

# AFS60A-TJPA262144

AFS/AFM60 SSI

**ABSOLUTE ENCODERS** 





# Ordering information

Туре	Part no.
AFS60A-TJPA262144	1105475

Other models and accessories → www.sick.com/AFS\_AFM60\_SSI

Illustration may differ



# Detailed technical data

### Performance

Number of steps per revolution (max. resolution)	262,144 (18 bit)
Error limits G	0.03° <sup>1)</sup>
Repeatability standard deviation $\boldsymbol{\sigma_{r}}$	0.002° <sup>2)</sup>

<sup>1)</sup> In accordance with DIN ISO 1319-1, position of the upper and lower error limit depends on the installation situation, specified value refers to a symmetrical position, i.e. deviation in upper and lower direction is the same.

#### Interfaces

Communication interface	SSI
Initialization time	50 ms <sup>1)</sup>
Position forming time	< 1 µs
SSI	
Code type	Gray
Code sequence parameter adjustable	CW/CCW (V/R) parameter adjustable
Clock frequency	≤ 2 MHz <sup>2)</sup>
Set (electronic adjustment)	H-active (L = $0 - 3 \text{ V}$ , H = $4.0 - U_s \text{ V}$ )
CW/CCW (counting sequence when turning)	L-active (L = 0 - 1,5 V, H = 2,0 - Us V)
Sin/Cos	
Load resistance	≥ 120 Ω

 $<sup>^{1)}</sup>$  Valid positional data can be read once this time has elapsed.

## Electrical data

Connection type	Male connector, M23, 12-pin, radial	
Supply voltage	4.5 32 V DC	
Power consumption	≤ 0.7 W (without load)	
Reverse polarity protection	✓	

<sup>1)</sup> This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40°C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

 $<sup>^{2)}</sup>$  In accordance with DIN ISO 55350-13; 68.3% of the measured values are inside the specified area.

 $<sup>^{2)}</sup>$  Minimum, LOW level (Clock +): 250 ns.

MTTFd: mean time to dangerous failure

250 years (EN ISO 13849-1) 1)

# Mechanical data

Mechanical design	Through hollow shaft
Shaft diameter	5/8″ <sup>1)</sup>
Weight	$0.2~{ m kg}^{2)}$
Shaft material	Stainless steel
Flange material	Aluminum
Housing material	Aluminum die cast
Start up torque	< 0.8 Ncm <sup>3) 3)</sup>
Operating torque	< 0.6 Ncm <sup>3) 3)</sup>
Permissible movement static	± 0.5 mm (axial) ± 0.3 mm (radial)
Permissible movement dynamic	± 0.2 mm (axial) ± 0.1 mm (radial)
Moment of inertia of the rotor	40 gcm <sup>2</sup>
Bearing lifetime	3.0 x 10^9 revolutions
Angular acceleration	+ 500,000 rad/s²
Operating speed	≤ 9,000 min <sup>-1 4)</sup>

 $<sup>^{1)}</sup>$  5/8" not available with multiturn.

# Ambient data

EMC	According to EN 61000-6-2 and EN 61000-6-3 1)
Enclosure rating	IP65, shaft side (according to IEC 60529) IP67, housing side (according to IEC 60529) <sup>2)</sup>
Permissible relative humidity	90 % (condensation of the optical scanning not permitted)
Operating temperature range	-40 °C +100 °C <sup>3)</sup>
Storage temperature range	-40 °C +100 °C, without package
Resistance to shocks	60 g, 6 ms (according to EN 60068-2-27)
Resistance to vibration	20 g, 10 Hz 2,000 Hz (according to EN 60068-2-6)

 $<sup>^{1)}</sup>$  EMC according to the standards quoted is achieved if shielded cables are used.

#### Classifications

ECI@ss 5.0	27270502
ECI@ss 5.1.4	27270502
ECI@ss 6.0	27270590
ECI@ss 6.2	27270590
ECI@ss 7.0	27270502

<sup>1)</sup> This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40°C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

<sup>&</sup>lt;sup>2)</sup> Relates to devices with male connector.

<sup>3)</sup> At 20 °C

 $<sup>^{4)}</sup>$  Allow for self-heating of 3.3 K per 1,000 rpm when designing the operating temperature range.

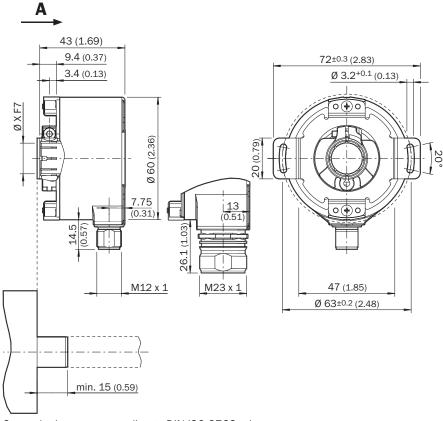
<sup>&</sup>lt;sup>2)</sup> For devices with male connector: With mating connector mounted.

<sup>&</sup>lt;sup>3)</sup> Stationary position of the cable.

ECI@ss 8.0	27270502
ECI@ss 8.1	27270502
ECI@ss 9.0	27270502
ECI@ss 10.0	27270502
ECI@ss 11.0	27270502
ETIM 5.0	EC001486
ETIM 6.0	EC001486
ETIM 7.0	EC001486
UNSPSC 16.0901	41112113

# Dimensional drawing (Dimensions in mm (inch))

Through hollow shaft, radial male connector M12 and M23



General tolerances according to DIN ISO 2768-mk ① Cable diameter = 5.6 mm +/- 0.2 mm bend radius = 30 mm

# PIN assignment

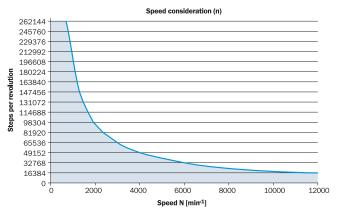
M23 male connector, 12-pin and cable, 12-wire, SSI/Gray + incremental



View of M23 male device connector on encoder

PIN	Wire colors (cable connection)	Signal	Explanation	
1	Red	U <sub>S</sub>	Operating voltage	
2	Blue	GND	Ground connection	
3	Yellow	Clock +	Interface signals	
4	White	Data +	Interface signals	
5	Orange	SET	Electronic adjustment	
6	Brown	Data -	Interface signals	
7	Violet	Clock -	Interface signals	
8	Black	_B	Signal wire	
9	Orange-black	V/R	Sequence in direction of rotation	
10	Green	¯A	Signal wire	
11	Gray	Α	Signal wire	
12	Pink	В	Signal wire	
		Screen	Screen connected to hous- ing on encoder side. Connect- ed to ground on control side.	

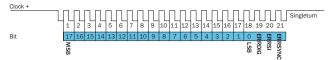
# Maximum revolution range



The maximum speed is also dependent on the shaft type.

### **Diagrams**

#### SSI data format singleturn



#### Bit 1-18: Position Bits

- · LSB: Least significant Bit
- . MSB: Most significant Bit

#### Bit 19-21: Error Bits

- ERRDIG: Failure message about speed. If this failure occurs during the position building procedure it will be indicated by the ERRDIG-Bit.
- ERRSI: Light source monitoring failure.
- ERRSYNC: Contamination of the disc or scanning system. During the determination of the position, an error has occurred since the last SSI transmission. The error bit will be deleted during the next data transmission.

#### The evaluation of the error bits has to be realized in the PLC.

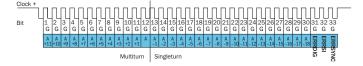
The provided error bits don't have to be used by the PLC compulsorily.

#### **Example**

If the resolution of the absolute encoder is set on 13 bits, 16 bits are provided by the encoder: 13 data bits and 3 error bits. If the PLC is not able to evaluate the error bits, the PLC has to be set on a resolution of 13 bits. Then the error bits have to be masked out by the PLC.

#### SSI data format multiturn

#### 30 Bits

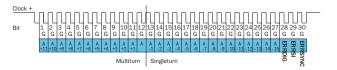


Bit 1–12: Position Bits multiturn

Bit 13-30: Position Bits singleturn

Bit 31-33: Error Bits

### 27 Bits



Bit 1-12: Position Bits multiturn

Bit 13-27: Position Bits singleturn

Bit 28-30: Error Bits

#### **Error Bits**

- ERRDIG: Failure message about speed. If this failure occurs during the position building procedure it will be indicated by the ERRDIG-Bit.
- ERRSI: Light source monitoring failure.
- ERRSYNC: Contamination of the disc or scanning system. During the determination of the position, an error has occurred since the last SSI transmission. The error bit will be deleted during the next data transmission.

#### The evaluation of the error bits has to be realized in the PLC.

The provided error bits don't have to be used by the PLC compulsorily. The multiturn resolution is fixed on 12 bits.

# Example

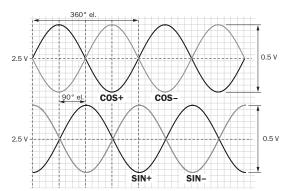
If the resolution of the absolute encoder is set on 27 bits, 30 bits are provided by the encoder: 27 data bits and 3 error bits. If the PLC is not able to evaluate the error bits, the PLC has to be set on a resolution of 27 bits. Then the error bits have to be masked out by the PLC.

# Electrical interfaces sine 0.5 $V_{pp}$

Power supply	Output
4.5 5.5 V	Sine 0.5 V

Signal **before** differential generation at load 120  $\Omega$  at U  $_{\rm S}$  = 5 V

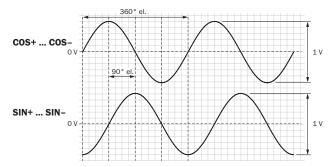
Signal diagram for clockwise rotation of the shaft looking in direction "A" (shaft)



Interface signals Sin, Sin, Cos, Cos	Signal before differential generation at load 120 $\boldsymbol{\Omega}$	Signal offset
Analog differential	0.5 V <sub>pp</sub> ± 20 %	2.5 V ± 10 %

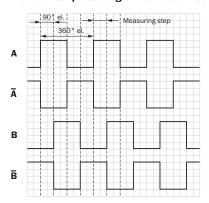
Signal after differential generation at load 120  $\Omega$  at U<sub>s</sub> = 5 V

Signal diagram for clockwise rotation of the shaft looking in direction "A" (shaft)



# **Electrical interfaces HTL/TTL**

Incremental pulse diagram for clockwise rotation of the shaft looking in direction "A", see dimensional drawing



# Recommended accessories

Other models and accessories → www.sick.com/AFS\_AFM60\_SSI

	Brief description	Туре	Part no.	
Programming and configuration tools				
	USB programming unit, for programmable SICK encoders AFS60, AFM60, DFS60, VFS60, DFV60 and wire draw encoders with programmable encoders	PGT-08-S	1036616	
A STATE OF THE PROPERTY OF THE	Programming unit display for programmable SICK DFS60, DFV60, AFS/AFM60, AHS/AHM36 encoders, and wire draw encoder with DFS60, AFS/AFM60 and AHS/AHM36. Compact dimensions, low weight, and intuitive operation.	PGT-10-Pro	1072254	
Plug connecto	ors and cables			
<u></u>	Head A: cable Head B: Flying leads Cable: SSI, Incremental, HIPERFACE <sup>®</sup> , PUR, halogen-free, shielded	LTG-2308-MWENC	6027529	
~	Head A: female connector, M23, 12-pin, straight Head B: Flying leads Cable: SSI, PUR, halogen-free, shielded, 3 m	DOL-2308-G03MAA6	2048597	
	Head A: female connector, M23, 12-pin, straight Head B: Flying leads Cable: SSI, PUR, halogen-free, shielded, 5 m	DOL-2308-G05MAA6	2048598	
	Head A: female connector, M23, 12-pin, straight Head B: Flying leads Cable: SSI, PUR, halogen-free, shielded, 0.5 m	DOL-2308-GOM5AA6	2048595	
	Head A: female connector, M23, 12-pin, straight Head B: Flying leads Cable: SSI, PUR, halogen-free, shielded, 10 m	DOL-2308-G10MAA6	2048599	
	Head A: female connector, M23, 12-pin, straight Head B: Flying leads Cable: SSI, PUR, halogen-free, shielded, 1.5 m	DOL-2308-G1M5AA6	2048596	
	Head A: female connector, M23, 9-pin, straight Cable: HIPERFACE <sup>®</sup> , SSI, Incremental, shielded	DOS-2309-G	6028533	
	Head A: female connector, M23, 12-pin, straight	DOS-2312-G	6027538	
	Head B: - Cable: HIPERFACE <sup>®</sup> , SSI, Incremental, shielded	DOS-2312-G02	2077057	
(Hind)	Head A: female connector, M23, 12-pin, angled Head B: - Cable: HIPERFACE <sup>®</sup> , SSI, Incremental, shielded	DOS-2312-W01	2072580	

# SICK AT A GLANCE

SICK is one of the leading manufacturers of intelligent sensors and sensor solutions for industrial applications. A unique range of products and services creates the perfect basis for controlling processes securely and efficiently, protecting individuals from accidents and preventing damage to the environment.

We have extensive experience in a wide range of industries and understand their processes and requirements. With intelligent sensors, we can deliver exactly what our customers need. In application centers in Europe, Asia and North America, system solutions are tested and optimized in accordance with customer specifications. All this makes us a reliable supplier and development partner.

Comprehensive services complete our offering: SICK LifeTime Services provide support throughout the machine life cycle and ensure safety and productivity.

For us, that is "Sensor Intelligence."

# **WORLDWIDE PRESENCE:**

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