



# AFM60I-BBKM262144

AFS/AFM60 Inox

**ABSOLUTE ENCODERS**

**SICK**  
Sensor Intelligence.



Illustration may differ



## Ordering information

| Type              | Part no. |
|-------------------|----------|
| AFM60I-BBKM262144 | 1102591  |

Other models and accessories → [www.sick.com/AFS\\_AFM60\\_Inox](http://www.sick.com/AFS_AFM60_Inox)

## Detailed technical data

## Performance

|                                                                                 |                                   |
|---------------------------------------------------------------------------------|-----------------------------------|
| <b>Max. resolution (number of steps per revolution x number of revolutions)</b> | 18 bit x 12 bit (262,144 x 4,096) |
| <b>Error limits G</b>                                                           | 0.03° <sup>1)</sup>               |
| <b>Repeatability standard deviation <math>\sigma_r</math></b>                   | 0.002° <sup>2)</sup>              |

<sup>1)</sup> In accordance with DIN ISO 1319-1, position of the upper and lower error limit depends on the installation situation, specified value refers to a symmetrical position, i.e. deviation in upper and lower direction is the same.

<sup>2)</sup> In accordance with DIN ISO 55350-13; 68.3% of the measured values are inside the specified area.

## Interfaces

|                                              |                                                      |
|----------------------------------------------|------------------------------------------------------|
| <b>Communication interface</b>               | SSI                                                  |
| <b>Communication Interface detail</b>        | SSI + Sin/Cos                                        |
| <b>Initialization time</b>                   | 50 ms <sup>1)</sup>                                  |
| <b>Position forming time</b>                 | < 1 µs                                               |
| <b>SSI</b>                                   |                                                      |
| Code type                                    | Gray                                                 |
| Code sequence parameter adjustable           | CW/CCW (V/R)                                         |
| Clock frequency                              | 2 MHz <sup>2)</sup>                                  |
| Set (electronic adjustment)                  | H-active (L = 0 - 3 V, H = 4,0 - U <sub>s</sub> V)   |
| CW/CCW (counting sequence when turning)      | L-active (L = 0 - 1,5 V, H = 2,0 - U <sub>s</sub> V) |
| <b>Sin/Cos</b>                               |                                                      |
| Sine/cosine periods per revolution           | 1,024                                                |
| Output frequency                             | ≤ 200 Hz                                             |
| Load resistance                              | ≥ 120 Ω                                              |
| Signal before differential generation        | 0.5 V <sub>pp</sub> , ± 20 %, 120 Ω                  |
| Signal offset before differential generation | 2.5 V ± 10 %                                         |

<sup>1)</sup> Valid positional data can be read once this time has elapsed.

<sup>2)</sup> SSI max. clock frequency 2 MHz, and min. LOW level (Clock+): 500 ns.

|                                      |                                   |
|--------------------------------------|-----------------------------------|
| Signal after differential generation | 1 V <sub>pp</sub> , ± 20 %, 120 Ω |
|--------------------------------------|-----------------------------------|

<sup>1)</sup> Valid positional data can be read once this time has elapsed.

<sup>2)</sup> SSI max. clock frequency 2 MHz, and min. LOW level (Clock+): 500 ns.

## Electrical data

|                                              |                             |
|----------------------------------------------|-----------------------------|
| <b>Connection type</b>                       | Cable, 12-wire, radial, 5 m |
| <b>Supply voltage</b>                        | 4.5 ... 32 V DC             |
|                                              | Cable, 12-wire              |
| <b>Output frequency</b>                      | ≤ 200 kHz                   |
| <b>Power consumption</b>                     | ≤ 0.7 W (without load)      |
| <b>Reverse polarity protection</b>           | ✓                           |
| <b>MTTFd: mean time to dangerous failure</b> | 250 years <sup>1)</sup>     |

<sup>1)</sup> This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40 °C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

## Mechanical data

|                                                          |                                         |
|----------------------------------------------------------|-----------------------------------------|
| <b>Mechanical design</b>                                 | Blind hollow shaft                      |
| <b>Shaft diameter</b>                                    | 8 mm                                    |
| <b>Weight</b>                                            | 0.5 kg <sup>1)</sup>                    |
| <b>Shaft material</b>                                    | Stainless steel V2A                     |
| <b>Flange material</b>                                   | Stainless steel V2A                     |
| <b>Housing material</b>                                  | Stainless steel V2A                     |
| <b>Start up torque</b>                                   | 1 Ncm                                   |
| <b>Operating torque</b>                                  | 0.5 Ncm                                 |
| <b>Permissible shaft movement, axial static/dynamic</b>  | ± 0.5 mm, ± 0.1 mm                      |
| <b>Permissible shaft movement, radial static/dynamic</b> | ± 0.3 mm, ± 0.1 mm                      |
| <b>Permissible Load capacity of shaft</b>                | 80 N / radial<br>40 N / axial           |
| <b>Moment of inertia of the rotor</b>                    | 40 gcm <sup>2</sup>                     |
| <b>Bearing lifetime</b>                                  | 3.0 x 10 <sup>9</sup> revolutions       |
| <b>Angular acceleration</b>                              | ≤ 500,000 rad/s <sup>2</sup>            |
| <b>Operating speed</b>                                   | ≤ 6,000 min <sup>-1</sup> <sup>2)</sup> |

<sup>1)</sup> Relates to devices with male connector connection.

<sup>2)</sup> Allow for self-heating of 3.3 K per 1,000 rpm when designing the operating temperature range.

## Ambient data

|                         |                                                                                                                         |
|-------------------------|-------------------------------------------------------------------------------------------------------------------------|
| <b>EMC</b>              | According to EN 61000-6-2 and EN 61000-6-3 <sup>1)</sup>                                                                |
| <b>Enclosure rating</b> | IP67, shaft side<br>IP67, housing side, male connector connection <sup>2)</sup><br>IP67, housing side, cable connection |

<sup>1)</sup> EMC according to the standards quoted is achieved if shielded cables are used.

<sup>2)</sup> With mating connector fitted.

<sup>3)</sup> Stationary position of the cable.

<sup>4)</sup> Flexible position of the cable.

|                                      |                                                                      |
|--------------------------------------|----------------------------------------------------------------------|
| <b>Permissible relative humidity</b> | 90 % (condensation of the optical scanning not permitted)            |
| <b>Operating temperature range</b>   | -40 °C ... +100 °C <sup>3)</sup><br>-30 °C ... +100 °C <sup>4)</sup> |
| <b>Storage temperature range</b>     | -40 °C ... +100 °C, without package                                  |
| <b>Resistance to shocks</b>          | 100 g, 6 ms (according to EN 60068-2-27)                             |
| <b>Resistance to vibration</b>       | 10 g, 10 Hz ... 2,000 Hz (according to EN 60068-2-6)                 |

<sup>1)</sup> EMC according to the standards quoted is achieved if shielded cables are used.

<sup>2)</sup> With mating connector fitted.

<sup>3)</sup> Stationary position of the cable.

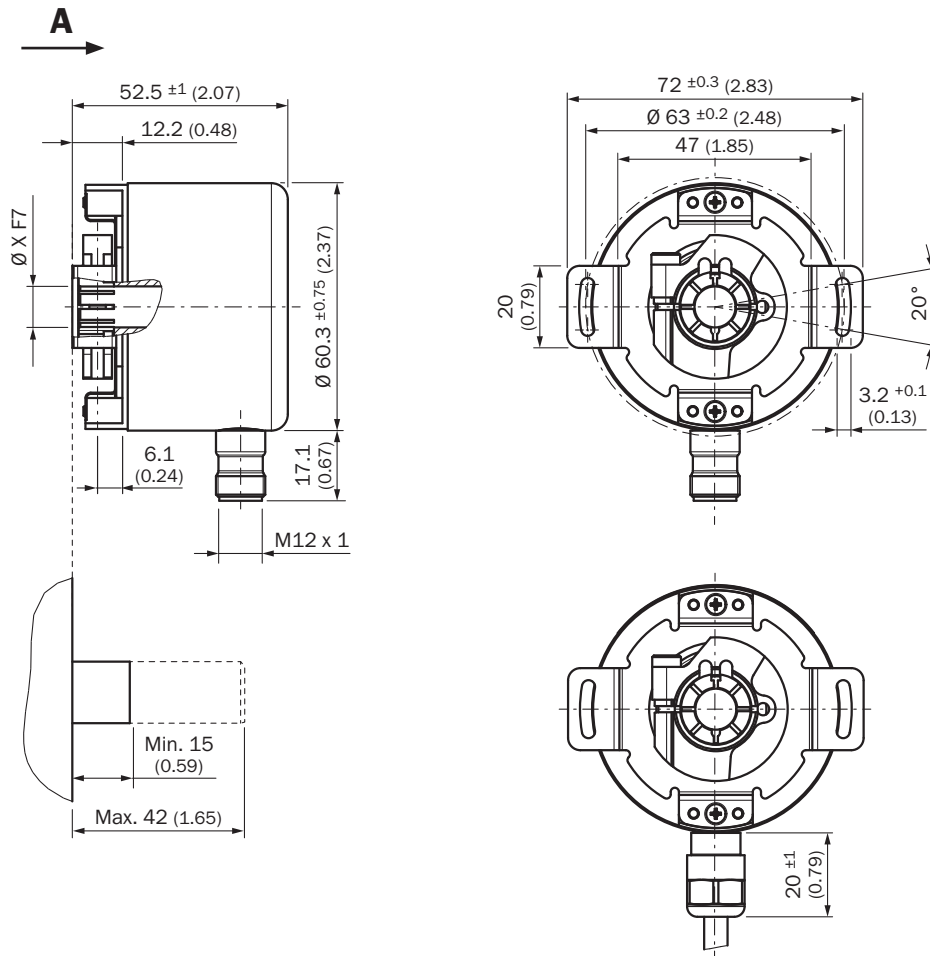
<sup>4)</sup> Flexible position of the cable.

## Classifications

|                       |          |
|-----------------------|----------|
| <b>ECI@ss 5.0</b>     | 27270502 |
| <b>ECI@ss 5.1.4</b>   | 27270502 |
| <b>ECI@ss 6.0</b>     | 27270590 |
| <b>ECI@ss 6.2</b>     | 27270590 |
| <b>ECI@ss 7.0</b>     | 27270502 |
| <b>ECI@ss 8.0</b>     | 27270502 |
| <b>ECI@ss 8.1</b>     | 27270502 |
| <b>ECI@ss 9.0</b>     | 27270502 |
| <b>ECI@ss 10.0</b>    | 27270502 |
| <b>ECI@ss 11.0</b>    | 27270502 |
| <b>ETIM 5.0</b>       | EC001486 |
| <b>ETIM 6.0</b>       | EC001486 |
| <b>ETIM 7.0</b>       | EC001486 |
| <b>UNSPSC 16.0901</b> | 41112113 |

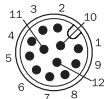
## Dimensional drawing (Dimensions in mm (inch))

Blind hollow shaft



## PIN assignment

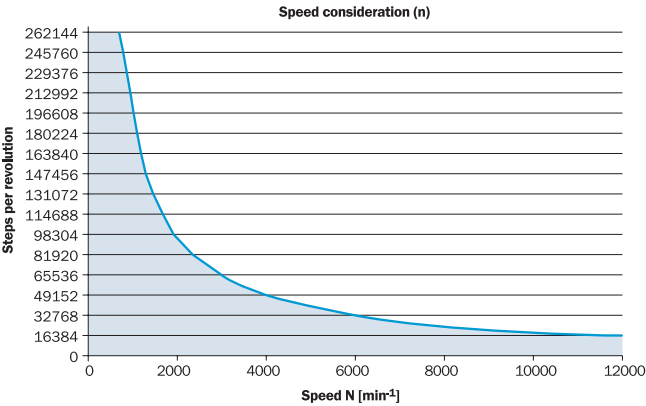
M12 male connector, 12-pin and cable connection, cable 12-wire, SSI/Gray + Sin/Cos



View to the connector M12 12-pin fitted to the encoder body

| PIN, 12-pin, M12 connector | Color of wires, cable outlet | Signal          | Explanation                                                                             |
|----------------------------|------------------------------|-----------------|-----------------------------------------------------------------------------------------|
| 1                          | Orange/black                 | 2W/CCW          | Counting sequence when turning                                                          |
| 2                          | White                        | Data+           | Interface signals                                                                       |
| 3                          | Brown                        | Data-           | Interface signals                                                                       |
| 4                          | Violet                       | Clock-          | Interface signals                                                                       |
| 5                          | Red                          | +U <sub>s</sub> | Supply voltage                                                                          |
| 6                          | Gray                         | Cos+            | Signal line                                                                             |
| 7                          | Green                        | Cos-            | Signal line                                                                             |
| 8                          | Pink                         | Sin+            | Signal line                                                                             |
| 9                          | Black                        | Sin-            | Signal line                                                                             |
| 10                         | Orange                       | SET             | Electronic adjustment                                                                   |
| 11                         | Yellow                       | Clock+          | Interface signals                                                                       |
| 12                         | Blue                         | GND             | Ground connection                                                                       |
|                            | Screen                       | Screen          | Screen connected to housing on side of encoder. Connected to ground on side of control. |

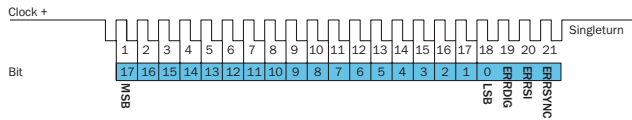
Maximum revolution range



The maximum speed is also dependent on the shaft type.

## Diagrams

### SSI data format singleturn



#### Bit 1–18: Position Bits

- LSB: Least significant Bit
- MSB: Most significant Bit

#### Bit 19–21: Error Bits

- ERRDIG: Failure message about speed. If this failure occurs during the position building procedure it will be indicated by the ERRDIG-Bit.
- ERRSI: Light source monitoring failure.
- ERRSYNC: Contamination of the disc or scanning system. During the determination of the position, an error has occurred since the last SSI transmission. The error bit will be deleted during the next data transmission.

#### The evaluation of the error bits has to be realized in the PLC.

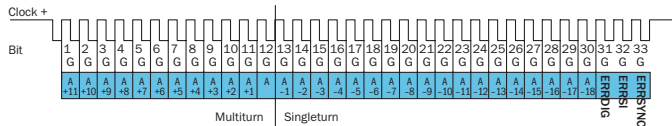
The provided error bits don't have to be used by the PLC compulsorily.

#### Example

If the resolution of the absolute encoder is set on 13 bits, 16 bits are provided by the encoder: 13 data bits and 3 error bits. If the PLC is not able to evaluate the error bits, the PLC has to be set on a resolution of 13 bits. Then the error bits have to be masked out by the PLC.

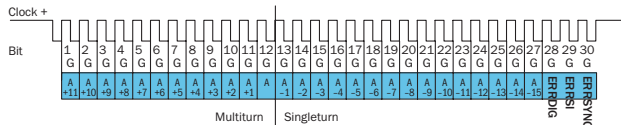
### SSI data format multiturn

#### 30 Bits



Bit 1–12: Position Bits multiturn  
Bit 13–30: Position Bits singleturn  
Bit 31–33: Error Bits

#### 27 Bits



Bit 1–12: Position Bits multiturn  
Bit 13–27: Position Bits singleturn  
Bit 28–30: Error Bits

#### Error Bits

- ERRDIG: Failure message about speed. If this failure occurs during the position building procedure it will be indicated by the ERRDIG-Bit.
- ERRSI: Light source monitoring failure.
- ERRSYNC: Contamination of the disc or scanning system. During the determination of the position, an error has occurred since the last SSI transmission. The error bit will be deleted during the next data transmission.

#### The evaluation of the error bits has to be realized in the PLC.

The provided error bits don't have to be used by the PLC compulsorily. The multiturn resolution is fixed on 12 bits.

#### Example

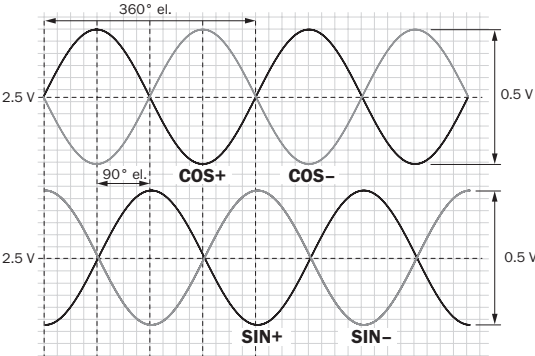
If the resolution of the absolute encoder is set on 27 bits, 30 bits are provided by the encoder: 27 data bits and 3 error bits. If the PLC is not able to evaluate the error bits, the PLC has to be set on a resolution of 27 bits. Then the error bits have to be masked out by the PLC.

Electrical interfaces sine  $0.5\text{ V}_{pp}$

| Power supply  | Output                   |
|---------------|--------------------------|
| 4.5 ... 5.5 V | Sine $0.5\text{ V}_{pp}$ |

Signal **before** differential generation at load  $120\ \Omega$  at  $U_s = 5\text{ V}$

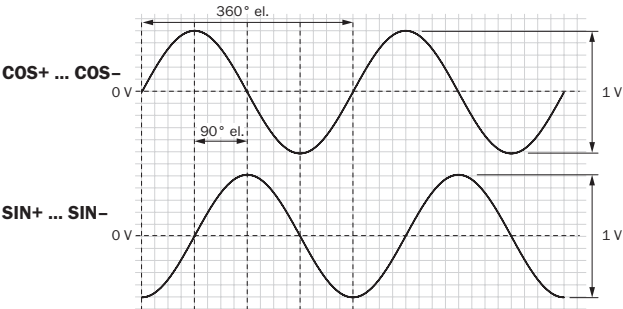
Signal diagram for clockwise rotation of the shaft looking in direction “A” (shaft)



| Interface signals Sin, $\overline{\text{Sin}}$ , Cos, $\overline{\text{Cos}}$ | Signal before differential generation at load $120\ \Omega$ | Signal offset           |
|-------------------------------------------------------------------------------|-------------------------------------------------------------|-------------------------|
| Analog differential                                                           | $0.5\text{ V}_{pp} \pm 20\%$                                | $2.5\text{ V} \pm 10\%$ |

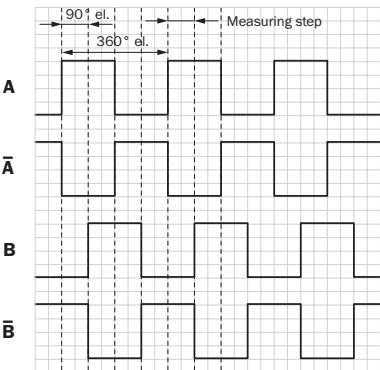
Signal **after** differential generation at load  $120\ \Omega$  at  $U_s = 5\text{ V}$

Signal diagram for clockwise rotation of the shaft looking in direction “A” (shaft)



Electrical interfaces HTL/TTL

Incremental pulse diagram for clockwise rotation of the shaft looking in direction “A”, see dimensional drawing





## SICK AT A GLANCE

SICK is one of the leading manufacturers of intelligent sensors and sensor solutions for industrial applications. A unique range of products and services creates the perfect basis for controlling processes securely and efficiently, protecting individuals from accidents and preventing damage to the environment.

We have extensive experience in a wide range of industries and understand their processes and requirements. With intelligent sensors, we can deliver exactly what our customers need. In application centers in Europe, Asia and North America, system solutions are tested and optimized in accordance with customer specifications. All this makes us a reliable supplier and development partner.

Comprehensive services complete our offering: SICK LifeTime Services provide support throughout the machine life cycle and ensure safety and productivity.

**For us, that is “Sensor Intelligence.”**

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