

TTK70-HXA0-K02







Motor feedback systems linear HIPERFACE® TTK70

Model Name > TTK70-HXA0-K02

Part No. > 1037434





At a glance

- · Absolute, non-contact, wear-free length measurement system for linear motors
- · Measured lengths of up to 4 m
- · Suitable for high traverse speeds of up to 10 m/s
- Reliable location positioning even in the event of condensation and contamination of the magnetic tape
- · Electronic type label and programming of the position value
- · Absolute location positioning, no reference run
- HIPERFACE® interface
- Conforms to RoHs

Your benefits

- · Reference traverse no longer necessary due to absolute measuring system
- · Maintenance-free thanks to non-contact measuring principle
- Simple integration of the system due to the HIPERFACE® interface
- · Developed specifically for use in linear direct drives
- · Also for use in rough ambient conditions



Performance

Measuring step: 0.244 µm at interpolation of the sine/cosine signals with e.g. 12 Bit

Length of period: 1 mm

Measuring length: Max. 4,000 mm

Available memory area: 1,792 Byte (EEPROM 2048)

System accuary (ambient temperature): \pm 10 μ m (20 °C)

Repeatability (Ta not constant): < 5 µm

Magnetic strip length: Measurement length + 80 mm

Measured value backlash: < 10 μm

Mechanical data

Dimensions: See dimensional drawing

Mass: Read head 0.06 kg without cable, magnetic tape 0.18 kg/m

Material: Read head die-cast zinc, magnetic tape 17410 hard ferrite 9/28 P

Piston speed: 10 m/s
Operating speed up to which the absolute position 1.3 m/s

can be rel:

Electrical data

Electrical interface: **HIPERFACE** Operating voltage range/supply Voltage: 7 V DC ... 12 V DC

Recommended supply voltage:

Operating power consumption (no load):

1) 100 mA approx. during adjustment

8 V DC ≤ 65 mA ¹⁾

Interfaces

Type of code for the absolute value: Binary

Parameter channel RS 485: digital, Process data channel SIN, REFSIN, Interface signals:

COS, REFCOS: analog, differential

Ambient data

-30 °C ... 80 °C Working temperature range:

Storage temperature range: -40 °C ... 85 °C, without package Relative humidity/Condensation: 100 %, Condensation allowed 30 g, 6 ms (EN 60068-2-27) Resistance to shocks:

20 g, 10 Hz ... 2,000 Hz (EN 60068-2-6) Resistance to vibration:

(EN 61000-6-2) ₁₎ EMC: (EN 61000-6-3)

Enclosure rating:

IP 65 (according to IEC 60529), with mating connector inserted

Temperature coefficient magnetic tape: $(11 \pm 1) \mu m/K/m$

< 3 kA/m ... 4 kA/m (3.8 mgT ... 5 mT) (to guarantee compliance with the Maximum permitted ambient field strength:

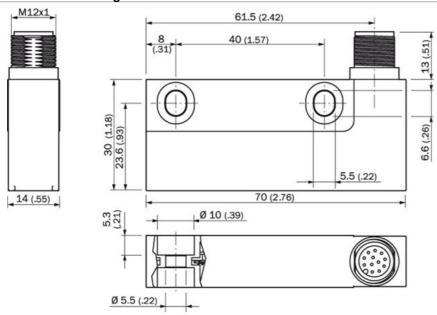
quoted accuracy values)

< 150 kA/m (< 190 mT) (to ensure that the magnetic tape is not Maximum permitted field strength:

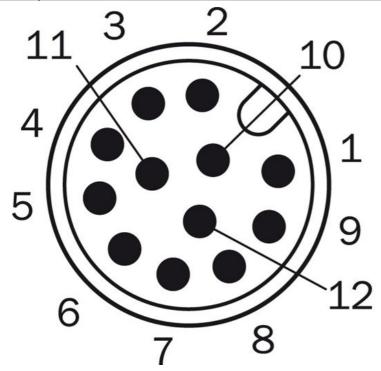
permanently damaged)

¹⁾ The EMC according to the standars quoted is achieved when the motor feedback system with put-on mating connector is connected to the central earthing point of the motor controller via a cable screen. Users must perform their own tests when other screen designs are used. 2) The maximum permitted external field influence is reached when the position value deviates from the original value (without external field influence) by more than 5 µm. This value is reached when, at the sensor location, a field strength of 3 kA/m to 4 kA/m (3.8 mT to 5 mT) occurs in addition to the field strength of the magnetic tape.

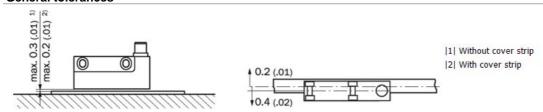
Dimensional drawing



Magnetic tape

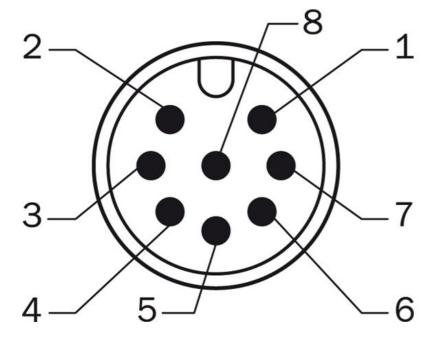


General tolerances



PIN and wire allocation

8-pin A-coded



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