5.1.4	27270501
ECI@ss 6.0	27270590
ECI@ss 6.2	27270590
ECI@ss 7.0	27270501
ECI@ss 8.0	27270501
ECI@ss 8.1	27270501
ECI@ss 9.0	27270501
ECI@ss 10.0	27270501
ECI@ss 11.0	27270501
ETIM 5.0	EC001486
ETIM 6.0	EC001486
ETIM 7.0	EC001486
UNSPSC 16.0901	41112113

### Dimensional drawing (Dimensions in mm (inch))



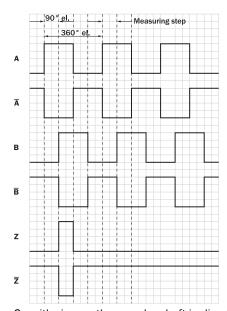


## Maximum revolution range



#### Signal outputs

Signal outputs for electrical interfaces TTL and HTL



Cw with view on the encoder shaft in direction "A", compare dimensional drawing.

Supply voltage	Output
4,5 V 5,5 V	ΠL
10 V 30 V	ΠL
10 V 27 V	HTL
4,5 V 30 V	TTL/HTL universal
4,5 V 30 V	ΠL

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