



DFS60I-S4PC32678

DFS60 Inox

INCREMENTAL ENCODERS

SICK
Sensor Intelligence.



Illustration may differ



Ordering information

Type	Part no.
DFS60I-S4PC32678	1102682

Other models and accessories → www.sick.com/DFS60_Inox

Detailed technical data

Performance

Pulses per revolution	32,678 ¹⁾
Measuring step	90° electric/pulses per revolution
Measuring step deviation at non binary number of lines	± 0.002°
Error limits	± 0.03°

¹⁾ See maximum revolution range.

Interfaces

Communication interface	Incremental
Communication Interface detail	TTL / HTL
Factory setting	Factory setting: output level TTL
Number of signal channels	6-channel
Programmable/configurable	✓
Initialization time	32 ms ¹⁾ 30 ms
Output frequency	≤ 820 kHz
Load current	≤ 30 mA
Power consumption	≤ 0.7 W (without load)

¹⁾ With mechanical zero pulse width.

Electrical data

Connection type	Male connector, M12, 8-pin, radial
Supply voltage	4.5 ... 32 V
Reference signal, number	1

¹⁾ Programming TTL with ≥ 5.5 V: short-circuit opposite to another channel or GND permissible for maximum 30 s.

²⁾ Programming HTL or TTL with < 5.5 V: short-circuit opposite to another channel, US or GND permissible for maximum 30 s.

³⁾ This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40°C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

Reference signal, position	90°, electric, logically gated with A and B
Reverse polarity protection	✓
Short-circuit protection of the outputs	✓ ^{1) 2)}
MTTFd: mean time to dangerous failure	300 years (EN ISO 13849-1) ³⁾

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Mechanical data

Mechanical design	Solid shaft, face mount flange
Shaft diameter	10 mm
Wavelength	19 mm
Weight	+ 0.5 kg
Shaft material	Stainless steel V2A
Flange material	Stainless steel V2A
Housing material	Stainless steel V2A
Start up torque	1 Ncm (+20 °C)
Operating torque	0.5 Ncm (+20 °C)
Permissible shaft loading radial/axial	80 N (radial) 40 N (axial)
Operating speed	$\leq 9,000 \text{ min}^{-1}$ ¹⁾
Moment of inertia of the rotor	6.2 gcm ²
Bearing lifetime	3.6 x 10 ¹⁰ revolutions
Angular acceleration	$\leq 500,000 \text{ rad/s}^2$

¹⁾ Allow for self-heating of 3.3 K per 1,000 rpm when designing the operating temperature range.

Ambient data

EMC	According to EN 61000-6-2 and EN 61000-6-3
Enclosure rating	IP67, housing side (according to IEC 60529) ¹⁾ IP67, shaft side (according to IEC 60529)
Permissible relative humidity	90 % (condensation of the optical scanning not permitted)
Operating temperature range	-40 °C ... +100 °C ²⁾ -30 °C ... +100 °C ³⁾
Storage temperature range	-40 °C ... +100 °C, without package
Resistance to shocks	100 g, 6 ms (according to EN 60068-2-27)
Resistance to vibration	10 g, 10 Hz ... 2,000 Hz (according to EN 60068-2-6)

¹⁾ With mating connector fitted.

²⁾ Stationary position of the cable.

³⁾ Flexible position of the cable.

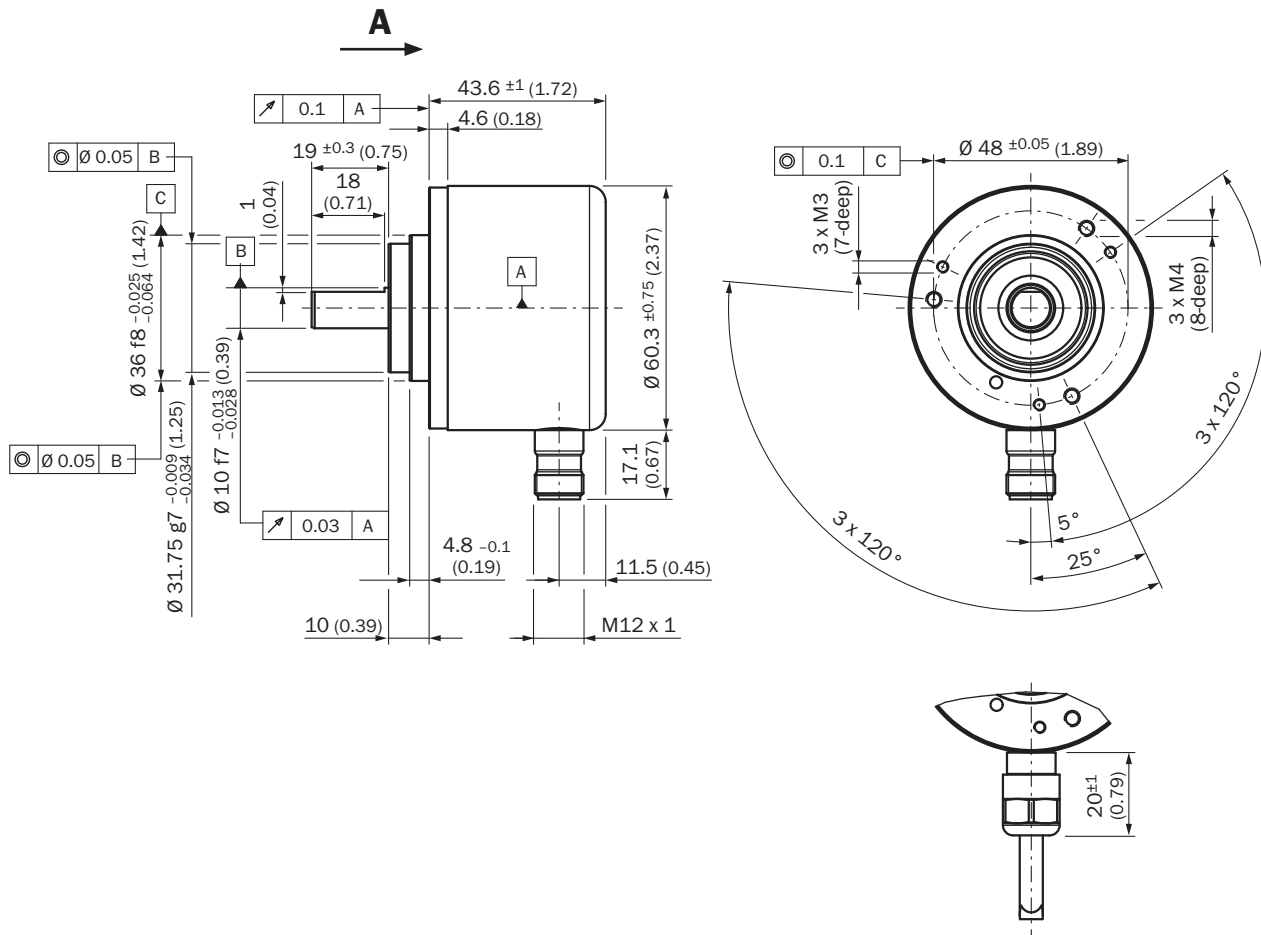
Classifications

ECl@ss 5.0	27270501
ECl@ss 5.1.4	27270501
ECl@ss 6.0	27270590

ECl@ss 6.2	27270590
ECl@ss 7.0	27270501
ECl@ss 8.0	27270501
ECl@ss 8.1	27270501
ECl@ss 9.0	27270501
ECl@ss 10.0	27270501
ECl@ss 11.0	27270501
ETIM 5.0	EC001486
ETIM 6.0	EC001486
ETIM 7.0	EC001486
UNSPSC 16.0901	41112113

Dimensional drawing (Dimensions in mm (inch))

Solid shaft, face mount flange



PIN assignment

View of M12, 8-pin male device connector on encoder



View of M12, 12-pin male device connector on encoder



¹⁾ For electrical interfaces only: M, V, W with O-SET function on PIN 10 on M12 male connector. The O-SET input is used to set the zero pulse on the current shaft position. If the O-SET input is connected to U_s for longer than 250 ms after it had previously been unassigned for at least 1,000 ms or had been connected to the GND, the current position of the shaft is assigned to the zero pulse signal "Z".

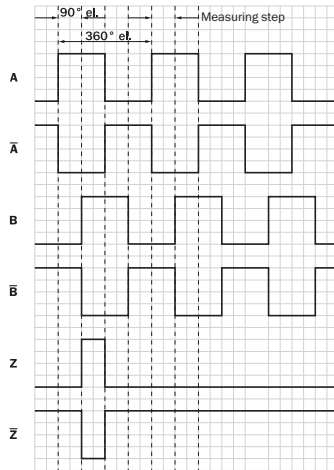
Maximum revolution range

Maximum revolution range



Signal outputs

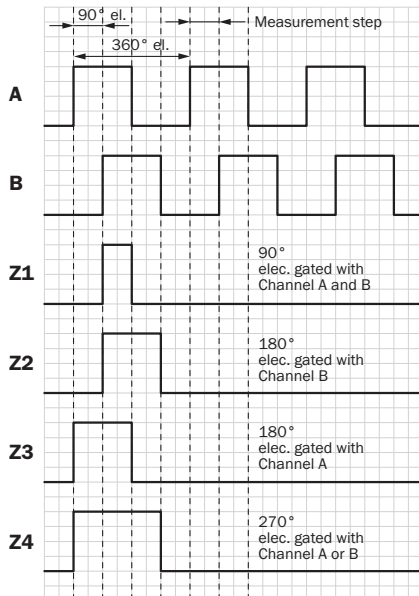
Signal outputs



CW with view on the encoder shaft in direction "A", compare dimensional drawing.

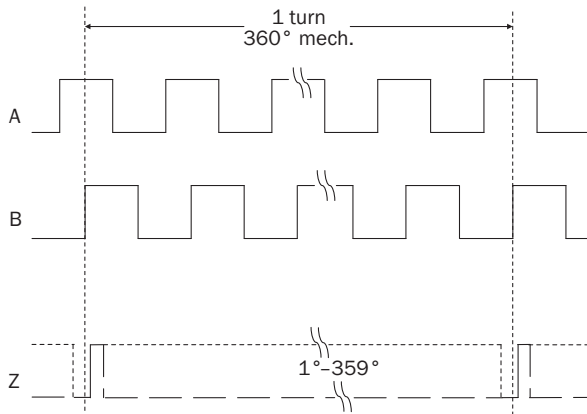
Diagrams

Electrical zero pulse width can be configured to 90°, 180°, or 270°. Width of the zero pulse in relation to a pulse period.



Cw with view on the encoder shaft in direction "A", compare dimensional drawing.

Mechanical zero pulse width 1° to 359° programmable. Width of the zero pulse in relation to a mechanical revolution of the shaft.



Recommended accessories

Other models and accessories → www.sick.com/DFS60_Inox

	Brief description	Type	Part no.
Plug connectors and cables			
	Head A: female connector, M12, 8-pin, straight Head B: Flying leads Cable: Incremental, SSI, PUR, halogen-free, shielded, 2 m	DOL-1208-G02MAC1	6032866
	Head A: female connector, M12, 8-pin, straight Head B: Flying leads Cable: Incremental, SSI, PUR, halogen-free, shielded, 5 m	DOL-1208-G05MAC1	6032867
	Head A: female connector, M12, 8-pin, straight Head B: Flying leads Cable: Incremental, SSI, PUR, halogen-free, shielded, 10 m	DOL-1208-G10MAC1	6032868
	Head A: female connector, M12, 8-pin, straight Head B: Flying leads Cable: Incremental, SSI, PUR, halogen-free, shielded, 20 m	DOL-1208-G20MAC1	6032869
	Head A: female connector, M12, 8-pin, straight Head B: Flying leads Cable: Incremental, SSI, PUR, halogen-free, shielded, 25 m	DOL-1208-G25MAC1	6067859
	Head A: female connector, M12, 8-pin, straight, A-coded Head B: - Cable: shielded	YF12ES8-0050S5586A	2097334
	Head A: male connector, M12, 8-pin, straight, A-coded Head B: - Cable: shielded	YM12ES8-0050S5586A	2097337

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Comprehensive services complete our offering: SICK LifeTime Services provide support throughout the machine life cycle and ensure safety and productivity.

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