

AFS60B-S1AK008192





# Absolute encoders AFS/AFM60 SSI

Model Name > AFS60B-S1AK008192

Part No. > 1053017



## At a glance

- High-resolution absolute encoders with up to 30 bits (AFM60) or up to 18 bits (AFS60)
- · Face mount flange, servo flange, blind or through hollow shaft
- SSI, SSI + Incremental or SSI + Sin/Cos interface
- · Programmable resolution and offset (dependent on type)
- · Connection system: M12, M23 connector or cable outlet
- Enclosure rating: IP 67 (housing), IP 65 (shaft)
- Operating temperature: -30 °C to +100 °C (depends on type)

## Your benefits

- Programmability of the encoders means less storage, greater machine availability and easy installation
- · Precise positioning due to high resolutions
- Large selection of mechanical interfaces and electrical contacting possibilities:
   Suitable for all applications
- Suitable for applications with limited space requirements (extremely short installation depth of 30 mm)
- · Very good rotation accuracy due to increased bearing distance
- One programming tool and software with automatic encoder detection for AFS60/AFM60/DFS60



Max. number of steps per revolution:

## **Performance**

## Mechanical data

Mechanical interface: Solid shaft, Servo flange

Shaft diameter: 6 mm

Start up torque: 0.5 Ncm (20 °C)

8,192

<sup>1)</sup> Valid positional data can be read once this time has elapsed

Operating torque: 0.3 Ncm (20 °C)

Permissible Load capacity of shaft: 40 N (axial), 80 N (radial)

9.000 /min Maximum operating speed: Moment of inertia of the rotor: 6.2 gcm<sup>2</sup>

3.0 x 10<sup>9</sup> revolutions Bearing lifetime:

Max. angular acceleration: 500,000 rad/s<sup>2</sup>

## **Electrical data**

Power consumption: 0.5 W (without load) Operating voltage range: 4.5 V DC ... 32 V DC 250 a (EN ISO 13849-1) 1) MTTFd: mean time to dangerous failure:

safety component as defined in the Machinery Directive.

Calculation based on nominal load of components, average ambient

temperature 40°C, frequency of use 8760 h/a. All

electronic failures are considered hazardous. For more information, see document no. 8015532.

## **Interfaces**

Cable, 8-pin, universal, 1.5 m<sup>1)</sup> Electrical interface: Clock +, Clock -, Data +, Data- $^{2)}$ Interface signals:

Clock frequency:

SET (electronic adjustment): H-active (L  $\equiv$  0 - 1,5 V, H  $\equiv$  2,0 - Us V) CW/CCW (counting sequence when turning): L-active (L  $\equiv$  0 - 1,5 V, H  $\equiv$  2,0 - Us V)

## **Ambient data**

(according to EN 61000-6-2 and EN 61000-6-3) 1) EMC:

IP 65 (according to IEC 60529), shaft side, IP 67 (according to IEC 60529) Enclosure rating:

90 % (condensation of the optical scanning not permitted) Permissible relative humidity:

Working temperature range: -30 °C ... 100 °C

-40 °C ... 100 °C, without package Storage temperature range: 70 g (according to EN 60068-2-27) Resistance to shocks:

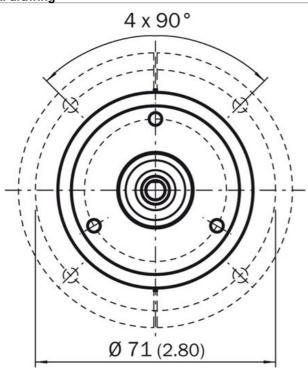
Resistance to vibration: 30 g, 10 Hz ... 2,000 Hz (according to EN 60068-2-6)

1)

<sup>1)</sup> Self warming of 3.3 K per 1000 revolutions/min when applying note working temperature range

<sup>1)</sup> This product is a standard product and does not constitute a

<sup>1)</sup> The universal cable outlet is positioned in such a way, that it is possible to lay the cable in a radial or axial direction without kinking it



|1| Cable diameter = 5,6 mm +/- 2 mmBending radius = 30 mm

## Signalausgänge

SSI data format singleturn



LSB: Least significant Bit
 MSB: Most significant Bit

# The evaluation of the error bits has to be realized in the PLC. The provided error bits don't have to be used by the PLC compute

Example
If the resolution of the absolute encoder is set on 13 bits, 16 bits are provided by the encoder: 13 data bits and 3 error bits.
If the PLC is not able to evaluate the error bits, the PLC has to be set on a resolution of 13 bits. Then the error bits have to b
masked out by the PLC.

## SSI data format multiturn





Bit 1–12: Position Bits multiturn Bit 13–30: Position Bits singleturn Bit 31–33: Error Bits

## 27 Bits



Bit 1-12: Position Bits multiturn Bit 13-27: Position Bits singleturn Bit 28-30: Error Bits

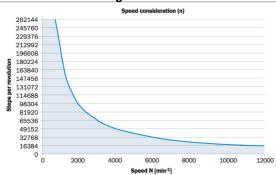
- ERRSYLC Contamination of the disc or scanning system. During the determination of the last SSI transmission. The error bit will be deleted during the next data transmiss.

The evaluation of the error bits has to be realized in the PLC.

The provided error bits don't have to be used by the PLC compulsorily. The multitum resolution is fixed on 12 bits.

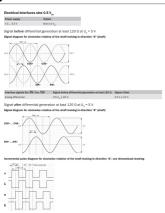
If the resolution of the absolute encoder is set on 27 bits, 30 bits are provided by the encoder; 27 data bits and 3 error bits. If the PLC is not able to evaluate the error bits, the PLC has to be set on a resolution of 27 bits. Then the error bits have to be masked out by the PLC.

# Drehzahlbetrachtung

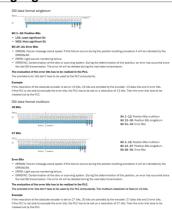


The maximum speed is also dependent on the shaft type.

## Interfaces



# Signalausgänge



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