



Absolute encoders ARS60 SSI/Parallel

ARS60-HDA00256



Model Name > ARS60-HDA00256
Part No. > 1031674



Illustration may differ

At a glance

- Absolute singleturn encoder
- Resolution: up to 15 bits (32,768 increments)
- Electrical interface: SSI with gray code type or gray capped
- Electrical interface: Parallel with gray, gray capped, binary, BCD code type
- Zero-set function
- Mechanical interfaces: face mount flange, servo flange, blind and through hollow shaft
- Enclosure rating: Up to IP66

Your benefits

- Optical and magnetic variants for the widest range of requirements
- Reduced maintenance costs thanks to magnetic, wearless scanning in single and multiturn design
- High level of productivity due to optical encoders with a high level of precision and fast calculation of positions
- Robust design for maximum system availability, even in extreme environmental conditions
- Absolutely compact - specially suited in cases where installation space is tight
- Flexible integration in all common networks



Performance

Max. number of steps per revolution:	256
Max. number of revolutions:	1
Resolution power:	256 x 1
Error limits:	0.035 ° (binary number of steps) 0.046 ° (non-binary number of steps)
Repeatability (Ta not constant):	0.005 °
Measuring step deviation:	0.005 °, 0.016 °
Measuring step:	360 ° /number of lines
Initialization time:	80 ms ¹⁾

¹⁾ Valid positional data can be read once this time has elapsed

Mechanical data

Mechanical interface:	Through hollow shaft
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Shaft diameter:	6 mm 8 mm 10 mm 12 mm 14 mm 15 mm 1/4 " 3/8 " ¹⁾ 1/2 " ¹⁾
Mass:	0.3 kg
Start up torque:	2.2 Ncm
Operating torque:	1.6 Ncm
Maximum operating speed:	3,000 /min
Bearing lifetime:	3.6 x 10 ⁹ revolutions
Max. angular acceleration:	500,000 rad/s ²
Permissible movement axial static/dynamic:	± 0.5 mm, ± 0.2 mm
Permissible movement radial static/dynamic:	± 0.3 mm, ± 0.1 mm
Operation of zero-set:	≥ 100 ms ²⁾

¹⁾ Collets for 6, 8, 10, 12, 14 mm and 1/4 ", 3/8 " and 1/2 " as accessories, separate order item. For 15 mm shaft diameter collet is not needed. ²⁾ Only with shaft stationary (note initialisation time)

Electrical data

Operating voltage range:	10 V DC ... 32 V DC
Operating power consumption (no load):	90 mA
MTTFd: mean time to dangerous failure:	300 a (EN ISO 13849-1) ¹⁾

¹⁾ This product is a standard product and does not constitute a safety component as defined in the Machinery Directive.

Calculation based on nominal load of components, average ambient

temperature 40°C, frequency of use 8760 h/a. All

electronic failures are considered hazardous. For more information, see document no. 8015532.

Interfaces

Electrical interface:	Connector M23, 21-pin, radial
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Ambient data

EMC:	(according to EN 61000-6-2 and EN 61000-6-3) ¹⁾
Enclosure rating:	IP 64 (according to IEC 60529), with mating connector fitted
Permissible relative humidity:	90 % (condensation of the optical scanning not permitted)
Working temperature range:	-20 °C ... 85 °C
Storage temperature range:	-40 °C ... 100 °C
Resistance to shocks:	50 g (according to EN 60068-2-27)
Resistance to vibration:	20 g, 10 Hz ... 2,000 Hz (according to EN 60068-2-6)

¹⁾

The technical drawing illustrates the M63-01 pressure washer nozzle assembly through three distinct views:

- Front View (Left):** Shows the circular face of the nozzle. Key dimensions include an outer diameter of $\varnothing 63 \text{ (2.48)}$, a central hole diameter of $\varnothing 3.2^{+0.1}_{-0} \text{ (0.13)}$, and a mounting flange diameter of $\varnothing 60 \text{ (2.36)}$. The distance between the two side handles is 72 (2.83) .
- Side View (Right):** Provides a perspective of the nozzle's profile. It shows a total length of $66.7^{+0.5}_{-0} \text{ (2.63)}$ and a maximum height of 4.5 (0.18) . The handle width at its base is 24 (0.94) .
- Detail View (Bottom Center):** A close-up of the trigger gun attachment point. It features a curved trigger gun with a diameter of $\varnothing 8 \text{ (0.31)}$ and a length of 10 (0.39) . The connection pin has a diameter of $\varnothing 29.5 \text{ (1.16)}$ and a thread specification of $\varnothing \times F7$. Other detail dimensions include a distance of 2 (0.08) from the trigger gun to the main body, a distance of 3.6 (0.14) between internal components, and a distance of 20 (0.79) from the trigger gun to the bottom edge.

- Allocation for encoder with 21-pin connector Single; Parallel Interface

PIN	Wire color/y cable output	Binary	Gray	BCD	Description
1	Lilac	2 ⁰	G ₀	2 ⁰ × 10 ¹	
2	White/brown	2 ¹	G ₁	2 ¹ × 10 ⁰	
3	White/green	2 ²	G ₂	2 ² × 10 ⁰	
4	White/yellow	2 ³	G ₃	2 ³ × 10 ⁰	
5	White/gray	2 ⁴	G ₄	2 ⁴ × 10 ⁰	
6	White/pink	2 ⁵	G ₅	2 ⁴ × 10 ¹	
7	White/blue	2 ⁶	G ₆	2 ⁴ × 10 ¹	
8	White/red	2 ⁷	G ₇	2 ⁴ × 10 ¹	
9	White/black	2 ⁸	G ₈	2 ⁴ × 10 ¹	
10	Brown/green	2 ⁹	G ₉	2 ⁴ × 10 ¹	
11	Brown/yellow	2 ¹⁰	G ₁₀	2 ⁴ × 10 ¹	
12	Brown/gray	2 ¹¹	G ₁₁	2 ⁴ × 10 ¹	
13	Brown/pink	2 ¹²	G ₁₂	2 ⁴ × 10 ¹	
14	Brown/blue	2 ¹³	G ₁₃	2 ⁴ × 10 ¹	
15	Brown/red	2 ¹⁴	G ₁₄	2 ⁴ × 10 ¹	
16	Green	Parity		Parity	
17	Pink	Store ₀	Store ₀	Store ₀	
18	Yellow	Enable ₀	Enable ₀	Enable ₀	
19	Brown	V/R ₀	V/R ₀	V/R ₀	
20	Gray	SET	SET	SET	
21	Blue	GND	GND	GND	
21	Red	U ₁	U ₁	U ₁	
Hour/mn		Screen	Screen	Screen	

² Set line only possible with a cable outlet.

U_s Supply voltage to the encoder (before commissioning, note must be taken of the type label of the encoder).

V _{CC}	Supply voltage for the encoder (before commissioning, note must be taken of the type and size of the encoder).
GND	Zero volt connection to the encoder; electrically isolated from the housing. The voltage referred to GND is U ₀ .

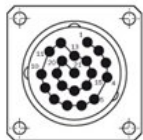
Forward/reverse: this input programs the counting direction of the encoder. If not connected, this input is **-high**. If the encoder shaft, as viewed on the drive shaft, rotates in the clockwise direction, it counts in an increasing sequence. If it should count upwards when the shaft rotates in the anti-clockwise direction, this connection must be connected permanently to **low** level (zero volts).

Enable_ This input activates the data output driver when a «low» level is applied. If not connected, this input is «low». In the case of a «high» level, the outputs are in the tri-state mode.

Strobe This input stores the encoder data in Gray code when a *slow* level is applied. This avoids a read error if the output data is requested in binary code. If this input is *slow*, the data at the encoder output is stable, irrespective of whether the input shaft rotates. If not switched, this input is *high*.

input is -low, the data at the encoder output is stable, irrespective of whether the input shift rotates. If not switched, this input is -high.

Parity	This output supplies a -high- level when the binary checksum of the data bits is even.
SET	This input serves to set the zero electronically. If the SET line is connected to Us for more than 100 ms, the mechanical position corresponds to the value 0.



View of the connector M23 fitted to the encoder body Single, Parallel

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