



Absolute encoders ARS60 SSI/Parallel

ARS60-J1A02000



Model Name > [ARS60-J1A02000](#)
Part No. > [1031739](#)



Illustration may differ

At a glance

- Absolute singleturn encoder
- Resolution: up to 15 bits (32,768 increments)
- Electrical interface: SSI with gray code type or gray capped
- Electrical interface: Parallel with gray, gray capped, binary, BCD code type
- Zero-set function
- Mechanical interfaces: face mount flange, servo flange, blind and through hollow shaft
- Enclosure rating: Up to IP66

Your benefits

- Optical and magnetic variants for the widest range of requirements
- Reduced maintenance costs thanks to magnetic, wearless scanning in single and multiturn design
- High level of productivity due to optical encoders with a high level of precision and fast calculation of positions
- Robust design for maximum system availability, even in extreme environmental conditions
- Absolutely compact - specially suited in cases where installation space is tight
- Flexible integration in all common networks



Performance

Max. number of steps per revolution:	2,000
Max. number of revolutions:	1
Resolution power:	2,000 x 1
Error limits:	0.035 ° (binary number of steps) 0.046 ° (non-binary number of steps)
Repeatability (Ta not constant):	0.005 °
Measuring step deviation:	0.005 °, 0.016 °
Measuring step:	360 ° /number of lines
Initialization time:	80 ms ¹⁾

¹⁾ Valid positional data can be read once this time has elapsed

Mechanical data

Mechanical interface:	Solid shaft, Servo flange
Shaft diameter:	6 mm
Mass:	0.3 kg

Start up torque:	0.25 Ncm
Operating torque:	0.2 Ncm
Permissible Load capacity of shaft:	10 N (axial), 20 N (radial)
Maximum operating speed:	10,000 /min (without shaft seal), 6,000 /min (with shaft seal) ¹⁾
Moment of inertia of the rotor:	48 gcm ²
Bearing lifetime:	3.6 x 10 ⁹ revolutions
Max. angular acceleration:	500,000 rad/s ²
Operation of zero-set:	≥ 100 ms ²⁾

¹⁾ If the shaft seal has been removed by the customer ²⁾ Only with shaft stationary (note initialisation time)

Electrical data

Operating voltage range:	10 V DC ... 32 V DC
Operating power consumption (no load):	90 mA
MTTFd: mean time to dangerous failure:	300 a (EN ISO 13849-1) ¹⁾

¹⁾ This product is a standard product and does not constitute a safety component as defined in the Machinery Directive.

Calculation based on nominal load of components, average ambient temperature 40°C, frequency of use 8760 h/a. All

electronic failures are considered hazardous. For more information, see document no. 8015532.

Interfaces

Electrical interface:	Connector M23, 21-pin, radial
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Ambient data

EMC:	(according to EN 61000-6-2 and EN 61000-6-3) ¹⁾
Enclosure rating:	IP 65 (according to IEC 60529), with mating connector fitted
Permissible relative humidity:	90 % (condensation of the optical scanning not permitted)
Working temperature range:	-20 °C ... 85 °C
Storage temperature range:	-40 °C ... 100 °C
Resistance to shocks:	50 g (according to EN 60068-2-27)
Resistance to vibration:	20 g, 10 Hz ... 2,000 Hz (according to EN 60068-2-6)

¹⁾

The technical drawing illustrates the M8x60-2B ballpoint pen nib assembly through three distinct views:

- Front View (Left):** Shows the circular tip of the nib. Key features include:
 - A central hole with a diameter of $\varnothing 42 \pm 0.1$ (1.65).
 - An outer diameter of $\varnothing 60$ (2.36).
 - A top flange with a thickness of 4.5 (0.18) and a diameter of $\varnothing 54 \pm 0.5$ (2.13).
 - A bottom section with a height of 24 (0.94) and a base diameter of $\varnothing 8$ (0.31).
 - Internal features are specified as M4 8 deep (0.31) and $\varnothing 0.2$ B.
 - Angles of 120° and 25° are indicated for the internal geometry.
- Side View (Middle):** Provides a profile of the nib's body, showing a total length of 66 (2.60) and a base diameter of $\varnothing 8$ (0.31). A small feature at the base is dimensioned as 10 (0.39).
- Cross-sectional View (Right):** Details the internal structure of the nib, highlighting several critical dimensions:
 - Overall length: 90 (3.54).
 - Tip diameter: $\varnothing 50 f_6$ (0.24).
 - Internal diameters: $\varnothing 51.5 \pm 0.1$ (2.03), $\varnothing 50 f_8$ (1.97), and $\varnothing 59.5 \pm 0.1$ (2.34).
 - Wall thicknesses: 0.1 A and 0.2 A.
 - Sectional area: $\varnothing 0.2$ A.
 - Base dimensions: 10 ± 1 (0.39), 4 (0.16), 3 (0.12), and 3 (0.12).
 - Bottom section: 24 (0.94) and 13.5 (0.53).

- Allocation for encoder with 21-pin connector Single; Parallel Interface

PIN	Wire color/y cable output	Binary	Gray	BCD	Description
1	Lilac	2 ⁰	G ₀	2 ⁰ × 10 ¹	
2	White/brown	2 ¹	G ₁	2 ¹ × 10 ⁰	
3	White/green	2 ²	G ₂	2 ² × 10 ⁰	
4	White/yellow	2 ³	G ₃	2 ³ × 10 ⁰	
5	White/gray	2 ⁴	G ₄	2 ⁴ × 10 ⁰	
6	White/pink	2 ⁵	G ₅	2 ⁴ × 10 ¹	
7	White/blue	2 ⁶	G ₆	2 ⁴ × 10 ¹	
8	White/red	2 ⁷	G ₇	2 ⁴ × 10 ¹	
9	White/black	2 ⁸	G ₈	2 ⁴ × 10 ¹	
10	Brown/green	2 ⁹	G ₉	2 ⁴ × 10 ¹	
11	Brown/yellow	2 ¹⁰	G ₁₀	2 ⁴ × 10 ¹	
12	Brown/gray	2 ¹¹	G ₁₁	2 ⁴ × 10 ¹	
13	Brown/pink	2 ¹²	G ₁₂	2 ⁴ × 10 ¹	
14	Brown/blue	2 ¹³	G ₁₃	2 ⁴ × 10 ¹	
15	Brown/red	2 ¹⁴	G ₁₄	2 ⁴ × 10 ¹	
16	Green	Parity		Parity	
17	Pink	Store ₀	Store ₀	Store ₀	
18	Yellow	Enable ₀	Enable ₀	Enable ₀	
19	Brown	V/R ₀	V/R ₀	V/R ₀	
20	Gray	SET	SET	SET	
21	Blue	GND	GND	GND	
21	Red	U ₁	U ₁	U ₁	
Hour/mn		Screen	Screen	Screen	

² Set line only possible with a cable outlet.

U_s Supply voltage to the encoder (before commissioning, note must be taken of the type label of the encoder).

GND Zero volt connection to the encoder; electrically isolated from the housing. The voltage referred to GND is U_v .

V/R₊ Forward/reverse: this input programs the counting direction of the encoder. If not connected, this input is -high-. If the encoder shaft, as viewed on the drive shaft, rotates in the clockwise direction, it counts in an increasing sequence; if it should count upwards when the shaft rotates in the anti-clockwise direction, this connection must be connected permanently to +low-level (zero volts).

Enable_ This input activates the data output driver when a *-low-* level is applied. If not connected, this input is *-low-*. In the case of a *-high-* level, the outputs are in

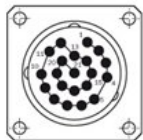
the 1-bit mode.

Store₀ This input stores the encoder data in Gray code when a *slow* level is applied. This avoids a read error if the output data is requested in binary code. If this input is *slow*, the data at the encoder output is stable, irrespective of whether the input shaft rotates. If not enabled, this input is *high*.

input is -low, the data at the encoder output is stable, irrespective of whether the input shift rotates. If not switched, this input is -high.

Fourth, This output supplies a -parity level when the binary checksum of the data bits is even.

Parity	This output supplies a -high- level when the binary checksum of the data bits is even.
SET	This input serves to set the zero electromechanically. If the SET line is connected to 0 for more than 100 ms, the mechanical position corresponds to the value 0.



View of the connector M23 fitted to the encoder body Single, Parallel

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