

ATM60-A1N12X12







# Absolute encoders ATM60 SSI

Model Name > ATM60-A1N12X12

Part No. > 1032925





Illustration may differ

# At a glance

- Extremely rugged, tried-and-tested absolute multiturn encoder with a resolution of up to 26 bits
- Mechanical interface: face mount flange, servo flange, blind hollow shaft and extensive adapter accessories
- · Zero-set and preset functions via hardware or software
- · No battery required
- Electrical interface: SSI with gray or binary code type
- · Electronically adjustable, configurable resolution
- Rotary axis function (optional) also for non-binary resolutions (per revolution) and decimal numbers (number of revolutions)
- · Magnetic scanning

#### Your benefits

- Fewer variants are required since one freely programmable encoder offers all singleturn and multiturn resolutions
- Easy setup due to various connectivity options (cable, M23)
- · Less maintenance and a long service life reduce overall costs
- Application flexibility due to easily interchangeable collets for the blind hollow shaft
- Quick commissioning using the zero set/preset function either at the press of the button on the device or via software
- · Increased productivity due to highly reliable shock and vibration resistance
- · Worldwide availability and service ensure quick and reliable customer service



# Performance

Max. number of steps per revolution: 4,096
Max. number of revolutions: 4,096

Resolution power:  $4,096 \times 4,096$  Resolution:  $12 \text{ bit } \times 12 \text{ bit}$  Error limits:  $\pm 0.25 ^{\circ}$  Repeatability (Ta not constant):  $0.1 ^{\circ}$  Measuring step:  $0.043 ^{\circ}$  Initialization time: 1,050 ms

<sup>1)</sup> Valid positional data can be read once this time has elapsed

#### Mechanical data

Mechanical interface: Solid shaft, Servo flange

Shaft diameter: 6 mm Mass: 0.5 kg

Permissible Load capacity of shaft: 300 N (radial), 50 N (axial)

Moment of inertia of the rotor: 35 gcm<sup>2</sup>

Bearing lifetime: 3.6 x 10<sup>9</sup> revolutions

Max. angular acceleration: 500.000 rad/s<sup>2</sup> Shaft material: Stainless steel Flange material: Aluminum

Housing material: Die-cast aluminum

Start up torque with shaft seal: 2.5 Ncm Start up torque without shaft seal: 0.5 Ncm Operating torque with shaft seal: 1.8 Ncm 0.3 Ncm <sup>1)</sup> Operating torque without shaft seal:

# **Electrical data**

Operating voltage range: 10 V ... 32 V 0.8 W Power consumption max.:

150 a (EN ISO 13849-1) 1) MTTFd: mean time to dangerous failure:

This product is a standard product and does not constitute a

safety component as defined in the Machinery Directive.

Calculation based on nominal load of components, average ambient

temperature 40°C, frequency of use 8760 h/a. All

electronic failures are considered hazardous. For more information, see document no. 8015532.

## Interfaces

Cable, 12-pin, radial, 10 m Electrical interface:

Clock +, Clock -, Data +, Data-, Programming interface: RS-422 1) Interface signals:

1 MHz Clock frequency:

SET (electronic adjustment): H-active (L  $\equiv$  0 - 4,7 V, H  $\equiv$  10 - Us V) CW/CCW (counting sequence when turning): L-active (L  $\equiv$  0 - 1,5 V, H  $\equiv$  2,0 - Us V)

# **Ambient data**

EMC: (according to EN 61000-6-2 and EN 61000-6-3)

Enclosure rating:::

IP 43 (according to IEC 60529), without shaft seal, on encoder flange not sealed, IP 65 (according to IEC 60529), without shaft seal, on encoder flange sealed, IP 67 (according to IEC 60529), with shaft seal

Permissible relative humidity: 98 %

-20 °C ... 85 °C Working temperature range:

-40 °C ... 100 °C, without package Storage temperature range: 100 g (according to EN 60068-2-27) Resistance to shocks:

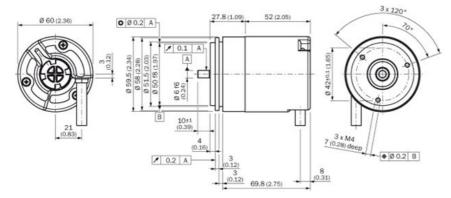
20 g, 10 Hz ... 2,000 Hz (according to EN 60068-2-6) Resistance to vibration:

1) 2) 3) With mating connector fitted

<sup>1)</sup> If the shaft seal has been removed by the customer

<sup>1)</sup> For higher clock frequencies, choose synchronous SSI

# **Dimensional drawing**



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