

# DFS60I-BENK01024

DFS60 Inox

**INCREMENTAL ENCODERS** 





## Ordering information

Туре	Part no.		
DFS60I-BENK01024	1091416		

Other models and accessories → www.sick.com/DFS60\_Inox

Illustration may differ



#### Detailed technical data

### Performance

Periods per revolution	1,024
Measuring step	90° electric/pulses per revolution
Measuring step deviation at binary number of lines	± 0.008°
Error limits	± 0.03°

#### Interfaces

Communication interface	Incremental
Communication Interface detail	Sin/Cos 1)
Number of signal channels	6-channel
Initialization time	40 ms
Output frequency	≤ 200 kHz
Load current	≤ 30 mA
Operating current	40 mA (without load)
Load resistance	≥ 120 Ω

 $<sup>^{1)}</sup>$  1.0 V<sub>SS</sub> (differential).

### Electrical data

Connection type	Cable, 8-wire, radial, 1.5 m	
Supply voltage	4.5 5.5 V	
Reference signal, number	1	
Reference signal, position	90°, electronically, gated with Sinus and Cosinus	
Reverse polarity protection	✓	
Short-circuit protection of the outputs	<b>✓</b> <sup>1)</sup>	

 $<sup>^{1)}\,\</sup>mbox{Short-circuit}$  opposite to another channel, US or GND permissable for maximum 30 s.

<sup>&</sup>lt;sup>2)</sup> This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40 °C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

#### MTTFd: mean time to dangerous failure

300 years (EN ISO 13849-1) 2)

#### Mechanical data

Mechanical design	Blind hollow shaft
Shaft diameter	12 mm
Weight	+ 0.5 kg
Shaft material	Stainless steel V2A
Flange material	Stainless steel V2A
Housing material	Stainless steel V2A
Start up torque	1 Ncm (+20 °C)
Operating torque	0.5 Ncm (+20 °C)
Permissible shaft movement, axial static/dynamic	$\pm 0.5 \text{ mm} / \pm 0.01 \text{ mm}$
Permissible shaft movement, radial static/dynamic	± 0.3 mm / ± 0.05 mm
Operating speed	≤ 6,000 min <sup>-1 1)</sup>
Moment of inertia of the rotor	40 gcm <sup>2</sup>
Bearing lifetime	3.6 x 10^10 revolutions
Angular acceleration	≤ 500,000 rad/s²

 $<sup>^{1)}</sup>$  Allow for self-heating of 3.3 K per 1,000 rpm when designing the operating temperature range.

### Ambient data

EMC	According to EN 61000-6-2 and EN 61000-6-3		
Enclosure rating	IP67, housing side (according to IEC 60529) IP67, shaft side (according to IEC 60529)		
Permissible relative humidity	90 % (condensation of the optical scanning not permitted)		
Operating temperature range	-40 °C +100 °C <sup>1)</sup> -30 °C +100 °C <sup>2)</sup>		
Storage temperature range	-40 °C +100 °C, without package		
Resistance to shocks	100 g, 6 ms (according to EN 60068-2-27)		
Resistance to vibration	10 g, 10 Hz 2,000 Hz (according to EN 60068-2-6)		

<sup>&</sup>lt;sup>1)</sup> Stationary position of the cable.

#### Classifications

ECI@ss 5.0	27270501
ECI@ss 5.1.4	27270501
ECI@ss 6.0	27270590
ECI@ss 6.2	27270590
ECI@ss 7.0	27270501
ECI@ss 8.0	27270501
ECI@ss 8.1	27270501

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<sup>&</sup>lt;sup>2)</sup> Flexible position of the cable.

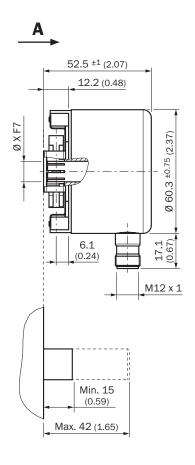
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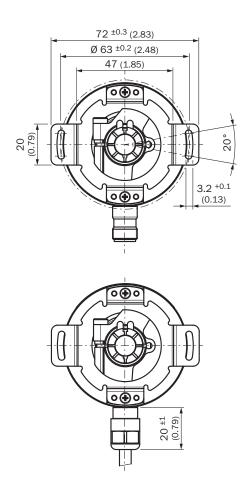
**INCREMENTAL ENCODERS** 

ECI@ss 9.0	27270501
ECI@ss 10.0	27270501
ECI@ss 11.0	27270501
ETIM 5.0	EC001486
ETIM 6.0	EC001486
ETIM 7.0	EC001486
UNSPSC 16.0901	41112113

## Dimensional drawing (Dimensions in mm (inch))

Blind hollow shaft

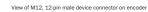




## PIN assignment

View of M12, 8-pin male device connector on encoder



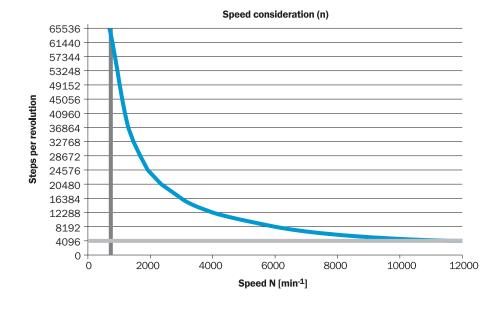




PIN, 8-pin, M12 male connector	PIN, 12-pin, M12 male connector	Color of the wires for encoders with cable outlet	TTL/HTL signal	Sin/cos 1.0 V <sub>ss</sub>	Explanation
1	7	Brown	Ā	COS-	Signal wire
2	6	White	A	COS+	Signal wire
3	9	Black	B	SIN-	Signal wire
4	8	Pink	В	SIN+	Signal wire
5	4	Yellow	Z	Z	Signal wire
6	11	Violet	Z	Z	Signal wire
7	12	Blue	GND	GND	Ground connection of the encoder
8	5	Red	+U <sub>s</sub>	+U <sub>s</sub>	Supply voltage (volt-free to housing)
-	2	-	n.c.	n.c.	Not assigned
-	3	-	n.c.	n.c.	Not assigned
-	1	-	n.c.	n.c.	Not assigned
-	101)	-	0-SET 1)	n.c.	Set zero pulse 1)
Screen	Screen	Screen	Screen	Screen	Screen connected to housing on encoder side.  Connected to ground on control side.

## Maximum revolution range

Maximum revolution range



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