



## Incremental encoders DFS60, Rotary

DFS60E-S4EK00250



**Model Name** > DFS60E-S4EK00250  
**Part No.** > 1038916



*Illustration may differ*

#### At a glance

- Compact installation depth
- High resolution up to 16 bits
- Optionally programmable: Output voltage, zero pulse position, zero pulse width and number of pulses
- Connection: Radial or axial cable outlet, M23 or M12 connector, axial or radial
- Electrical interfaces: 5V & 24V TTL/RS-422, 24 V HTL/push pull
- Mechanical interfaces: face mount or servo flange, blind or through hollow shaft
- Remote zero set possible

#### Your benefits

- Reduced storage costs and downtime due to customer-specific programming
- Variety of different mechanical and electrical interfaces enable the encoder to be optimally adjusted to fit the installation situation
- Excellent concentricity even at high speeds
- High resolution of up to 16 bits ensures precise measurements
- Permanent and safe operation due to a high enclosure rating, temperature resistance and a long bearing lifetime
- Programmability via the PGT-08 programming software and the PGT-10-S display programming tool allow the encoder to be adapted flexibly and quickly according to customer needs
- Programmable zero pulse position simplifies installation



#### Performance

|                        |                                                    |
|------------------------|----------------------------------------------------|
| Error limits:          | $\pm 0.3^\circ$                                    |
| Measuring step:        | $90^\circ / \text{electronically/number of lines}$ |
| Initialization time:   | 40 ms                                              |
| Pulses per revolution: | 250                                                |

#### Mechanical data

|                                 |                                  |
|---------------------------------|----------------------------------|
| Mechanical interface:           | Solid shaft, Face mount flange   |
| Shaft diameter:                 | 10 mm x 19 mm                    |
| Mass:                           | 0.3 kg                           |
| Start up torque:                | 0.5 Ncm (20 °C)                  |
| Operating torque:               | 0.3 Ncm (20 °C)                  |
| Maximum operating speed:        | 10,000 /min                      |
| Moment of inertia of the rotor: | 6.2 gcm <sup>2</sup>             |
| Bearing lifetime:               | $3.6 \times 10^{10}$ revolutions |

|                                         |                             |
|-----------------------------------------|-----------------------------|
| Max. angular acceleration:              | 500,000 rad/s <sup>2</sup>  |
| Permissible shaft loading radial/axial: | 40 N (axial), 80 N (radial) |

#### Electrical data

|                                        |                                                              |
|----------------------------------------|--------------------------------------------------------------|
| Electrical interface:                  | 10 V ... 32 V, HTL/Push pull, Cable, 8-pin, universal, 1.5 m |
| Connection type:                       | Cable, 8-pin, universal, 1.5 m <sup>1)</sup>                 |
| Maximum output frequency:              | 300 kHz                                                      |
| Reference signal, number:              | 1                                                            |
| Reference signal, position:            | 90 °, electronically, gated with A and B                     |
| Operating voltage range:               | 10 V ... 32 V                                                |
| Load current max.:                     | 30 mA                                                        |
| Power consumption:                     | 0.5 W (without load)                                         |
| MTTFd: mean time to dangerous failure: | 300 a (EN ISO 13849-1) <sup>2)</sup>                         |

<sup>1)</sup> The universal cable outlet is positioned in such a way, that it is possible to lay the cable in a radial or axial direction without kinking it <sup>2)</sup> This product is a standard product and does not constitute a safety component as defined in the Machinery Directive.

Calculation based on nominal load of components, average ambient temperature 40°C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

#### Ambient data

|                                |                                                                            |
|--------------------------------|----------------------------------------------------------------------------|
| EMC:                           | (according to EN 61000-6-2 and EN 61000-6-3)                               |
| Working temperature range:     | 0 °C ... 85 °C                                                             |
| Storage temperature range:     | -40 °C ... 100 °C, without package                                         |
| Resistance to shocks:          | 50 g (according to EN 60068-2-27)                                          |
| Resistance to vibration:       | 20 g, 10 Hz ... 2,000 Hz (according to EN 60068-2-6)                       |
| Enclosure rating:              | IP 65 (according to IEC 60529), shaft side, IP 67 (according to IEC 60529) |
| Permissible relative humidity: | 90 % (condensation of the optical scanning not permitted)                  |

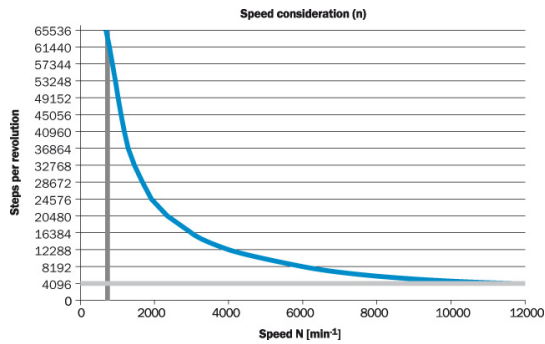
View of M12 device connector on encoder

<sup>a</sup> Only at 4.5 ... 32 V, TTL/HTL programmable

The SET input serves to carry out the zero pulse teach function. If the SET input is applied to U<sub>3</sub> for longer than 250 ms, after it has been open for at least 1,000 ms or applied to GND, the current shaft position is assigned the zero pulse signal "Z".

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Drehzahlbetrachtung



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