



Absolute encoders AFS/AFM60 SSI

AFM60E-S4AL000256

Model Name > [AFM60E-S4AL000256](#)
Part No. > [1037841](#)



At a glance

- High-resolution absolute encoders with up to 30 bits (AFM60) or up to 18 bits (AFS60)
- Face mount flange, servo flange, blind or through hollow shaft
- SSI, SSI + Incremental or SSI + Sin/Cos interface
- Programmable resolution and offset (dependent on type)
- Connection system: M12, M23 connector or cable outlet
- Enclosure rating: IP 67 (housing), IP 65 (shaft)
- Operating temperature: -30 °C to +100 °C (depends on type)

Your benefits

- Programmability of the encoders means less storage, greater machine availability and easy installation
- Precise positioning due to high resolutions
- Large selection of mechanical interfaces and electrical contacting possibilities: Suitable for all applications
- Suitable for applications with limited space requirements (extremely short installation depth of 30 mm)
- Very good rotation accuracy due to increased bearing distance
- One programming tool and software with automatic encoder detection for AFS60/AFM60/DFS60



Performance

Max. number of steps per revolution:	256
Max. number of revolutions:	4,096
Resolution power:	256 x 4,096
Resolution:	8 bit x 12 bit
Error limits:	± 0.2 °
Repeatability (Ta not constant):	0.002 °
Measuring step deviation:	± 0.2 °
Measuring step:	0.09 °
Initialization time:	50 ms ¹⁾

¹⁾ Valid positional data can be read once this time has elapsed

Mechanical data

Mechanical interface:	Solid shaft with flat, Face mount flange
Shaft diameter:	10 mm

Start up torque:	0.5 Ncm (20 °C)
Operating torque:	0.3 Ncm (20 °C)
Permissible Load capacity of shaft:	40 N (axial), 80 N (radial)
Maximum operating speed:	9,000 /min ¹⁾
Moment of inertia of the rotor:	6.2 gcm ²
Bearing lifetime:	3.0 x 10 ⁹ revolutions
Max. angular acceleration:	500,000 rad/s ²

¹⁾ Self warming of 3.3 K per 1000 revolutions/min when applying note working temperature range

Electrical data

Power consumption:	0.5 W (without load)
Operating voltage range:	4.5 V DC ... 32 V DC
MTTFd: mean time to dangerous failure:	250 a (EN ISO 13849-1) ¹⁾

¹⁾ This product is a standard product and does not constitute a safety component as defined in the Machinery Directive.

Calculation based on nominal load of components, average ambient

temperature 40°C, frequency of use 8760 h/a. All

electronic failures are considered hazardous. For more information, see document no. 8015532.

Interfaces

Electrical interface:	Cable, 8-pin, universal, 3 m ¹⁾
Interface signals:	Clock +, Clock -, Data +, Data-
Clock frequency:	1 MHz ²⁾
SET (electronic adjustment):	H-active (L ≡ 0 - 1,5 V, H ≡ 2,0 - Us V)
CW/CCW (counting sequence when turning):	L-active (L ≡ 0 - 1,5 V, H ≡ 2,0 - Us V)

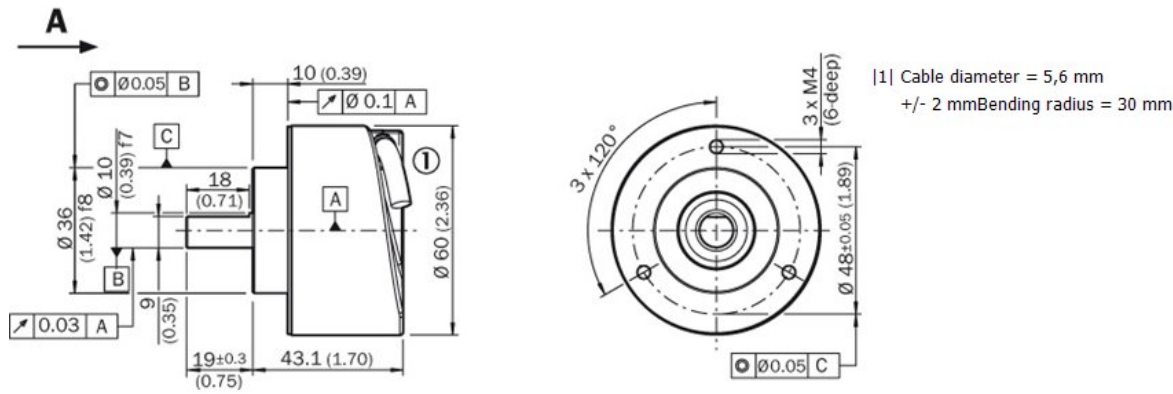
¹⁾ The universal cable outlet is positioned in such a way, that it is possible to lay the cable in a radial or axial direction without kinking it²⁾

Ambient data

EMC:	(according to EN 61000-6-2 and EN 61000-6-3) ¹⁾
Enclosure rating:	IP 65 (according to IEC 60529), shaft side, IP 67 (according to IEC 60529)
Permissible relative humidity:	90 % (condensation of the optical scanning not permitted)
Working temperature range:	0 °C ... 85 °C
Storage temperature range:	-40 °C ... 100 °C, without package
Resistance to shocks:	50 g (according to EN 60068-2-27)
Resistance to vibration:	20 g, 10 Hz ... 2,000 Hz (according to EN 60068-2-6)

¹⁾

Dimensional drawing



Signalausgänge

SSI data format singleturn



Example

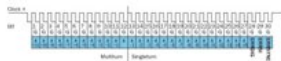
If the resolution of the absolute encoder is set on 13 bits, 16 bits are provided by the encoder: 13 data bits and 3 error bits. If the PLC is not able to evaluate the error bits, the PLC has to be set on a resolution of 13 bits. Then the error bits have to be masked out by the PLC.

SSI data format multiturn

30 Bits



27 Bits



Error Bits

- ERRDIG: Failure message about speed. If this failure occurs during the position building procedure it will be indicated by the ERRDIG-Bit.
- ERRSL: Light source monitoring failure.
- ERRSYNC: Contamination of the disc or scanning system. During the determination of the position, an error has occurred since the last SSI transmission. The error bit will be deleted during the next data transmission.

The evaluation of the error bits has to be realized in the PLC.

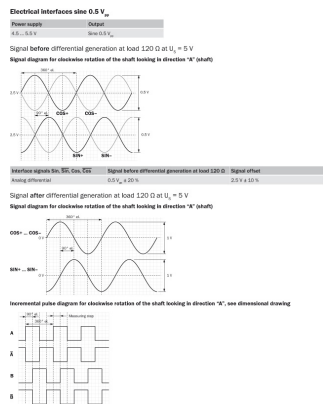
The provided error bits don't have to be used by the PLC compulsorily. The multiturn resolution is fixed on 12 bits.

Example

If the resolution of the absolute encoder is set on 27 bits, 30 bits are provided by the encoder: 27 data bits and 3 error bits. If the PLC is not able to evaluate the error bits, the PLC has to be set on a resolution of 27 bits. Then the error bits have to be masked out by the PLC.

The graph illustrates the relationship between Speed N [min⁻¹] and Steps per revolution. The curve shows a decreasing trend, starting at approximately 262,144 steps per revolution at 0 min⁻¹ and approaching 16,384 steps per revolution at 12,000 min⁻¹.

Interfaces



SSI data format singlets

Bit 1-14: Position Bits

- LSI data format singlet
- MDS: High impedance bit

Bit 15-20: Error Bits

- Error 1: Error message about speed if the data occurs during the position holding procedure it will be indicated by the ERROR15
- Error 2: Error message monitoring fault
- ERROR16: Containing the data of the monitoring system. During the determination of the position, an error has occurred since the error has not been detected during the data transmission

The evaluation of the error bits has to be realized in the PLC.

The provided error data has to be used by the PLC completely.

Example:

If the monitoring of the absolute encoder set on 27, 16 bits are provided by the encoder: 11 data bits and 5 error bits. The error 15 and 16 error bits, the PLC has to be set on a monitoring of 13 bits. Then the error bits have to be read out by the PLC.

SSI data format multimux

Bit 1-14: Position Bits

- LSI data format multimux
- MDS: High impedance bit

Bit 15-20: Error Bits

- Error 1: Error message about speed if the data occurs during the position holding procedure it will be indicated by the ERROR15
- Error 2: Error message monitoring fault
- ERROR16: Containing the data of the monitoring system. During the determination of the position, an error has occurred since the error has not been detected during the data transmission

The evaluation of the error bits has to be realized in the PLC.

The provided error data has to be used by the PLC completely. The multimux resolution is fixed on 12 bits.

Example:

If the monitoring of the absolute encoder is set on 27, 16 bits are provided by the encoder: 27 data bits and 2 error bits. The error 15 and 16 error bits, the PLC has to be set on a monitoring of 27 bits. Then the error bits have to be

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