

AHM36A-BDPL014x12

AHS/AHM36

ABSOLUTE ENCODERS





Ordering information

Туре	Part no.
AHM36A-BDPL014x12	1093426

Other models and accessories → www.sick.com/AHS_AHM36

Illustration may differ



Detailed technical data

Performance

Max. resolution (number of steps per revolution x number of revolutions)	14 bit x 12 bit (16,384 x 4,096)
Error limits G	0.35° (at 20 °C) ¹⁾
Repeatability standard deviation σ_{r}	0.2° (at 20 °C) ²⁾

¹⁾ In accordance with DIN ISO 1319-1, position of the upper and lower error limit depends on the installation situation, specified value refers to a symmetrical position, i.e. deviation in upper and lower direction is the same.

Interfaces

Communication interface	SSI
Process data	Position
Parameterising data	Number of steps per revolution Number of revolutions PRESET Counting direction Code type Offset of position bits Position error bit Round axis functionality SSI mode
Initialization time	100 ms ¹⁾
Position forming time	125 μs
SSI	
Code type	Gray, binary
Code sequence parameter adjustable	CW/CCW (V/R) configurable via programming tool or cable
Clock frequency	2 MHz ²⁾
Set (electronic adjustment)	H-active (L = $0 - 3 \text{ V}$, H = $4.0 - U_s \text{ V}$)
CW/CCW (counting sequence when turning)	L-active (L = $0 - 1 \text{ V}$, H = $2.0 - \text{Us V}$)

 $^{^{1)}}$ Valid positional data can be read once this time has elapsed.

 $^{^{2)}}$ In accordance with DIN ISO 55350-13; 68.3% of the measured values are inside the specified area.

 $^{^{2)}}$ Minimum, LOW level (Clock +): 250 ns.

Electrical data

Connection type	Cable, 8-wire, universal, 3 m
Supply voltage	4.5 32 V DC
Power consumption	≤ 1.5 W (without load)
Reverse polarity protection	✓
MTTFd: mean time to dangerous failure	230 years (EN ISO 13849-1) ¹⁾

¹⁾ This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40°C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

Mechanical data

Mechanical design	Blind hollow shaft
Shaft diameter	10 mm
Weight	$0.12 \mathrm{kg}^{ 1)}$
Shaft material	Stainless steel
Flange material	Aluminum
Housing material	Zinc
Material, cable	PUR
Start up torque	1 Ncm
Operating torque	< 1 Ncm
Permissible movement static	± 0.3 mm (radial) ± 0.3 mm (axial)
Permissible movement dynamic	± 0.1 mm (radial) ± 0.1 mm (axial)
Moment of inertia of the rotor	15 gcm ²
Bearing lifetime	2.0 x 10^9 revolutions
Angular acceleration	$\leq 500,000 \text{ rad/s}^2$
Operating speed	≤ 6,000 min ^{-1 2)}

 $^{^{1)}}$ Based on devices with male connector.

Ambient data

EMC	According to EN 61000-6-2 and EN 61000-6-3
Enclosure rating	IP66 (according to IEC 60529) IP67 (according to IEC 60529)
Permissible relative humidity	90 % (Condensation not permitted)
Operating temperature range	-40 °C +100 °C
Storage temperature range	-40 °C +100 °C, without package
Resistance to shocks	100 g, 6 ms (according to EN 60068-2-27)
Resistance to vibration	20 g, 10 Hz 2,000 Hz (according to EN 60068-2-6)

Classifications

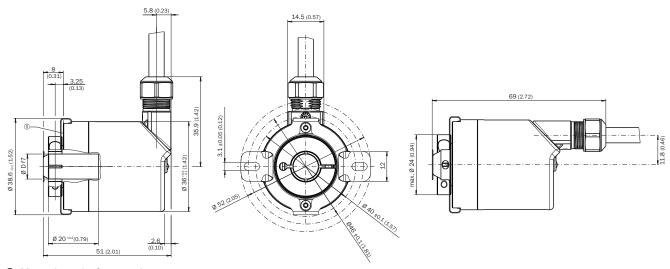
ECI@ss 5.0	27270502
ECI@ss 5.1.4	27270502
ECI@ss 6.0	27270590

 $^{^{2)}}$ Allow for self-heating of 3.5 K per 1,000 rpm when designing the operating temperature range.

ECI@ss 6.2	27270590
ECI@ss 7.0	27270502
ECI@ss 8.0	27270502
ECI@ss 8.1	27270502
ECI@ss 9.0	27270502
ECI@ss 10.0	27270502
ECI@ss 11.0	27270502
ETIM 5.0	EC001486
ETIM 6.0	EC001486
ETIM 7.0	EC001486
UNSPSC 16.0901	41112113

Dimensional drawing (Dimensions in mm (inch))

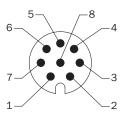
Blind hollow shaft, cable



 $\textcircled{1} \ \ \text{Measuring point for operating temperature}$

PIN assignment

M12 male connector, 8-pin and cable, 8-wire, SSI/Gray



View of M12 male device connector on encoder

PIN	Wire colors (cable connection)	Signal	Explanation
1	Brown	Data -	Interface signals
2	White	Data +	Interface signals

PIN	Wire colors (cable connection)	Signal	Explanation
3	Black	V/R	Sequence in direction of rotation
4	Pink	SET	Electronic adjustment Interface signals
5	Yellow	Clock +	Interface signals
6	Purple	Clock -	Interface signals
7	Blue	GND	Ground connection
8	Red	U_S	Operating voltage
		Screen	Screen connected to hous- ing on encoder side. Connect- ed to ground on control side.

Recommended accessories

Other models and accessories → www.sick.com/AHS_AHM36

	Brief description	Туре	Part no.	
Flanges				
	Stator coupling on hole circle 63 mm	BEF-DS08	2072206	
	Standard stator coupling, AHS/AHM36	BEF-DS16-AHX	2108615	
Programming	and configuration tools			
	USB programming unit, for programmable SICK encoders AFS60, AFM60, DFS60, VFS60, DFV60 and wire draw encoders with programmable encoders	PGT-08-S	1036616	
A D . W A	Programming unit display for programmable SICK DFS60, DFV60, AFS/AFM60, AHS/AHM36 encoders, and wire draw encoder with DFS60, AFS/AFM60 and AHS/AHM36. Compact dimensions, low weight, and intuitive operation.	PGT-10-Pro	1072254	
Plug connectors and cables				
	Head A: female connector, terminal box, 8-pin, straight Head B: male connector, D-Sub, 9-pin, straight Cable: SSI + incremental, PVC, shielded, 0.5 m Programming adapter cable for programming tool PGT-10-Pro and PGT-08-S	DSL-0D08-G0M5AC3	2061739	
	Head A: male connector, M12, 8-pin, straight, A-coded Head B: - Cable: Incremental, shielded	STE-1208-GA01	6044892	

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